





# **CLC401**

# Fast Settling, Wideband High Gain Monolithic Op Amp

# **General Description**

The CLC401 is a wideband, fast settling op amp designed for applications requiring gains greater than ±7. Constructed using an advanced complementary bipolar process and a proprietary design, the CLC401 features dynamic performance far beyond that of typical high speed monolithic op amps. For example, at a gain of +20, the –3dB bandwidth is 150MHz and the rise/fall time is only 2.5ns.

The wide bandwidth and linear phase (0.2° deviation from linear at 50MHz) and a very flat gain response makes the CLC401 ideal for many digital communication system applications. For example, demodulators need both DC coupling and high frequency amplification-requirements that are ordinarily difficult to meet.

The very fast 10ns settling to 0.1% and the ability to drive capacitive loads lend themselves well to flash A/D applications. Systems employing D/A converters also benefit from the settling time and also by the fact that current-to-voltage transimpedance amplification is easily accomplished.

The CLC401 provides a quick, effective design solution. Its stable operation over the entire ±7 to ±50 gain range precludes the need for external compensation. And, unlike many other high speed-op amps, the CLC401's power dissipation of 150mW is compatible with designs which must limit total power dissipation or power supply requirements.

The CLC401 is based on **National's** proprietary op amp topology that uses current feedback instead of the usual voltage feedback. This unique design has many advantages over conventional designs (such as settling time that is relatively independent of gain), yet it is used in basically the same way (see the gain equations in *Figure 1* and *Figure 2*). However, an understanding of the topology will aid in achieving the best performance. The discussion below will proceed for the non-inverting gain configuration with the inverting mode analysis being very similar.

# **Enhanced Solutions (Military/Aerospace)**

SMD Number: 5962-89973

Space level versions also available.

For more information, visit http://www.national.com/mil

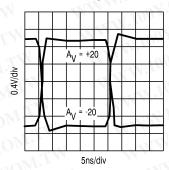
# **Features**

- -3dB bandwidth of 150MHz
- 0.1% settling in 10ns
- Low power, 150mW
- Overload and short circuit protected
- Stable without compensation
- Recommended gain range, ±7 to ±50

# **Applications**

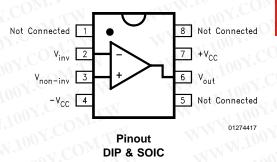
- Flash, precision A/D conversion
- Photodiode, CCD preamps
- IF processors
- High speed modems, radios
- Line drivers
- DC coupled log amplifiers
- High speed communications

## Pulse Response

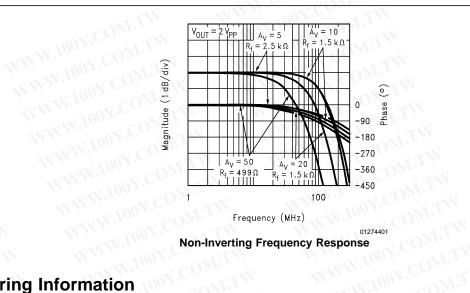


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# **Connection Diagram**



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Non-Inverting Frequency Response

# **Ordering Information**

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Package	Temperature Range Industrial	Part Number	Package Marking	NSC Drawing
8-pin plastic DIP	-40°C to +85°C	CLC401AJP	CLC401AJP	N08E
8-pin plastic SOIC	-40°C to +85°C	CLC401AJE	CLC401AJE	M08A

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# **Absolute Maximum Ratings** (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Supply Voltage (V<sub>CC</sub>) ±7V

 $I_{OUT}$ 

Output is short circuit protected to ground, but maximum reliability will be maintained if  $I_{\rm OUT}$  does not

exceed... 60mA
Common Mode Input Voltage ±V<sub>CC</sub>

Differential Input Voltage 5

Junction Temperature Range +150°C

Operating Temperature Range -40°C to +85°C

Storage Temperature Range -65°C to +150°C

Lead Solder Duration (+300°C) 10 sec

# **Operating Ratings**

Thermal Resistance

 $\begin{array}{lll} \mbox{Package} & (\theta_{\mbox{\scriptsize JC}}) & (\theta_{\mbox{\scriptsize JA}}) \\ \mbox{MDIP} & 70\mbox{\ensuremath{}^{\circ}\mbox{\scriptsize C/W}} & 125\mbox{\ensuremath{}^{\circ}\mbox{\scriptsize C/W}} \\ \mbox{SOIC} & 65\mbox{\ensuremath{}^{\circ}\mbox{\scriptsize C/W}} & 145\mbox{\ensuremath{}^{\circ}\mbox{\scriptsize C/W}} \end{array}$ 

# **Electrical Characteristics**

 $(A_V = +20, V_{CC} = \pm 5V, R_L = 100\Omega, R_f = 1.5k\Omega; unless specified)$ 

Symbol	Parameter	Conditions	Тур	Max/Min Ratings (Note 2)			Units
Ambient T	emperature	CLC401AJ	+25°C	-40°C	+25°C	+85°C	
Frequency	y Domain Response	M.Ing. COM.	×1	TANW.	100 ×1 (	OM.	ON .
SSBW	-3dB Bandwidth	$V_{OUT} < 2V_{PP}$	150	>100	>100	>70	MHz
LSBW	ON COMPANY W	$V_{OUTt} < 5V_{PP}$	100	>65	>65	>55	MHz
WIN	Gain Flatness	V <sub>OUT</sub> < 2V <sub>PP</sub>	and i	WW	M. P.	COM	TW
GFPL	Peaking	<25MHz	0	<0.1	<0.1	<0.1	dB
GFPH	Peaking	>25MHz	0	<0.2	<0.2	<0.2	dB
GFR	Rolloff	<50MHz	0.2	<1.0	<1.0	<1.3	dB
LPD	Linear Phase Deviation	DC to 50MHz	0.2	<1.0	<1.0	<1.5	deg
Time Dom	nain Response	W.100	OW.		WW.	Inn - 1 C	OM.
TRS 🔨	Rise and Fall Time	2V Step	2.5	<3.5	<3.5	<5.0	ns
TRL		5V Step	5	<7.0	<7.0	<8.0	ns
TS	Settling Time to ±0.1%	2V Step	0 10	<15	<15	<15	ns
OS	Overshoot	2V Step	0	<10	<10	<10	%
SR	Slew Rate	1/1/1/100	1200	>800	>800	>700	V/µs
Distortion	And Noise Response	MMM	V.COB	TW	W	MAN	U.Y.C.
HD2	2nd Harmonic Distortion	2V <sub>PP</sub> , 20MHz	-45	<-35	<-35	<-35	dBc
HD3	3rd Harmonic Distortion	2V <sub>PP</sub> , 20MHz	-60	<-50	<-50	<-45	dBc
	Equivalent Input Noise	M MM	1007.00	WELL	-	MA	1007
SNF	Noise Floor	>1MHz	-158	<-155	<-155	<-154	dBm (1Hz)
INV	Integrated Noise	1MHz to 150MHz	35	<50	<50	<55	μV
Static, DC	Performance	WW WW	1007	CONTRACT		MW	-110
VIO	Input Offset Voltage (Note 3)	M. TI	3	±10.0	±6.0	±11.0	mV
DVIO	Average Temperature Coefficient	W.J.	20	±50		±50	μV/°C
IBN	Input Bias Current (Note 3)	Non-Inverting	10	±36	±20	±20	μΑ
DIBN	Average Temperature Coefficient	Own	100	±200	<b>₩</b>	±100	nA/°C
IBI	Input Bias Current (Note 3)	Inverting	10	46	30	40	μΑ
DIBI	Average Temperature Coefficient	COMITY	100	±200	ONF F.	±100	nA/°C
PSRR	Power Supply Rejection Ratio	Y.CO. TW	55	50	50	50	dB
CMRR	Common Mode Rejection Ratio	V.CON.	55	50	50	50	dB
ICC	Supply Current (Note 3)	No Load	15	21	21	21	mA
Miscellan	eous Performance	OOX. COWILL	- 11	W.1003	MOD	. 1	-
RIN	Non-Inverting Input	Resistance	200	>50	>100	>100	kΩ
CIN	TWW	Capacitance	0.5	<2.5	<2.5	<2.5	pF

<b>Electrical Characteristics</b> (Continued) $(A_V = +20, V_{CC} = \pm 5V, R_L = 100\Omega, R_f = 1.5k\Omega; unless specified).$								
Symbol	Parameter	Conditions	Тур	Max/Min Ratings (Note 2)			Units	
RO	Output Impedance	at DC	0.2	<0.3	<0.3	<0.3	Ω	
VO	Output Voltage Range	No Load	3.5	>3.0	>3.2	>3.2	V	
CMIR	Common Mode Input Range	For Rated Performance	2.8	>2.0	>2.5	>2.5	V	
Ю	Output Current	WW.to	60	>35	>50	>50	mA	

Note 1: "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. They are not meant to imply that the devices should be operated at these limits. The table of "Electrical Characteristics" specifies conditions of device operation.

Note 2: Max/min ratings are based on product characterization and simulation. Individual parameters are tested as noted. Outgoing quality levels are determined from tested parameters.

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Note 3: AJ-level: spec. is 100% tested at +25°C. WWW.100Y.COM.TW

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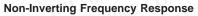
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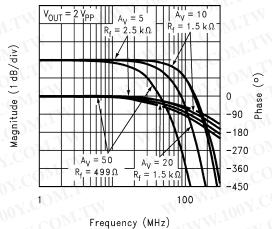
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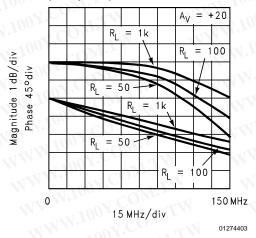
# $\textbf{Typical Performance Characteristics} \quad (T_{A} = 25^{\circ}, \ A_{V} = +20, \ V_{CC} = \pm 5V, \ R_{L} = 100\Omega : \ \text{Unless Special Performance Characteristics}$



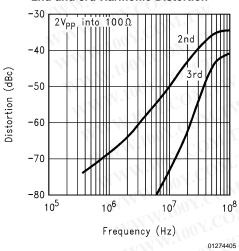


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# Frequency Response for Various R<sub>L</sub>s



# 2nd and 3rd Harmonic Distortion

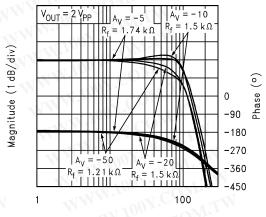


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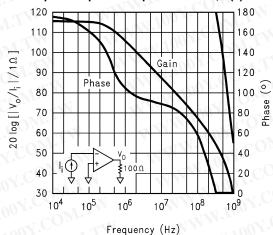
# **Inverting Frequency Response**



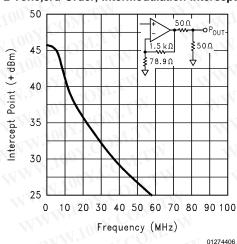
Frequency (MHz)

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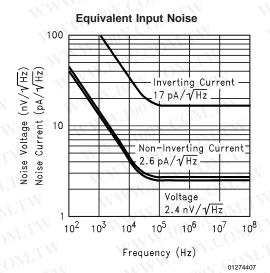
# Open-Loop Transimpedance Gain, Z(s)



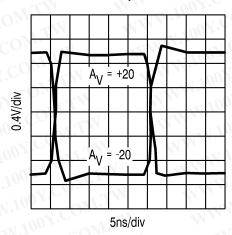
# 2-Tone,3rd Order, Intermodulation Intercept



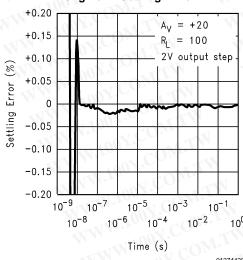
# **Typical Performance Characteristics** $(T_A = 25^{\circ}, A_V = +20, V_{CC} = \pm 5V, R_L = 100\Omega$ : Unless Specified). (Continued)



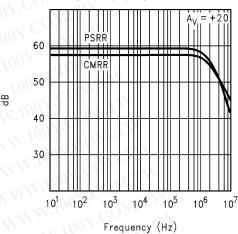
## **Pulse Response**



# Long-Term Settling Time

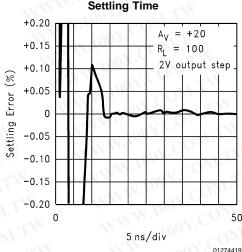


### **CMRR and PSRR**

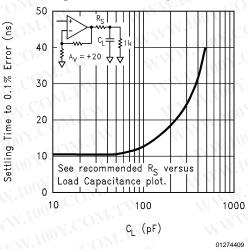


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# **Settling Time**



# Settling Time vs. Load Capacitance



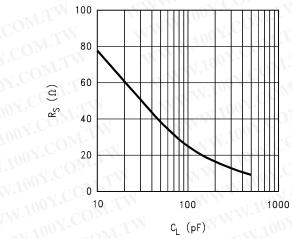
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# **Typical Performance Characteristics** $(T_A = 25^{\circ}, A_V = +20, V_{CC} = \pm 5V, R_L = 100\Omega$ : Unless

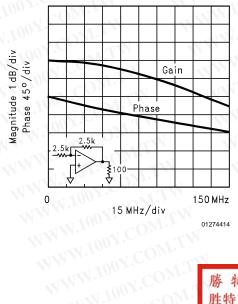
Specified). (Continued)

### Recommended R<sub>s</sub> vs. Load Capacitance



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# Frequency Response, $A_V = -1$ , $R_f = 2.25k\Omega$



Low Gain & Transimpedance Applications

The CLC401 may be used at gains down to unity ( $A_V = \pm 1$ ) by choosing  $R_f$  according to Equation (4) in this datasheet. The curves to the right show performance at inverting unity gain with  $R_f = 2500\Omega$ , a configuration appropriate for D/A converter buffering and other transimpedance applications.

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# **Application Division**

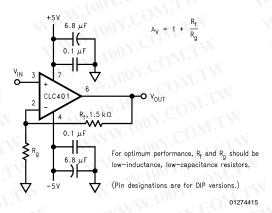


FIGURE 1. Recommended Non-Inverting Gain Circuit

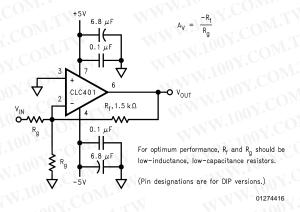


FIGURE 2. Recommended Inverting Gain Circuit

### **Understanding the Loop Gain**

Referring to the equivalent circuit of *Figure 3*, any current flowing in the inverting input is amplified to a voltage at the output through the transimpedance gain shown on the plots on page 3. This Z(s) is analogous to the open-loop gain of a voltage feedback amplifier.

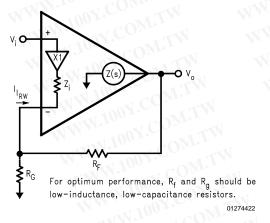


FIGURE 3. Current feedback topology

Developing the non-inverting frequency response for the topology of *Figure 3* yields:

**Equation 1** 

$$\frac{V_{O}}{V_{i}} = \frac{1 + R_{f} / R_{g}}{1 - 1 / LG}$$

where LG is the loop gain defined by,

### **Equation 2**

$$LG = \frac{Z(s)}{R_f} \times \frac{1}{1 + Z_i / (R_f IIR_g)}$$

Equation 1 has a form identical to that for a voltage feedback amplifier with the differences occurring in the LG expression. For an idealized treatment, set  $Z_i=0$  which results in a very simple LG =  $Z(s)/R_f$  (Derivation of the transfer function for the case where  $Z_i=0$  is given in Application Note AN300-1). Using the Z(s) (open-loop transimpedance gain) plot shown on the previous page and dividing by the recommended  $R_f=1.5k\Omega$ , yields a large loop gain at DC. As a result, Equation 1 shows that the closed-loop gain at DC is very close to  $(1+R_f/R_g)$ .

At higher frequencies, the roll-off of Z(s) determines the closed-loop frequency response which, ideally, is dependent only on  $R_{\rm f}$ . The specifications reported on the previous pages are therefore valid only for the specified  $R=1.5k\Omega$ . Increasing R from  $1.5k\Omega$  will decrease the loop gain and band width, while decreasing it will increase the loop gain possibly leading to inadequate phase margin and closed-loop peaking. Conversely, fixing  $R_{\rm f}$  will hold the frequency response constant while the closed-loop gain can be adjusted using  $R_{\rm g}$ .

The CLC401 departs from this idealized analysis to the extent that the inverting input impedance is finite. With the low quiescent power of the CLC401,  $Z \cong 50\Omega$  leading to drop in loop gain and bandwidth at high gain settlings, as given by Equation 2. The second term is Equation 2 accounts for the division in feedback current that occurs between  $Z_i$  and  $R_i\|R_g$  at the inverting node of the CLC400. This decrease in bandwidth can be circumvented as described in "Increasing Bandwidth at High Gains."

### DC Accuracy and Noise

Since the two inputs for the CLC401 are quite dissimilar, the noise and offset error performance differs somewhat from that of a standard differential input amplifier. Specifically, the inverting input current noise is much larger than the non-inverting current noise. Also the two input bias currents are physically unrelated rendering bias current cancellation through matching of the inverting and non-inverting pin resistors ineffective.

In Equation 3, the output offset is the algebraic sum of the equivalent input voltage and current sources that influence DC operation. Output noise is determined similarly except that a root-sum-of-squares replaces the algebraic sum.  $\rm R_{\rm s}$  is the non-inverting pin resistance.

### **Equation 3**

Output Offset 
$$V_O = \pm IBN \times R_S (1 + R_f/R_g) \pm VIO (1 + R_f/R_g) \pm IBI \times R_f$$

An important observation is that for fixed  $R_{\rm f}$ , offsets as referred to the input improve as the gain is increased (divide all terms by 1+R/ $R_{\rm g}$ ). A similar result is obtained for noise where noise figure improves as gain increases.

## Selecting Between the CLC400 or CLC401

The CLC400 is intended for gains of  $\pm 1$  to  $\pm 8$  while the CLC401 is designed for gains of  $\pm 7$  to  $\pm 50$ . Optimum performance is achieved with a feedback resistor of  $250\Omega$  with the CLC400 and  $1.5\Omega$  with the CLC401- this distinction may be important in transimpedance applications such as D/A buffering. Although the CLC400 can be used at higher gains, the CLC401 will provide a wider bandwidth because loop gain losses due to finite  $Z_i$  are lower with the larger CLC401 feedback resistor as explained above. On the other hand, the lower recommended feedback resistance of the CLC400 minimizes the output errors due to inverting input noise and bias currents.

### Increasing Bandwidth At High Gains

Bandwidth may be increased at high closed-loop gains by adjusting  $R_{\rm f}$  and  $R_{\rm g}$ to make up for the losses in loop gain that occur at these high gain settlings due to current division at the inverting input. An approximate relationship my be obtained by holding the LG expression constant as the gain is changed from the design point used in the specifications (that is,  $R_{\rm f}=1.5 k\Omega$  and  $R_{\rm g}=79\Omega).$  For the CLC401 this gives,

# **Equation 4**

$$R_f = 2500 - 50A_V \text{ and } R_g = \frac{2500 - 50A_V}{A_V - 1}$$

where  $A_V$  is the desired non-inverting gain. Note that with  $A_V=+20$  we get the specified  $R_f=1.5k\Omega,$  while at higher gains, a lower value gives stable performance with improved bandwidth.

### Capacitive Feedback

Capacitive feedback should not be used with the CLC401 because of the potential for loop instability. See Application Note OA-7 for active filter realizations with the CLC401.

### **Printed Circuit Layout**

As with any high frequency device, a good PCB layout will enhance performance. Ground plane construction and good power supply bypassing close to the package are critical to achieving full performance. In the non-inverting configuration, the amplifier is sensitive to stray capacitance to ground at the inverting input. Hence, the inverting node connections should be small with minimal coupling to the ground plane. Shunt capacitance across the feedback resistor should not be used to compensate for this effect.

Parasitic or load capacitance directly on the output will introduce additional phase shift in the loop degrading the loop phase margin and leading to frequency response peaking. A small series resistor before the capacitance effectively decouples this effect. The graphs on the preceding page illustrate the required resistor value and resulting performance vs. capacitance.

Precision buffed resistors (PRP8351 series from Precision Resistive Products) with low parasitic reactances were used to develop the data sheet specifications. Precision carbon composition resistors will also yield excellent results. Standard spirally-trimmed RN55D metal film resistors will work with the slight decrease in bandwidth due to their reactive nature at high frequencies.

Evaluation PC boards (part no. CLC730013 for through-hole and CLC730027 for SOIC) for the CLC401 are available.

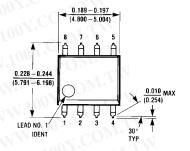
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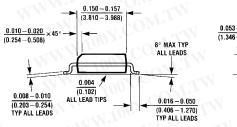
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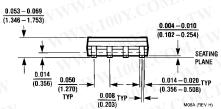
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# Physical Dimensions inches (millimeters)

unless otherwise noted

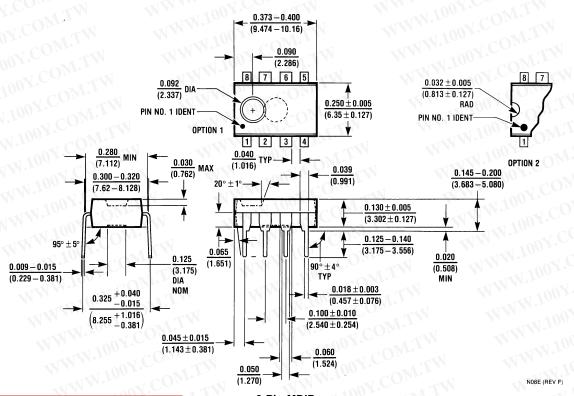






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8-Pin SOIC
NS Package Number M08A



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8-Pin MDIP NS Package Number N08E

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# **Notes**

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- A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.



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