

## Low Cost, High Speed, **Rail-to-Rail Amplifiers**

## AD8051/AD8052/AD8054

#### **FEATURES**

High speed and fast settling on 5 V

110 MHz, -3 dB bandwidth (G = +1) (AD8051/AD8052)

150 MHz, -3 dB bandwidth (G = +1) (AD8054)

145 V/µs slew rate

50 ns settling time to 0.1%

Single-supply operation

Output swings to within 25 mV of either rail Input voltage range: -0.2 V to +4 V;  $V_s = 5 \text{ V}$ 

Video specifications (G = +2)

0.1 dB gain flatness: 20 MHz;  $R_L = 150 \Omega$ Differential gain/phase: 0.03%/0.03°

Low distortion

-80 dBc total harmonic @ 1 MHz, R<sub>L</sub> = 100 Ω

**Outstanding load drive capability** 

Drives 45 mA, 0.5 V from supply rails (AD8051/AD8052)

Drives 50 pF capacitive load (G = +1) (AD8051/AD8052)

Low power: 2.75 mA/amplifier (AD8054)

Low power: 4.4 mA/amplifier (AD8051/AD8052)

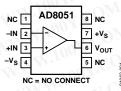
#### **APPLICATIONS**

**Active filters Analog-to-digital drivers** Clock buffer **Consumer video Professional cameras** CCD imaging systems

**CD/DVD ROMs** 

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#### **PIN CONNECTIONS (TOP VIEWS)**



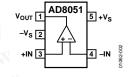
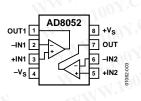


Figure 1. SOIC-8 (R)

Figure 2. SOT-23-5 (RJ)



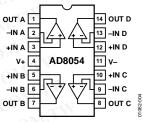


Figure 3. SOIC (R-8) and MSOP (RM-8)

Figure 4, SOIC (R-14) and TSSOP (RU-14)

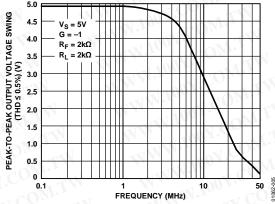


Figure 5. Low Distortion Rail-to-Rail Output Swing

#### **GENERAL DESCRIPTION**

The AD8051 (single), AD8052 (dual), and AD8054 (quad) are low cost, high speed, voltage feedback amplifiers. The amplifiers operate on +3 V, +5 V, or  $\pm 5$  V supplies at low supply current. They have true single-supply capability with an input voltage range extending 200 mV below the negative rail and within 1 V of the positive rail.

Despite their low cost, the AD8051/AD8052/AD8054 provide excellent overall performance and versatility. The output voltage swings to within 25 mV of each rail, providing maximum output dynamic range with excellent overdrive recovery.

The AD8051/AD8052/AD8054 are well suited for video electronics, cameras, video switchers, or any high speed portable equipment. Low distortion and fast settling make them ideal for active filter applications.

The AD8051/AD8052 in the 8-lead SOIC, the AD8052 in the MSOP, the AD8054 in the 14-lead SOIC, and the 14-lead TSSOP packages are available in the extended temperature range of

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Fax: 781.461.3113

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### **SPECIFICATIONS**

Table 1.

Cable 1.	TOM:THE	ADS	3051A/AD	8052A		AD8054A		
Parameter	Conditions	Min	Тур	Max	Min	Тур	Max	Unit
DYNAMIC PERFORMANCE	ON.CO. TW	W	MAL	no V.C.	VTI			
–3 dB Small Signal Bandwidth	$G = +1, V_{OUT} = 0.2 \text{ V p-p}$	70	110		80	150		MHz
	$G = -1, +2, V_{OUT} = 0.2 V p-p$		50		OWIL	60		MHz
Bandwidth for 0.1 dB Flatness	$G = +2$ , $V_{OUT} = 0.2 \text{ V p-p}$ , $R_L = 150 \Omega$ to 2.5 V				COM:			
	$R_F = 806 \Omega \text{ (AD8051A/} AD8052A)$		20		COM!			MHz
	$R_F = 200 \Omega (AD8054A)$	- 7			- c01	12		MHz
Slew Rate	$G = -1$ , $V_{OUT} = 2 V$ step	100	145		140	170		V/µs
Full Power Response	$G = +1, V_{OUT} = 2 V p-p$	N.	35		N.C.	45		MHz
Settling Time to 0.1%	$G = -1$ , $V_{OUT} = 2 V$ step	- 1	50		00 - -7 C	40		ns
NOISE/DISTORTION PERFORMANCE	WW 1007.	1.44			100,	-oM.T		
Total Harmonic Distortion <sup>1</sup>	$f_C = 5 \text{ MHz}, V_{OUT} = 2 \text{ V p-p},$ G = +2	LTW.	-67		100X	-68		dB
Input Voltage Noise	f = 10 kHz	VIII	16		100	16		nV/√Hz
Input Current Noise	f = 10 kHz	Mr.	850		M	850		fA/√Hz
Differential Gain Error (NTSC)	$G = +2$ , $R_L = 150 \Omega$ to 2.5 V	$DM^{*}$	0.09		M.In.	0.07		%
	$R_L = 1 \text{ k}\Omega \text{ to } 2.5 \text{ V}$		0.03		_ 1XX 10	0.02		%
Differential Phase Error (NTSC)	$G = +2$ , $R_L = 150 \Omega$ to 2.5 V	One	0.19		11	0.26		Degrees
	$R_L = 1 \text{ k}\Omega \text{ to } 2.5 \text{ V}$	COM	0.03			0.05		Degrees
Crosstalk	f = 5 MHz, G = +2		-60		N TON	-60		dB
DC PERFORMANCE	WWW	I.Co.	WTI		MAN	100X.	-11	IM
Input Offset Voltage	AL ALWAY.IOU	T CC	1.7	10	WW	1.7	12	mV
	T <sub>MIN</sub> – T <sub>MAX</sub>	7.		25			30	mV
Offset Drift	M MM	OY.C	10			15		μV/°C
Input Bias Current	TWW.		1.4	2.5	TXI Y	2	4.5	μΑ
	T <sub>MIN</sub> – T <sub>MAX</sub>	$700$ $_{I}$ .		3.25			4.5	μΑ
Input Offset Current	TW WW	1007	0.1	0.75		0.2	1.2	μΑ
Open-Loop Gain	$R_L = 2 k\Omega$ to 2.5 V	86	98		82	98		dB
	T <sub>MIN</sub> — T <sub>MAX</sub>	N.100	96			96		dB
	$R_L = 150 \Omega \text{ to } 2.5 \text{ V}$	76	82		74	82		dB
WWW.To C	T <sub>MIN</sub> – T <sub>MAX</sub>	M.	78	TV		78	1005	dB
INPUT CHARACTERISTICS	OM.	WW.	- 1 C	$O_{Mr}$ ,	-XI	WIN	M. In	A COM.
Input Resistance	M.TW W	N'	290		N	300		kΩ
Input Capacitance	CONT	MAN	1.4		W	1.5		pF
Input Common-Mode Voltage Range	Y.COM.	WW	-0.2 to +4		WT	−0.2 to +4		V <sub>Y</sub> .CO
Common-Mode Rejection Ratio	$V_{CM} = 0 \text{ V to } 3.5 \text{ V}$	72	88		70	86		dB

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	OUT.	AD8051A/AD8052A			AD8054A			
Parameter \(\)	Conditions	Min	Тур	Max	Min	Тур	Max	Unit
OUTPUT CHARACTERISTICS	CON	1XI	MM	V.CO	W			
Output Voltage Swing	$R_L = 10 \text{ k}\Omega \text{ to } 2.5 \text{ V}$	1	0.015 to 4.985		MITY	0.03 to 4.975		V
	$R_L = 2 \text{ k}\Omega \text{ to } 2.5 \text{ V}$	0.1 to 4.9	0.025 to 4.975		0.125 to 4.875	0.05 to 4.95		V
	$R_L = 150 \Omega$ to 2.5 V	0.3 to 4.625	0.2 to 4.8		0.55 to 4.4	0.25 to 4.65		V
Output Current	$V_{OUT} = 0.5 \text{ V to } 4.5 \text{ V}$		45		Mon	30		mA
	$T_{MIN} - T_{MAX}$	N	45		Y.Com	30		mA
Short-Circuit Current	Sourcing	- 1	80		TON	45		mA
	Sinking		130		101.	85		mA
Capacitive Load Drive	G = +1 (AD8051/AD8052)	W	50		OOY.CC			pF
	G = +2  (AD8054)	- XXI			ov C	40		pF
POWER SUPPLY	1007	1.1.			100	$-0M_{\odot}$	. 1	
Operating Range	MAN TOOX.CO.	3		12	3		12	V
Quiescent Current/Amplifier	MM. Too CO	NT.	4.4	5	1.20	2.75	3.275	mA
Power Supply Rejection Ratio	$\Delta V_S = \pm 1 V$	70	80		68	80		dB
OPERATING TEMPERATURE RANGE	RJ-5	-40	M	+85	100	7.0	V.TV	°C
	RM-8, R-8, RU-14, R-14	-40		+125	-40		+125	°C

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Table 2.

- TW WW. 100	Y.C.	AD	8051A/AD80	052A	LA	AD8054A	ı	
Parameter	Conditions	Min	Тур	Max	Min	Тур	Max	Unit
DYNAMIC PERFORMANCE	COM	- 11	MMila	A COM	N. T. N.			
–3 dB Small Signal Bandwidth	$G = +1, V_{OUT} = 0.2 V p-p$	70	110		80	135		MHz
	$G = -1, +2, V_{OUT} =$	V	50		TW	65		MHz
	0.2 V p-p				Mr.			
Bandwidth for 0.1 dB Flatness	$G = +2$ , $V_{OUT} = 0.2 \text{ V p-p}$ , $R_L = 150 \Omega \text{ to } 2.5 \text{ V}$				OWI			
	$R_F = 402 \Omega \text{ (AD8051A)}$		17		Low			MHz
	AD8052A)		17		Con			IVITIZ
	$R_F = 200 \Omega \text{ (AD8054A)}$	«T			COM	10		MHz
Slew Rate	$G = -1$ , $V_{OUT} = 2 \text{ V step}$	90	135		110	150		V/µs
Full Power Response	$G = +1, V_{OUT} = 1 V p-p$	W	65		Y.Co	85		MHz
Settling Time to 0.1%	$G = -1$ , $V_{OUT} = 2 V$ step		55		V.CO	55		ns
NOISE/DISTORTION PERFORMANCE	11 100 COM	3.4		1. W.T		JM:	cT	
Total Harmonic Distortion <sup>1</sup>	$f_C = 5 \text{ MHz}, V_{OUT} = 2 \text{ V p-p},$	WIT	-47		100 A.C.	-48		dB
	$G = -1$ , $R_L = 100 \Omega$ to 1.5 V	1			ON.			
Input Voltage Noise	f = 10 kHz	$M_{i,T}$	16		700	16		nV/√Hz
Input Current Noise	f = 10 kHz	TIL	600		111007	600		fA/√Hz
Differential Gain Error (NTSC)	$G = +2, V_{CM} = 1 V$	Ohr.			W			
	$R_L = 150 \Omega \text{ to } 1.5 \text{ V}$	OM	0.11		W.100	0.13		%
	$R_L = 1 \text{ k}\Omega \text{ to } 1.5 \text{ V}$	Mo	0.09		10	0.09		%
Differential Phase Error (NTSC)	$G = +2, V_{CM} = 1 V$	COn			1			
	$R_L = 150 \Omega \text{ to } 1.5 \text{ V}$	CON	0.24			0.3		Degrees
	$R_L = 1 \text{ k}\Omega \text{ to } 1.5 \text{ V}$	Y	0.10			0.1		Degrees
Crosstalk	f = 5  MHz, G = +2	N.Co	-60	-		-60		dB
DC PERFORMANCE	WW.IO	ov.C			WWW			TW
Input Offset Voltage	1. 1.	00 7.	1.6	10		1.6	12	mV
	$T_{MIN} - T_{MAX}$	1007.		25	1/1/1/1		30	mV
Offset Drift	WWW WWW	V	C(10)		WV	15		μV/°C
Input Bias Current	L.I.V	1.100	1.3	2.6		2	4.5	μΑ
WW. 1007.CO	$T_{MIN} - T_{MAX}$	100		3.25			4.5	μΑ
Input Offset Current	WW WW	11.2	0.15	0.8		0.2	1.2	μΑ
Open-Loop Gain	$R_L = 2 k\Omega$	80	96		80	96		dB
	T <sub>MIN</sub> — T <sub>MAX</sub>	XI 1	94			94		dB
	$R_L = 150 \Omega$	74	82		72	80		dB
V 38/W.100	T <sub>MIN</sub> — T <sub>MAX</sub>	WW.	76	Mr.	1	76	N. P	dB
INPUT CHARACTERISTICS	TOMITW	1	17007.					II-COM
Input Resistance	I.CO. TW	MM	290			300		kΩ
Input Capacitance	Z COM.	W.	1.4		· CVV	1.5		pF CO
Input Common-Mode Voltage Range	Dr. COM'I'M	AA .	-0.2 to +2			-0.2 to +2		OV X
Common Mode Paiastian Patia	$V_{CM} = 0 \text{ V to } 1.5 \text{ V}$	72			70			dB
Common-Mode Rejection Ratio	VCM = U V (U 1.5 V	72	88	4.CO	70	86		UD

	$m_{1}$	AD8051A/AD8052A			AD8054A			
Parameter \(\)	Conditions	Min	Тур	Max	Min	Тур	Max	Unit
OUTPUT CHARACTERISTICS	COM	w V	111.	V.CO	W			
Output Voltage Swing	$R_L = 10 \text{ k}\Omega \text{ to } 1.5 \text{ V}$	W	0.01 to 2.99		MITY	0.025 to 2.98		V
	$R_L = 2 \text{ k}\Omega \text{ to } 1.5 \text{ V}$	0.0.75 to 2.9	0.02 to 2.98		0.1 to 2.9	0.35 to 2.965		V
	$R_L = 150 \Omega$ to 1.5 V	0.2 to 2.75	0.125 to 2.875		0.35 to 2.55	0.15 to 2.75		V
Output Current	$V_{OUT} = 0.5 \text{ V to } 2.5 \text{ V}$		45			25		mA
	$T_{MIN} - T_{MAX}$	W	45		V.CO.	25		mA
Short-Circuit Current	Sourcing	]- ` -≪1	60		1 CO	30		mA
	Sinking	IN	90		01.	50		mA
Capacitive Load Drive	G = +1 (AD8051/AD8052)	WT	45		OOY.C.			рF
	G = +2 (AD8054)	1. 1			N.C	35		рF
POWER SUPPLY	W. 1001.	$M_{i,I}$		Wir	Too .	COM	-1	
Operating Range	MM	3		12	300		12	٧
Quiescent Current/Amplifier	WWW.IO OV.C	$O_{Mr}$	4.2	4.8	001	2.625	3.125	mA
Power Supply Rejection Ratio	$\Delta V_S = 0.5 \text{ V}$	68	80	- XX	68	80	. 1	dB
OPERATING TEMPERATURE RANGE	RJ-5	-40		+85	100			°C
	RM-8, R-8, RU-14, R-14	-40		+125	-40		+125	°C

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WWW.100Y.COM.TW <sup>1</sup> Refer to Figure 19.

@  $T_{\text{A}}$  = 25°C,  $V_{\text{S}}$  =  $\pm 5$  V,  $R_{\text{L}}$  = 2  $k\Omega$  to ground, unless otherwise noted.

Table 3.

DM: 100	Condition		51A/AD80			AD8054A	NA -	11
Parameter	Conditions	Min	Тур	Max	Min	Тур	Max	Unit
DYNAMIC PERFORMANCE	AN COMP.		· Voo		W			
–3 dB Small Signal Bandwidth	$G = +1, V_{OUT} = 0.2 \text{ V p-p}$	70	110		85	160		MHz
	$G = -1, +2, V_{OUT} = 0.2 \text{ V p-p}$	MM.	50		TIN	65		MHz
Bandwidth for 0.1 dB Flatness	$G = +2$ , $V_{OUT} = 0.2 \text{ V p-p}$ ,	WW			TW			
	$R_L = 150 \Omega$ ,				Mrr			
	$R_F = 1.1 \text{ k}\Omega \text{ (AD8051A/}$		20		TIME			MHz
	AD8052A)	***			OM	<b>W</b> _		
100 X. W. I.M.	$R_F = 200 \Omega \text{ (AD8054A)}$		SIN.1		OMI	15		MHz
Slew Rate	$G = -1$ , $V_{OUT} = 2 V$ step	105	170		150	190		V/µs
Full Power Response	$G = +1, V_{OUT} = 2 V p-p$	J	40		$CO_{Mr}$	50		MHz
Settling Time to 0.1%	$G = -1$ , $V_{OUT} = 2 V$ step		50	$1100^{\circ}$	LON	40		MHz
NOISE/DISTORTION PERFORMANCE	WWW. 1007.CO				V.C			
Total Harmonic Distortion	$f_C = 5 \text{ MHz}, V_{OUT} = 2 \text{ V p-p},$ G = +2	TW	-71		OY.CO	<b>-72</b>		dB
Input Voltage Noise	f = 10 kHz	·cW	16		V.C.	16		nV/√H:
Input Current Noise	f = 10 kHz	1.1	900		216	900		fA/√Hz
Differential Gain Error (NTSC)	$G = +2$ , $R_L = 150 \Omega$	TW	0.02		1001	0.06		%
COM.	$R_L = 1 k\Omega$	TIN	0.02		· NOV.	0.02		%
Differential Phase Error (NTSC)	$G = +2$ , $R_L = 150 \Omega$	M.r.	0.11		1.700	0.15		Degree
WWW.cox.Co	$R_L = 1 \text{ k}\Omega$	TIN	0.02		100	0.03		Degree
Crosstalk	f = 5 MHz, G = +2	OM	√-60		W	-60		dB
DC PERFORMANCE		COM:	-1		J. W. 14	1.00	M-	4.1
Input Offset Voltage	WW. 100X.	TILL	1.8	11	× 10	1.8	13	mV
input onset voltage	T <sub>MIN</sub> – T <sub>MAX</sub>	COMP	1.0	27	MM·	1.0 CC	32	mV
Offset Drift	TMIN — TMAX	MOD	10	21	W.	15	32	μV/°C
Input Bias Current	W WW 100		1.4	26	N. V.	15 2	4.5	
input bias current	THE TOWN. 10	ST CON	1.4	2.6		. 2		μΑ
100 10 M	T <sub>MIN</sub> – T <sub>MAX</sub>	101	1, 1, 1,	3.5	-31	1,100	4.5	μΑ
Input Offset Current	SWILL WWW	MAY.CO	0.1	0.75		0.2	1.2	μΑ
Open-Loop Gain	$R_L = 2 k\Omega$	88	96		84	96		dB
	T <sub>MIN</sub> - T <sub>MAX</sub>	1001.	96			96		dB
	$R_L = 150 \Omega$	78	82		76	82		dB
W.100	T <sub>MIN</sub> — T <sub>MAX</sub>	1.10	80	- <b>S</b> I		80	- T	dB
INPUT CHARACTERISTICS	M.TW WY	M 100 Y.			N.			COM
Input Resistance	ON WW	100	290		4	300		kΩ
Input Capacitance	COM.	111.100	1.4			1.5		pF
Input Common-Mode Voltage Range	TIN W	100 xx	-5.2 to			-5.2 to		V
	CONTRACTOR IN		+4		N	+4		N.C.
Common-Mode Rejection Ratio	$V_{CM} = -5 \text{ V to } +3.5 \text{ V}$	72	88	)	70	86	11.10	dB
OUTPUT CHARACTERISTICS	Y.C.	1						M 7.
Output Voltage Swing	$R_L = 10 \text{ k}\Omega$	MM	-4.98 to		W	-4.97 to		V
	COM		+4.98		-XXI	+4.97		
	$R_L = 2 k\Omega$	-4.85 to	-4.97 to		-4.8 to	-4.9 to		V
	COM	+4.85	+4.97		+4.8	+4.9		- 100
	$R_L = 150 \Omega$	-4.45 to	-4.6 to		-4.0 to	-4.5 to		V
WW.	00\:\.\.\.\.\.\.\.\.\.\.\.\.\.\.\.\.\	+4.3	+4.6		+3.8	+4.5		W.101
Output Current	$V_{OUT} = -4.5 \text{ V to } +4.5 \text{ V}$		45		7	30		mA
NV '	$T_{MIN} - T_{MAX}$		45		$O_{Mr}$ ,	30		mA
Short-Circuit Current	Sourcing		100		LOW!	60		mA
	Sinking	4	160		CON	100		mA
Capacitive Load Drive	G = +1 (AD8051/AD8052)		50					pF
	G = +2  (AD8054)	N			1	40		рF

10	0.01.	AD8	051A/AD8	052A	- 1	AD8054A	L	
Parameter \(\square\)	Conditions	Min	Тур	Max	Min	Тур	Max	Unit
POWER SUPPLY	COM	Win	W.	COM	W			
Operating Range	TOO J. COM'I	3		12	3		12	٧
Quiescent Current/Amplifier	100Y. COTTW	M/	4.8	5.5	MIN	2.875	3.4	mA
Power Supply Rejection Ratio	$\Delta V_S = \pm 1$	68	80		68	80		dB
OPERATING TEMPERATURE RANGE	RJ-5	-40	TAIW.II	+85	Dir	-XX		°C
	RM-8, R-8, RU-14, R-14	-40		+125	-40		+125	°C

MMM.100X.

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#### **ABSOLUTE MAXIMUM RATINGS**

Table 4.

Parameter	Ratings
Supply Voltage	12.6 V
Internal Power Dissipation <sup>1</sup>	A COM.
SOIC Packages	Observe power derating curves
SOT-23 Package	Observe power derating curves
MSOP Package	Observe power derating curves
TSSOP Package	Observe power derating curves
Input Voltage (Common Mode)	±V <sub>S</sub>
Differential Input Voltage	±2.5 V
Output Short-Circuit Duration	Observe power derating curves
Storage Temperature Range (R)	−65°C to +150°C
Operating Temperature Range (A Grade)	-40°C to +125°C
Lead Temperature (Soldering 10 sec)	300°C

<sup>&</sup>lt;sup>1</sup> See Table 5.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### THERMAL RESISTANCE

Specification is for device in free air.

**Table 5. Thermal Resistance** 

Package Type	Αιθ	Unit
8-Lead SOIC	125	°C/W
5-Lead SOT-23	180	°C/W
8-Lead MSOP	150	°C/W
14-Lead SOIC	90	°C/W
14-Lead TSSOP	120	°C/W

#### **MAXIMUM POWER DISSIPATION**

The maximum power that can be safely dissipated by the AD8051/AD8052/AD8054 is limited by the associated rise in junction temperature. The maximum safe junction temperature for plastic encapsulated devices is determined by the glass transition temperature of the plastic, approximately 150°C. Temporarily exceeding this limit can cause a shift in parametric performance due to a change in the stresses exerted on the die by the package. Exceeding a junction temperature of 175°C for an extended period can result in device failure.

While the AD8051/AD8052/AD8054 are internally short-circuit protected, this cannot be sufficient to guarantee that the maximum junction temperature (150°C) is not exceeded under all conditions. To ensure proper operation, it is necessary to observe the maximum power derating curves.

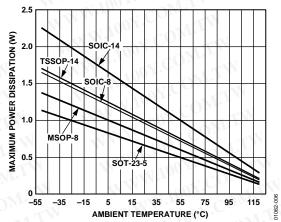


Figure 6. Maximum Power Dissipation vs. Temperature for AD8051/AD8052/AD8054

#### **ESD CAUTION**



**ESD** (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

### TYPICAL PERFORMANCE CHARACTERISTICS

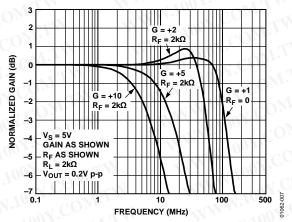


Figure 7. AD8051/AD8052 Normalized Gain vs. Frequency;  $V_S = 5 V$ 

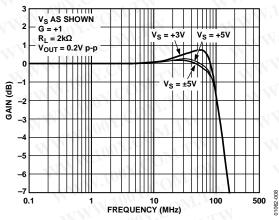


Figure 8. AD8051/AD8052 Gain vs. Frequency vs. Supply

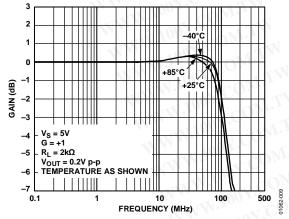


Figure 9. AD8051/AD8052 Gain vs. Frequency vs. Temperature

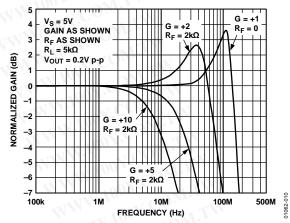


Figure 10. AD8054 Normalized Gain vs. Frequency;  $V_S = 5 V$ 

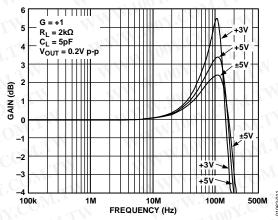


Figure 11. AD8054 Gain vs. Frequency vs. Supply

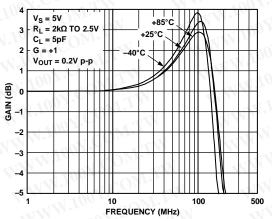


Figure 12. AD8054 Gain vs. Frequency vs. Temperature

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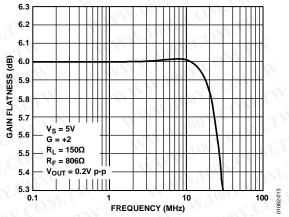


Figure 13. AD8051/AD8052 0.1 dB Gain Flatness vs. Frequency; G = +2

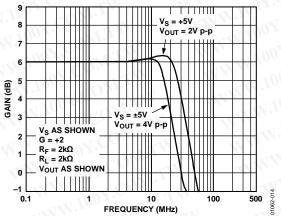


Figure 14. AD8051/AD8052 Large Signal Frequency Response; G = +2

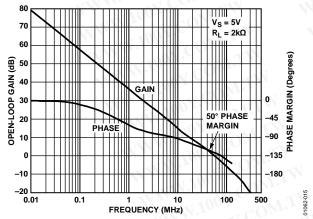


Figure 15. AD8051/AD8052 Open-Loop Gain and Phase vs. Frequency

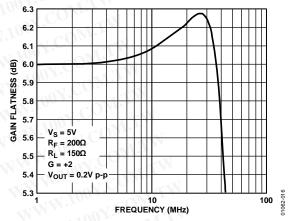


Figure 16. AD8054 0.1 dB Gain Flatness vs. Frequency; G = +2

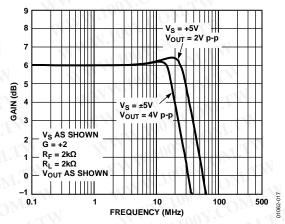


Figure 17. AD8054 Large Signal Frequency Response; G = +2

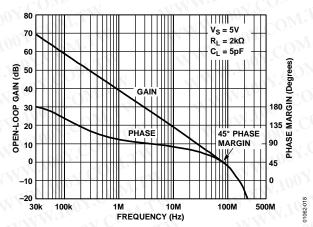


Figure 18. AD8054 Open-Loop Gain and Phase Margin vs. Frequency

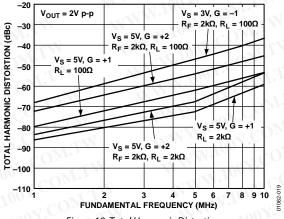


Figure 19. Total Harmonic Distortion

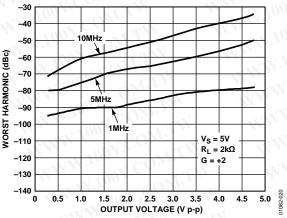


Figure 20. Worst Harmonic vs. Output Voltage

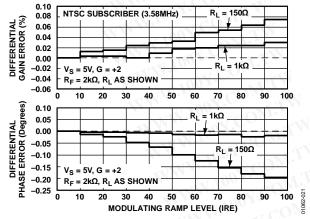


Figure 21. AD8051/AD8052 Differential Gain and Phase Errors

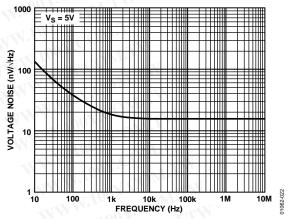


Figure 22. Input Voltage Noise vs. Frequency

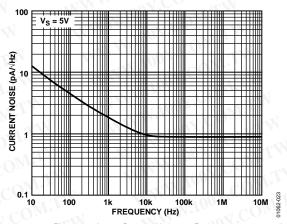


Figure 23. Input Current Noise vs. Frequency

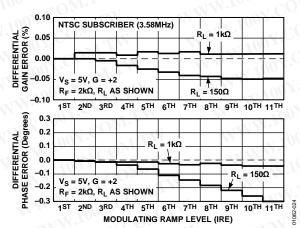


Figure 24. AD8054 Differential Gain and Phase Errors

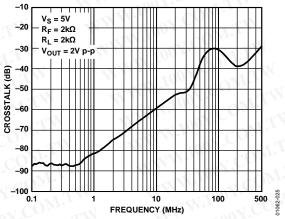


Figure 25. AD8052 Crosstalk (Output-to-Output) vs. Frequency

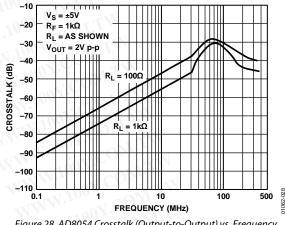


Figure 28. AD8054 Crosstalk (Output-to-Output) vs. Frequency

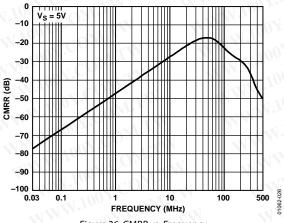


Figure 26. CMRR vs. Frequency

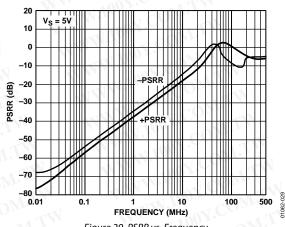


Figure 29. PSRR vs. Frequency

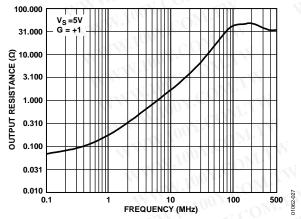


Figure 27. Closed-Loop Output Resistance vs. Frequency

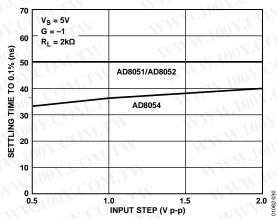
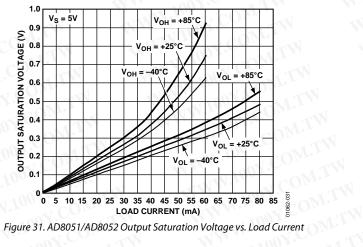


Figure 30. Settling Time vs. Input Step



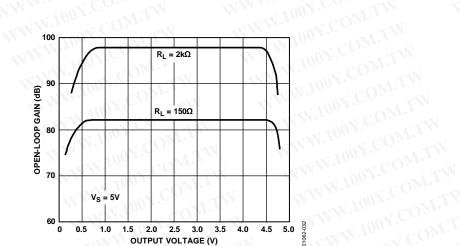
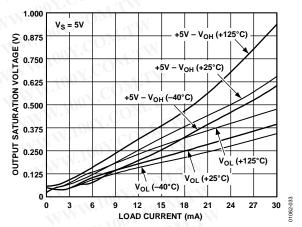


Figure 32. Open-Loop Gain vs. Output Voltage



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Figure 33. AD8054 Output Saturation Voltage vs. Load Current

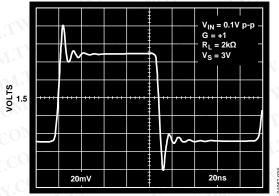
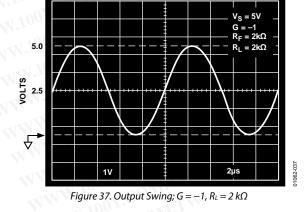


Figure 34. 100 mV Step Response, G = +1



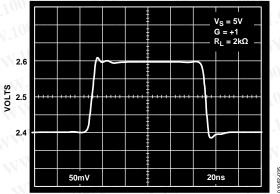


Figure 35. AD8051/AD8052 200 mV Step Response;  $V_S = 5 \text{ V}$ , G = +1

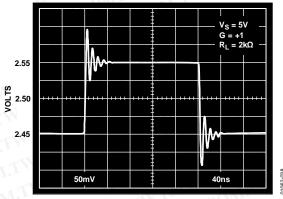


Figure 38. AD8054 100 mV Step Response;  $V_S = 5 V$ , G = +1

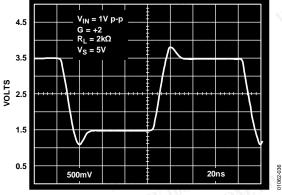


Figure 36. Large Signal Step Response;  $V_S = 5 V$ , G = +2

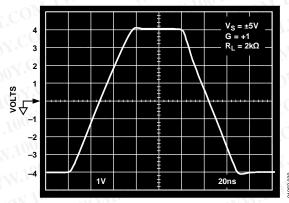


Figure 39. Large Signal Step Response;  $V_S = \pm 5 V$ , G = +1

## THEORY OF OPERATION CIRCUIT DESCRIPTION

The AD8051/AD8052/AD8054 are fabricated on the Analog Devices, Inc. proprietary eXtra-Fast Complementary Bipolar (XFCB) process, which enables the construction of PNP and NPN transistors with similar fTs in the 2 GHz to 4 GHz region. The process is dielectrically isolated to eliminate the parasitic and latch-up problems caused by junction isolation. These features allow the construction of high frequency, low distortion amplifiers with low supply currents. This design uses a differential output input stage to maximize bandwidth and headroom (see Figure 40). The smaller signal swings required on the first stage outputs (nodes SIP, SIN) reduce the effect of nonlinear currents due to junction capacitances and improve the distortion performance. This design achieves harmonic distortion of  $-80~\rm dBc$  @ 1 MHz into 100  $\Omega$  with  $V_{\rm OUT}$  = 2 V p-p (gain = +1) on a single 5 V supply.

The inputs of the device can handle voltages from -0.2 V below the negative rail to within 1 V of the positive rail. Exceeding these values do not cause phase reversal; however, the input ESD devices begin to conduct if the input voltages exceed the rails by greater than 0.5 V. During this overdrive condition, the output stays at the rail.

The rail-to-rail output range of the AD8051/AD8052/AD8054 is provided by a complementary common emitter output stage. High output drive capability is provided by injecting all output stage predriver currents directly into the bases of the output devices Q8 and Q36. Biasing of Q8 and Q36 is accomplished by I8 and I5, along with a common-mode feedback loop (not shown). This circuit topology allows the AD8051/AD8052 to drive 45 mA of output current and allows the AD8054 to drive 30 mA of output current with the outputs within 0.5 V of the supply rails.

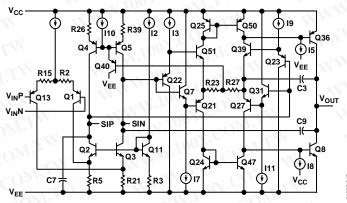


Figure 40. AD8051/AD8052 Simplified Schematic

# APPLICATION INFORMATION OVERDRIVE RECOVERY

Overdrive of an amplifier occurs when the output and/or input range is exceeded. The amplifier must recover from this overdrive condition. As shown in Figure 41, the AD8051/AD8052/AD8054 recover within 60 ns from negative overdrive and within 45 ns from positive overdrive.

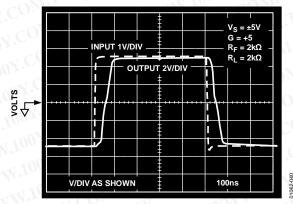


Figure 41. Overdrive Recovery

#### **DRIVING CAPACITIVE LOADS**

Consider the AD8051/AD8052 in a closed-loop gain of +1 with  $+V_s=5$  V and a load of 2 k $\Omega$  in parallel with 50 pF. Figure 42 and Figure 43 show their frequency and time domain responses, respectively, to a small-signal excitation. The capacitive load drive of the AD8051/AD8052/AD8054 can be increased by adding a low value resistor in series with the load. Figure 44 and Figure 45 show the effect of a series resistor on the capacitive drive for varying voltage gains. As the closed-loop gain is increased, the larger phase margin allows for larger capacitive loads with less peaking. Adding a series resistor with lower closed-loop gains accomplishes the same effect. For large capacitive loads, the frequency response of the amplifier is dominated by the roll-off of the series resistor and the load capacitance.

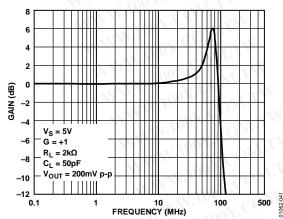


Figure 42. AD8051/AD8052 Closed-Loop Frequency Response;  $C_L = 50 \text{ pF}$ 

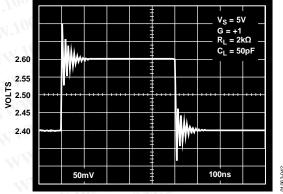


Figure 43. AD8051/AD8052 200 mV Step Response;  $C_L = 50 pF$ 

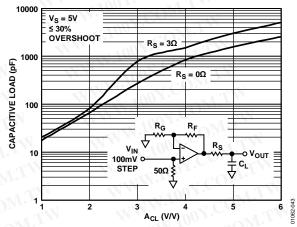


Figure 44. AD8051/AD8052 Capacitive Load Drive vs. Closed-Loop Gain

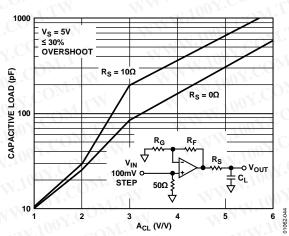


Figure 45. AD8054 Capacitive Load Drive vs. Closed-Loop Gain

#### LAYOUT CONSIDERATIONS

The specified high speed performance of the AD8051/AD8052/AD8054 requires careful attention to board layout and component selection. Proper RF design techniques and low parasitic component selection are necessary.

The PCB should have a ground plane covering all unused portions of the component side of the board to provide a low impedance path. The ground plane should be removed from the area near the input pins to reduce parasitic capacitance.

Chip capacitors should be used for supply bypassing. One end should be connected to the ground plane and the other within 3 mm of each power pin. An additional large (4.7  $\mu F$  to 10  $\mu F$ ) tantalum electrolytic capacitor should be connected in parallel, but not necessarily so close, to supply current for fast, large signal changes at the output.

The feedback resistor should be located close to the inverting input pin to keep the parasitic capacitance at this node to a minimum. Parasitic capacitance of less than 1 pF at the inverting input can significantly affect high speed performance.

Stripline design techniques should be used for long signal traces (greater than about 25 mm). These should be designed with a characteristic impedance of 50  $\Omega$  or 75  $\Omega$  and be properly terminated at each end.

#### **ACTIVE FILTERS**

Active filters at higher frequencies require wider bandwidth op amps to work effectively. Excessive phase shift produced by lower frequency op amps can significantly affect active filter performance.

Figure 46 shows an example of a 2 MHz biquad bandwidth filter that uses three op amps of an AD8054. Such circuits are sometimes used in medical ultrasound systems to lower the

noise bandwidth of the analog signal before analog-to-digital conversion.

Note that the unused amplifier's inputs should be tied to ground.

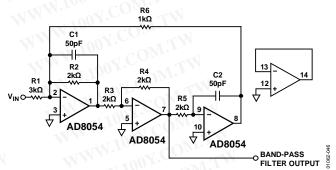


Figure 46. 2 MHz Biquad Band-Pass Filter Using AD8054

The frequency response of the circuit is shown in Figure 47.

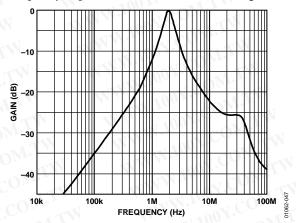


Figure 47. Frequency Response of 2 MHz Band-Pass Biquad Filter

#### ANALOG-TO-DIGITAL AND DIGITAL-TO-ANALOG **APPLICATIONS**

Figure 50 is a schematic showing the AD8051 used as a driver for an AD9201, a 10-bit, 20 MSPS, dual analog-to-digital converter. This converter is designed to convert I and Q signals in communications systems. In this application, only the I channel is being driven. The I channel is enabled by applying a logic high to SELECT (Pin 13).

The AD8051 is running from a dual supply and is configured for a gain of +2. The input signal is terminated in 50  $\Omega$  and the output is 2 V p-p, which is the maximum input range of the AD9201. The 22  $\Omega$  series resistor limits the maximum current that flows and helps to lower the distortion of the ADC.

The AD9201 has differential inputs for each channel. These are designated the A and B inputs. The B inputs of each channel are connected to VREF (Pin 22), which supplies a positive reference of 2.5 V. Each of the B inputs has a small low-pass filter that also helps to reduce distortion.

The output of the op amp is ac-coupled into INA-I (Pin 16) via two parallel capacitors to provide good high frequency and low frequency coupling. The 1  $k\Omega$  resistor references the signal to VREF that is applied to INB-I. Thus, INA-I swings both positive and negative with respect to the bias voltage applied to INB-I.

With the sampling clock running at 20 MSPS, the analog-todigital output was analyzed with a digital analyzer. Two input frequencies were used, 1 MHz and 9.5 MHz, which is just short of the Nyquist frequency. These signals were well filtered to minimize any harmonics.

Figure 48 shows the FFT response of the ADC for the case of a 1 MHz analog input. The SFDR is 71.66 dB, and the analog-todigital is producing 8.8 ENOB (effective number of bits). When the analog frequency was raised to 9.5 MHz, the SFDR was

reduced to -60.18 dB and the ADC operated with 8.46 ENOBs as shown in Figure 49. The inclusion of the AD8051 in the circuit did not worsen the distortion performance of the AD9201.

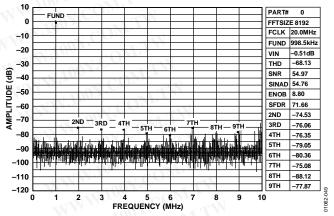


Figure 48. FFT Plot for AD8051 Driving the AD9201 at 1 MHz

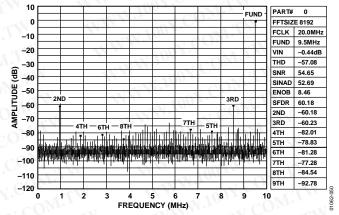


Figure 49. FFT Plot for AD8051 Driving the AD9201 at 9.5 MHz

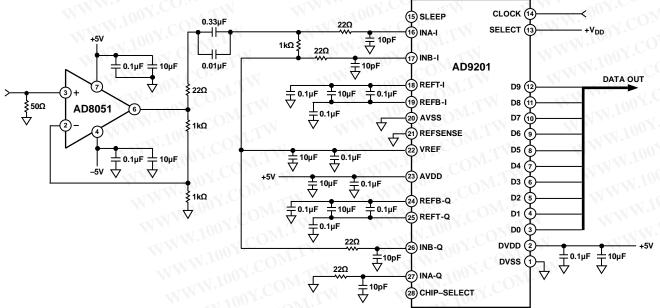


Figure 50. The AD8051 Driving an AD9201, a 10-Bit, 20 MSPS Analog-to-Digital Converter Rev. J | Page 19 of 24

#### **SYNC STRIPPER**

Synchronizing pulses are sometimes carried on video signals so as not to require a separate channel to carry the synchronizing information. However, for some functions, such as analog-todigital conversion, it is not desirable to have the sync pulses on the video signal. These pulses reduce the dynamic range of the video signal and do not provide any useful information for such a function.

A sync stripper removes the synchronizing pulses from a video signal while passing all the useful video information. Figure 51 shows a practical single-supply circuit that uses only a single AD8051. It is capable of directly driving a reverse terminated video line.

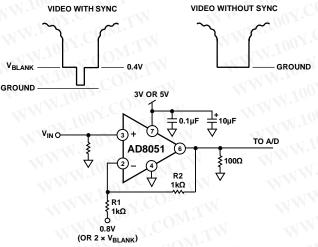


Figure 51. Sync Stripper

The video signal plus sync is applied to the noninverting input with the proper termination. The amplifier gain is set to 2 via the two 1 k $\Omega$  resistors in the feedback circuit. A bias voltage must be applied to R1 so that the input signal has the sync pulses stripped at the proper level.

The blanking level of the input video pulse is the desired place to remove the sync information. This level is multiplied by 2 by the amplifier. This level must be at ground at the output for the sync stripping action to take place. Since the gain of the amplifier from the input of R1 to the output is -1, a voltage equal to  $2 \times V_{BLANK}$ must be applied to make the blanking level come out at ground.

#### SINGLE-SUPPLY COMPOSITE VIDEO LINE DRIVER

Many composite video signals have their blanking level at ground and have video information that is both positive and negative. Such signals require dual-supply amplifiers to pass them. However, by ac level shifting, a single-supply amplifier can be used to pass these signals. The following complications can arise from such techniques.

Signals of bounded peak-to-peak amplitude that vary in duty cycle require larger dynamic swing capacity than their (bounded) peak-to-peak amplitude after they are ac-coupled. As a worst case, the dynamic signal swing will approach twice the peak-topeak value. The two conditions that define the maximum

dynamic swing requirements are a signal that is mostly low but goes high with a duty cycle that is a small fraction of a percent, and the other extreme defined by the opposite condition.

The worst case of composite video is not quite this demanding. One bounding condition is a signal that is mostly black for an entire frame but has a white (full amplitude) minimum width spike at least once in a frame.

The other extreme is for a full white video signal. The blanking intervals and sync tips of such a signal have negative-going excursions in compliance with the composite video specifications. The combination of horizontal and vertical blanking intervals limit such a signal to being at the highest (white) level for a maximum of about 75% of the time.

As a result of the duty cycles between the two extremes previously presented, a 1 V p-p composite video signal that is multiplied by a gain of 2 requires about 3.2 V p-p of dynamic voltage swing at the output for an op amp to pass a composite video signal of arbitrarily varying duty cycle without distortion.

Some circuits use a sync tip clamp to hold the sync tips at a relatively constant level to lower the amount of dynamic signal swing required. However, these circuits can have artifacts, such as sync tip compression, unless they are driven by a source with a very low output impedance. The AD8051/AD8052/AD8054 have adequate signal swing when running on a single 5 V supply to handle an ac-coupled composite video signal.

The input to the circuit in Figure 52 is a standard composite (1 V p-p) video signal that has the blanking level at ground. The input network level shifts the video signal by means of ac coupling. The noninverting input of the op amp is biased to half of the supply voltage.

The feedback circuit provides unity gain for the dc-biasing of the input and provides a gain of 2 for any signals that are in the video bandwidth. The output is ac-coupled and terminated to drive the line.

The capacitor values were selected for providing minimum tilt or field time distortion of the video signal. These values would be required for video that is considered to be studio or broadcast quality. However, if a lower consumer grade of video, sometimes referred to as consumer video, is all that is desired, the values and the cost of the capacitors can be reduced by as much as a factor of five with minimum visible degradation in the picture

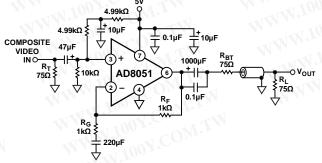
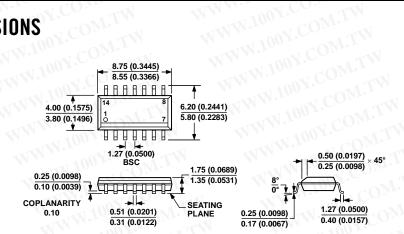


Figure 52. Single-Supply Composite Video Line Driver

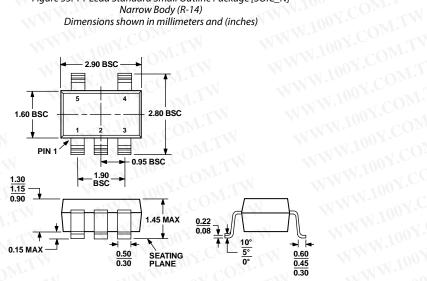
### **OUTLINE DIMENSIONS**



#### **COMPLIANT TO JEDEC STANDARDS MS-012-AB**

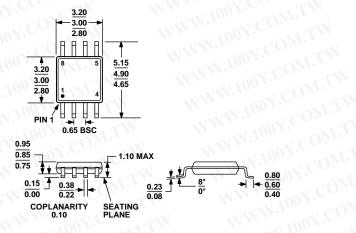
CONTROLLING DIMENSIONS ARE IN MILLIMETERS: INCH DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

WW.100Y.COM.TW Figure 53. 14-Lead Standard Small Outline Package [SOIC\_N] Narrow Body (R-14) Dimensions shown in millimeters and (inches)



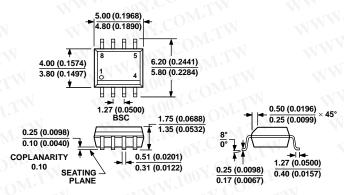
#### COMPLIANT TO JEDEC STANDARDS MO-178-A A

Figure 54. 5-Lead Small Outline Transistor Package [SOT-23] (RJ-5)Dimensions shown in millimeters WWW.100Y.COM.



#### COMPLIANT TO JEDEC STANDARDS MO-187-AA

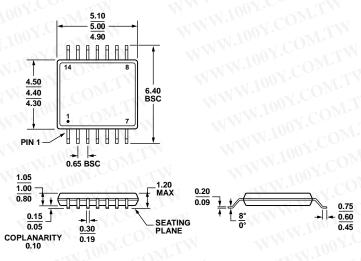
Figure 55. 8-Lead Mini Small Outline Package [MSOP] (RM-8) Dimensions shown in millimeters



#### COMPLIANT TO JEDEC STANDARDS MS-012-A A

CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

Figure 56. 8-Lead Standard Small Outline Package [SOIC\_N] Narrow Body (R-8) Dimensions shown in millimeters and (inches)



COMPLIANT TO JEDEC STANDARDS MO-153-AB-1

Figure 57. 14-Lead Thin Shrink Small Outline Package [TSSOP] (RU-14) Dimensions shown in millimeters

#### **ORDERING GUIDE**

Model	Temperature Range	Package Description	Package Option	Branding
AD8051AR	-40°C to +125°C	8-Lead SOIC_N	R-8	
AD8051AR-REEL	-40°C to +125°C	8-Lead SOIC_N, 13" Tape and Reel	R-8	
AD8051AR-REEL7	-40°C to +125°C	8-Lead SOIC_N, 7" Tape and Reel	R-8	
AD8051ARZ <sup>1</sup>	-40°C to +85°C	8-Lead SOIC_N	R-8	
AD8051ARZ-REEL <sup>1</sup>	-40°C to +85°C	8-Lead SOIC_N, 13" Tape and Reel	R-8	
AD8051ARZ-REEL7 <sup>1</sup>	−40°C to +85°C	8-Lead SOIC_N, 7" Tape and Reel	R-8	
AD8051ART-R2	-40°C to +85°C	5-Lead SOT-23, 7" Tape and Reel	RJ-5	H2A
AD8051ART-REEL	-40°C to +85°C	5-Lead SOT-23, 13" Tape and Reel	RJ-5	H2A
AD8051ART-REEL7	-40°C to +85°C	5-Lead SOT-23, 7" Tape and Reel	RJ-5	H2A
AD8051ARTZ-R2 <sup>1</sup>	-40°C to +85°C	5-Lead SOT-23, 7" Tape and Reel	RJ-5	H06
AD8051ARTZ-REEL <sup>1</sup>	-40°C to +85°C	5-Lead SOT-23, 13" Tape and Reel	RJ-5	H06
AD8051ARTZ-REEL7 <sup>1</sup>	-40°C to +85°C	5-Lead SOT-23, 7" Tape and Reel	RJ-5	H06
AD8052AR	-40°C to +125°C	8-Lead SOIC_N	R-8	
AD8052AR-REEL	-40°C to +125°C	8-Lead SOIC_N, 13" Tape and Reel	R-8	
AD8052AR-REEL7	-40°C to +125°C	8-Lead SOIC_N, 7" Tape and Reel	R-8	
AD8052ARZ <sup>1</sup>	-40°C to +125°C	8-Lead SOIC_N	R-8	
AD8052ARZ-REEL <sup>1</sup>	-40°C to +125°C	8-Lead SOIC_N, 13" Tape and Reel	R-8	
AD8052ARZ-REEL7 <sup>1</sup>	-40°C to +125°C	8-Lead SOIC_N, 7" Tape and Reel	R-8	ſ
AD8052ARM	-40°C to +125°C	8-Lead MSOP	RM-8	H4A
AD8052ARM-REEL	-40°C to +125°C	8-Lead MSOP, 13" Tape and Reel	RM-8	M4A
AD8052ARM-REEL7	-40°C to +125°C	8-Lead MSOP, 7" Tape and Reel	RM-8	H4A
AD8052ARMZ <sup>1</sup>	-40°C to +125°C	8-Lead MSOP	RM-8	H4A#
AD8052ARMZ-REEL7 <sup>1</sup>	-40°C to +125°C	8-Lead MSOP, 7" Tape and Reel	RM-8	H4A#
AD8054AR	-40°C to +125°C	14-Lead SOIC_N	R-14	-XN
AD8054AR-REEL	-40°C to +125°C	14-Lead SOIC_N, 13" Tape and Reel	R-14	VIII
AD8054AR-REEL7	-40°C to +125°C	14-Lead SOIC_N, 7" Tape and Reel	R-14	WILL
AD8054ARZ <sup>1</sup>	-40°C to +125°C	14-Lead SOIC_N	R-14	J. T.
AD8054ARZ-REEL <sup>1</sup>	-40°C to +125°C	14-Lead SOIC_N, 13" Tape and Reel	R-14	$M_{i,I}$
AD8054ARZ-REEL7 <sup>1</sup>	-40°C to +125°C	14-Lead SOIC_N, 7" Tape and Reel	R-14	WILL
AD8054ARU	−40°C to +125°C	14-Lead TSSOP	RU-14	Dir
AD8054ARU-REEL	-40°C to +125°C	14-Lead TSSOP, 13" Tape and Reel	RU-14	COM:1
AD8054ARU-REEL7	-40°C to +125°C	14-Lead TSSOP, 7" Tape and Reel	RU-14	TIME
AD8054ARUZ <sup>1</sup>	-40°C to +125°C	14-Lead TSSOP	RU-14	A COM
AD8054ARUZ-REEL <sup>1</sup>	-40°C to +125°C	14-Lead TSSOP, 13" Tape and Reel	RU-14	COM.
AD8054ARUZ-REEL71	-40°C to +125°C	14-Lead TSSOP, 7" Tape and Reel	RU-14	OX.C

 $<sup>^{1}</sup>$  Z = RoHS Compliant Part. # denotes lead-free product may be top or bottom marked. WWW.100Y.COM.TW WWW.100Y.COM.TW

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