# **TCN Series INSTRUCTION MANUAL**

TCD210225AB

Autonics

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

Keep this instruction manual in a place where you can find easily.

The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice. Follow Autonics website for the latest information.

# Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- $\Lambda$  symbol indicates caution due to special circumstances in which hazards may occur.

**Warning** Failure to follow instructions may result in serious injury or death

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) Failure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.

Failure to follow this instruction may result in explosion or fire. 03. Install on a device panel to use.

Failure to follow this instruction may result in fire or electric shock.

- 04. Do not connect, repair, or inspect the unit while connected to a power source.
- Failure to follow this instruction may result in fire or electric shock. 05. Check 'Connections' before wiring.

#### Failure to follow this instruction may result in fire. 06. Do not disassemble or modify the unit.

Failure to follow this instruction may result in fire or electric shock.

**Caution** Failure to follow instructions may result in injury or product damage

01. When connecting the power input and relay output, use AWG 20 (0.50 mm<sup>2</sup>) cable or over, and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.

When connecting the sensor input and communication cable without dedicated cable, use AWG 28 to 16 cable and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.

Failure to follow this instruction may result in fire or malfunction due to contact

## 02. Use the unit within the rated specifications.

- Failure to follow this instruction may result in fire or product damage 03. Use a dry cloth to clean the unit, and do not use water or organic solvent.
- Failure to follow this instruction may result in fire or electric shock.
- 04. Keep the product away from metal chip, dust, and wire residue which flow into the unit.

Failure to follow this instruction may result in fire or product damage.

# **Cautions during Use**

- · Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- Check the polarity of the terminals before wiring the temperature sensor.
  For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (TC) temperature sensor, use the designated compensation wire for extending wire.
- Keep away from high voltage lines or power lines to prevent inductive noise. In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line. Do not use near the equipment which generates strong magnetic force or high frequency noise. • Install a power switch or circuit breaker in the easily accessible place for supplying or
- disconnecting the power
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller
- When changing the input sensor, turn off the power first before changing. After changing the input sensor, modify the value of the corresponding parameter.
- 24 VAC~, 24-48 VDC == power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- Make a required space around the unit for radiation of heat. For accurate temperature measurement, warm up the unit over 20 min after turning on the power.
- · Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- This unit may be used in the following environments
- Indoors (in the environment condition rated in 'Specifications') - Altitude Max. 2,000 m - Pollution degree 2
- Installation category II

# Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website

# T C N O O - O O O - O

O Digit 4:4 digit

# Ø Size

S: DIN W 48  $\times$  H 48 mm M: DIN W 72  $\times$  H 72 mm H: DIN W 48  $\times$  H 96 mm

L: DIN W 96  $\times$  H 96 mm Option in/output

2: Alarm 1/2

No mark: Bolt P: Connector plug connection

# **Product Components**

Product (+ bracket)

Instruction manual

## Sold Separately

Terminal protection cover: RSA / RMA / RHA / RLA-COVER

# Specifications

-							
Series		TCN4 -22 -	TCN4□-24□-□				
Power su	upply	24 VAC~ 50/60 Hz 24 - 48 VDC== 100 - 240 VAC~ 50/60 Hz					
Permissible voltage range		90 to 110 % of rated voltage					
Power co	onsumption	AC: $\leq$ 5 VA, DC: $\leq$ 3 W $\leq$ 5 VA					
Samplin	g period	100 ms					
Input sp	ecification	Refer to 'Input Type and Using Ran	ge.				
Control	Relay	250 VAC~ 3A, 30 VDC= 3A, 1a					
output	SSR	$12 \text{ VDC} = \pm 2 \text{ V}, \le 20 \text{ mA}$					
Alarm ou	utput	250 VAC~1 A 1a					
Display t	type	7 Segment (red, green), LED type					
Control type	Heating, Cooling	ON/OFF, P, PI, PD, PID Control					
Hysteres	sis	1 to 100 (0.1 to 50.0) °C/°F					
Proporti (P)	onal band	0.1 to 999.9 °C/°F					
Integral	time (I)	0 to 9,999 sec					
Derivativ	ve time (D)	0 to 9,999 sec					
Control	cycle (T)	0.5 to 120.0 sec					
Manual	reset	0.0 to 100.0%					
Relay	Mechanical	$\geq$ 5,000,000 operations					
life cycle	Electrical	$\begin{array}{l} \text{OUT1/2:} \geq 200,\!000 \text{ operations} \left(\text{load resistance: } 250 \text{ VAC} \sim 3 \text{ A}\right) \\ \text{AL1/2:} \geq 300,\!000 \text{ operations} \left(\text{load resistance: } 250 \text{ VAC} \sim 1 \text{ A}\right) \end{array}$					
Dielectri	c strength	Between the charging part and the case: 1,000 VAC~ 50/60 Hz for 1 min					
Vibratio	n	0.75 mm amplitude at frequency of 5 to 55 Hz in each X, Y, Z direction for 2 hours					
Insulation resistance		$\geq$ 100 MΩ (500 VDC== megger)					
Noise im	imunity	$\pm 2$ kV square shaped noise (pulse width: 1 $\mu$ s) by noise simulator R-phase, S-phase					
Memory	retention	pprox 10 years (non-volatile semiconductor memory type)					
Ambient temperature		-10 to 50 °C, storage: -20 to 60 °C (no freezing or condensation)					
Ambient humidity		35 to 85%RH, storage: 35 to 85%RH (no freezing or condensation)					
Insulation type		Mark: , double or reinforced insulation (dielectric strength between the measuring input part and the power part: 1 kV) Mark: , double or reinforced insulation (dielectric strength between the measuring input and the power part: 2 kV)					
Certifica	tion	C E KK 6 <b>93 </b> 005 EAE ©					
Unit wei		- TCN4S: $\approx$ 100 g ( $\approx$ 147 g)	• TCN4M: $\approx$ 133 g ( $\approx$ 203 g)				
(package	ed)	• TCN4H: $\approx$ 124 g ( $\approx$ 194 g)	• TCN4L: $\approx$ 179 g ( $\approx$ 275 g)				

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胜特力电子(深圳)	86-755-83298787
http://www	v.100y.com.tw

<ul> <li>Power supply</li> <li>2: 24 VAC ~ 50/60 Hz, 24-48 VDC=</li> </ul>
4: 100-240 VAC $\sim 50/60~{\rm Hz}$
Control output     R: Relay
S: SSR drive
Wiring type

# Input Type and Using Range

The setting range of some parameters is limited when using the decimal point display.

Input type		Decimal point	Display	Using range (°C	C) Using range (°F)
	14 (64)	1	ЕС Я.Н	-50 to 1,2	00 -58 to 2,192
	K (CA)	0.1	E C A.L	-50.0 to 999	9.9 -58.0 to 999.9
	J (IC)	1	JI E.H	-30 to 800	) -22 to 1,472
	J (IC)	0.1	JI [.L	-30.0 to 800	0.0 -22.0 to 999.9
Thermo	L (IC)	1	LIE.H	-40 to 800	-40 to 1,472
-couple		0.1	LI E.L	-40.0 to 800	0.0 -40.0 to 999.9
	T (CC)	1	Е С С.Н	-50 to 400	-58 to 752
		0.1	ECC.L	-50.0 to 400	0.0 -58.0 to 752.0
	R (PR)	1	rPr	0 to 1,7	00 32 to 3,092
	S (PR)	1	5Pr	0 to 1,7	00 32 to 3,092
	Cu50 Ω	1	C U 5.H	-50 to 200	-58 to 392
RTD		0.1	C U 5.L	-50.0 to 200	0.0 -58.0 to 392.0
KID	DPt100 Ω	1	dPE.H	-100 to 400	) -148 to 752
		0.1	dPt.L	-100.0 to 400	0.0 -148.0 to 752.0

#### Display accuracy

Input type	Using temperature	Display accuracy	
Thermocouple	At room temperature (23°C ±5 °C)	$ \begin{array}{l} (\text{PV}\pm0.5\% \text{ or }\pm1^\circ\text{C} \text{ higher one})\pm1\text{-digit} \\ \bullet \text{Thermocouple R, S below 200^\circ\text{C}:} \\ (\text{PV}\pm0.5\% \text{ or }\pm3^\circ\text{C} \text{ higher one})\pm1\text{-digit} \\ \text{Over 200^\circ\text{C}:} \\ (\text{PV}\pm0.5\% \text{ or }\pm2^\circ\text{C} \text{ higher one})\pm1\text{-digit} \\ \bullet \text{Thermocouple L, RTD Cu50}\Omega: \\ (\text{PV}\pm0.5\% \text{ or }\pm2^\circ\text{C} \text{ higher one})\pm1\text{-digit} \end{array} $	
RTD	Out of room temperature range	$ \begin{array}{l} (\text{PV}\pm0.5\% \text{ or }\pm2\ ^\circ\text{C} \text{ higher one})\pm1\text{-digit} \\ \bullet\text{Thermocouple R, S below 200\ ^\circ\text{C}:} \\ (\text{PV}\pm1.0\% \text{ or }\pm6\ ^\circ\text{C} \text{ higher one})\pm1\text{digit} \\ \text{Over 200\ ^\circ\text{C}:} \\ (\text{PV}\pm0.5\% \text{ or }\pm5\ ^\circ\text{C} \text{ higher one})\pm1\text{digit} \\ \bullet\text{Thermocouple L, RTD Cu50\ }\Omega: \\ (\text{PV}\pm0.5\% \text{ or }\pm3\ ^\circ\text{C} \text{ higher one})\pm1\text{digit} \\ \end{array} $	

For TCN4S —P, add ±1°C by accuracy standard.
 If the input specification is set to 'decimal point 0.1' display, add ±1°C by accuracy standard.

# Unit Descriptions



# 1. PV Display part (red)

• RUN mode: Displays PV (Present value)

Setting mode: Displays parameter name

2. SV Display part (green)

- RUN mode: Displays SV (Setting value)
- · Setting mode: Displays parameter setting value

3.	Indicator	

. indicat	. Indicator						
Display	Name	Description					
AL1/2	Alarm output	Turns ON when the alarm output is ON.					
OUT	Control output	Turns ON when control output is ON • CYCLE/PHASE control of SSR drive output: Turns ON when MV is over 3.0% [AC power model]					
AT	Auto tuning	Flashes during auto tuning every 1 sec					
°C, %, °F	Unit	Displays selected unit (parameter).					

4. Input key					
Display	Name				
[MODE]	Mode key				
[◀], [▼], [▲]	Setting value control key				

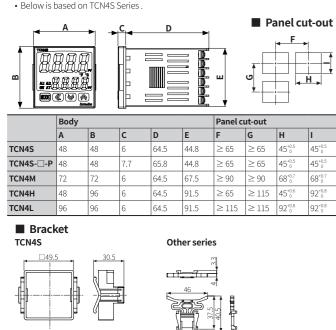
# Errors

Display	Description	Troubleshooting
oPEn	Flashes when input sensor is disconnected or sensor is not connected.	Check input sensor status.
нннн	Flashes when PV is higher than input range. <sup>01)</sup>	When input is within the rated input
LLLL	Flashes when PV is lower than input range. <sup>01)</sup>	range, this display disappears.

01) Be careful that when HHHH / LLLL error occurs, the control output may occur by recognizing the nimum input der nding on the control type

# Dimensions

• Unit: mm, For the detailed drawings, follow the Autonics website. • Below is based on TCN4S Series .



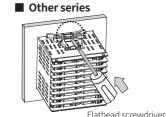
23.9



## Installation Method

TCN4S



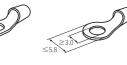


Insert the unit into a panel, fasten the bracket by pushing with a flathead screwdriver.

# **Crimp Terminal Specifications**

• Unit: mm, Use the crimp terminal of follow shape.





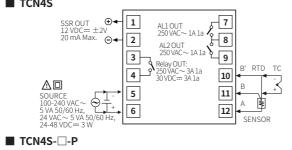
Fork crimp terminal Round crimp terminal

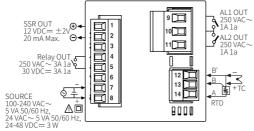
Terminal number	a	b	с
1 to 8	6	$\leq 1.7$	$\leq 3.7$
9 to 11	6 to 8	$\leq 2.1$	≤ 4.2
12 to 14	6 to 8	$\leq 1.5$	$\leq 3.5$

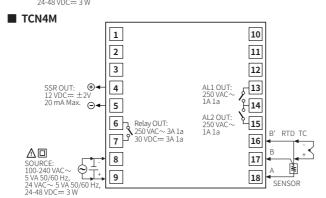
Wire ferrule

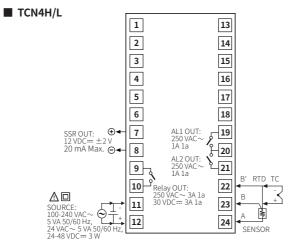
# Connections



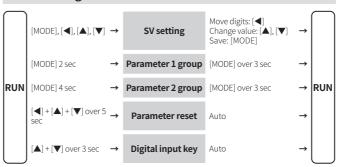








#### Mode Setting



## Parameter Setting

 Some parameters are activated/deactivated depending on the model or setting of other parameters. Refer to the description of each item.

• The setting range in parentheses is for using the decimal point display in the input specification.

• If there is no key input for more than 30 seconds in each parameter, it returns to RUN mode.

• When pressing the [MODE] key within 1 second after returning to the operation mode from the parameter group, it will enter the parameter group before returning.

• [MODE] key: Saves the current parameter setting value and moves to the next narameter

[◀] key: Checks the fixed item / Moves the row when changing the set value

[▲], [▼] keys: Selects the parameter / Changes the set value • Recommended parameter setting sequence: Parameter 2 group → Parameter 1 group

 $\rightarrow$  SV setting mode

#### Parameter 1 group

	_ · · · · · · · · · · · · · · · · · · ·						
Parameter		Display	Default	Setting range	Condition		
1-1	AL1 alarm temperature	AL I	1250	Deviation alarm: -F.S. to F.S. °C/°F	2-12/14 alarm		
1-2	AL2 alarm temperature	AL 2	1250	Absolute value alarm: Within input range	operation: AM1 to AM6		
1-3	Auto tuning	RĿ	oFF	OFF: Stop, ON: Execution			
1-4	Proportional band	Ρ	0 10.0	0.1 to 999.9 °C/°F	2-8 Control		
1-5	Integral time	1	0000	0 (OFF) to 9999 sec	type: PID		
1-6	Derivative time	Ь	0000	0 (OFF) to 9999 sec			
1-7	Manual reset	r E S E	050.0	0.0 to 100.0%	2-8 Control type: PID & 1-5 Integral time: 0		
1-8	Hysteresis	Н У 5	200	1 to 100 (0.1 to 50.0) °C/°F	2-8 Control type: ONOF		

	Parameter		-			
Para	meter	Display	Default	Setting range	Condition	
2-1	Input specification <sup>01)</sup>	In-E	ЧС R.H	Refer to 'Input Type and Using Range'.	-	
2-2	Temperature unit <sup>01)</sup>	Unit	٥٢	°C, °F	-	
2-3	Input correction	In-b	0000	-999 to 999 (-199.9 to 999.9) °C/°F	-	
2-4	Input digital filter	ñ R u.F	000.1	0.1 to 120.0 sec	-	
2-5	SV low limit $^{\scriptscriptstyle (2)}$	L-5u	- 5 0	Within 2-1 Input specification Input	-	
2-6	SV high limit <sup>02)</sup>	H-5u	1200	range,  L-SV ≤ H-SV - 1-digit °C/°F  H-SV ≥ L-SV + 1-digit °C/°F	-	
2-7	Control output mode <sup>03)</sup>	o-FŁ	HERE	HEAT: Heating, COOL: Cooling	-	
2-8	Control type <sup>04)</sup>	[-ād	Pid	PID, ONOF: ON/OFF	-	
2-9	Control output	oUt	гĽУ	RLY: relay, SSR	-	
2-10	SSR drive output type	55r.ñ	S≿∩d	[AC model] STND: standard, CYCL: cycle, PHAS: phase	2-9 Control output: SSR	
2-11	Control cycle	E	20.0	0.5 to 120.0 sec	2-9 Control output: RLY 2-10 SSR drive output type: STND	
	control cycle		2.0		2-9 Control output: SSR 2-10 SSR drive output type: STND	
2-12	AL1 alarm operation	AL-1		AM0: Off AM1: Deviation high limit alarm AM2: Deviation low limit alarm AM3: Deviation high, low limit alarm AM4: Deviation high, low reverse alarm AM5: Absolute value high limit alarm AM6: Absolute value low limit alarm SBA: Sensor break alarm LBA: Loop break alarm (LBA)	-	
2-13	AL1 alarm option					A: Standard alarm B: Alarm latch C: Standby D: Alarm latch and Standby sequence 1 F: Alarm latch and F: Alarm latch and
				in 2-12 AL-1 alarm operation.		
	AL2 alarm operation	AL-2	8 <del>.</del> 2.8	Same as 2-12/13 AL1 alarm operation/		
2-15	AL2 alarm option			option		
2-16	Alarm output hysteresis	януз	00 1	1 to 100 (0.1 to 50.0) °C/°F	2-12/14 AL1/2 alarm operation: AM1 to 6	
2-17	LBA time	L & A.E	0000	0 (OFF) to 9999 sec or auto (auto tunning)	2-12/14 AL1/2 alarm operation: LBA	
2-18	LBA band	L & A. &	0002	0 (OFF) to 999 (0.0 to 999.9) °C/°F or auto (auto tunning)	2-12/14 AL1/2 alarm operation: LBA & 2-18 LBA time: > 0	
2-19	Digital input key	d1 - E	5±0P	STOP: Stop control output, AL.RE: Alarm reset, AT*: Auto tuning execution, OFF	*2-8 Control type: PID	
2-20	Sensor error MV	Er.ñu	000.0	0.0: OFF, 100.0: ON 0.0 to 100.0%	2-8 Control type: ONOF 2-8 Control type: PID	
2-21	Lock	Lo[	٥FF	OFF LOC1: Parameter 2 group lock LOC2: Parameter 1/2 group lock LOC3: Parameter 1/2 group, SV setting lock	-	

01) Below parameters are initialized when the setting value is changed. - Parameter 1 group: AL1/2 alarm temperature

- remeter a group. Acu/2 alotti temperature
 - Parameter 2 group: Input correction, SV high/low limit, Alarm output hysteresis, LBA time, LBA band
 - SV setting mode: SV

02) If SV is lower than low limit or higher than high limit when the value is changed, SV is changed to the low/high limit value

If 2-1 Input specification is changed, the value is changed to Min./Max. value of Input specification.

03) When the setting value is changed, setting value of 2-20 Sensor error MV is initialized to 0.0 (OFF).
04) When changing the value from PID to ONOF, each value of following parameter is changed.
2-19 Digital input key: OFF, 2-20 Sensor error MV: 0.0 (when setting value is lower than 100.0)

