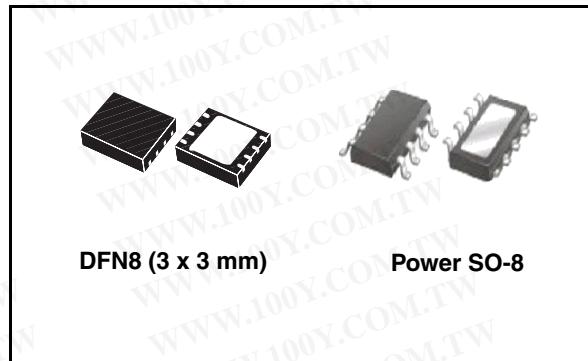


1.5 A max constant current LED driver

Features

- Up to 40 V input voltage
- Less than 0.5 V voltage overhead
- Up to 1.5 A output current
- PWM dimming pin
- Shutdown pin
- LED disconnection diagnostic
- Slope control with external cap



Applications

- LED constant current supplying for varying input voltages
- Low voltage lighting
- Small appliances LED lighting
- Car LED lights

The current is set with external resistor up to 1.5 A with a $\pm 10\%$ precision; a dedicated pin allows implementing PWM dimming. An external capacitor allows setting the slope for the current rise from tens of microseconds to tens of milliseconds allowing reduction of EMI.

An open-drain pin output provides information on load disconnection condition.

Description

The STCS1A is a BiCMOS constant current source designed to provide a precise constant current starting from a varying input voltage source. The main target is to replace discrete components solution for driving LEDs in low voltage applications such as 5 V, 12 V or 24 V giving benefits in terms of precision, integration and reliability.

Table 1. Device summary

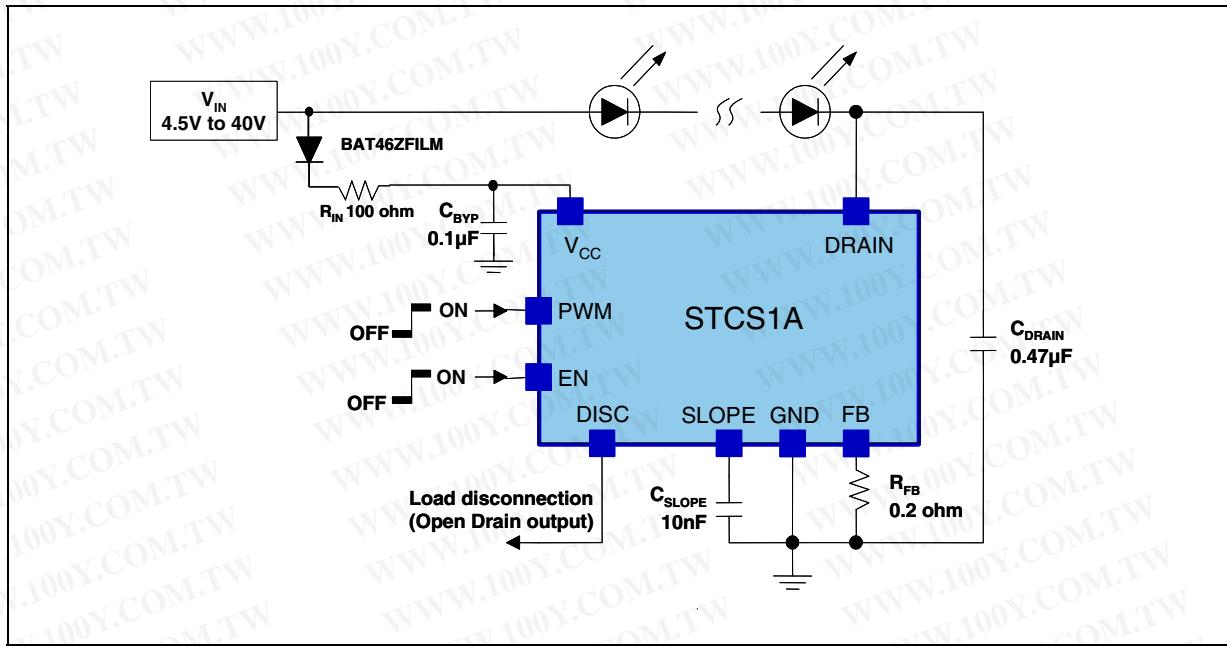
| Order codes | Packages | Packaging |
|-------------|-----------------|---------------------|
| STCS1APUR | DFN8 (3 x 3 mm) | 3000 parts per reel |
| STCS1APHR | Power SO-8 | 2500 parts per reel |

Contents

| | | |
|-----------|--|-----------|
| 1 | Application diagram | 3 |
| 2 | Pin configuration | 4 |
| 3 | Maximum ratings | 5 |
| 4 | Electrical characteristics | 6 |
| 5 | Timing | 7 |
| 6 | Typical performance characteristics | 8 |
| 7 | Detail description | 10 |
| 7.1 | Current setting | 10 |
| 7.2 | Enable | 10 |
| 7.3 | PWM Dimming | 10 |
| 7.4 | Diagnostic | 11 |
| 8 | Application information | 12 |
| 8.1 | Reverse polarity protection | 12 |
| 8.2 | Thermal considerations | 12 |
| 9 | Package mechanical data | 14 |
| 10 | Revision history | 18 |

1 Application diagram

Figure 1. Typical application diagram for 0.5 A LED current



2 Pin configuration

Figure 2. Pin connections (top view)

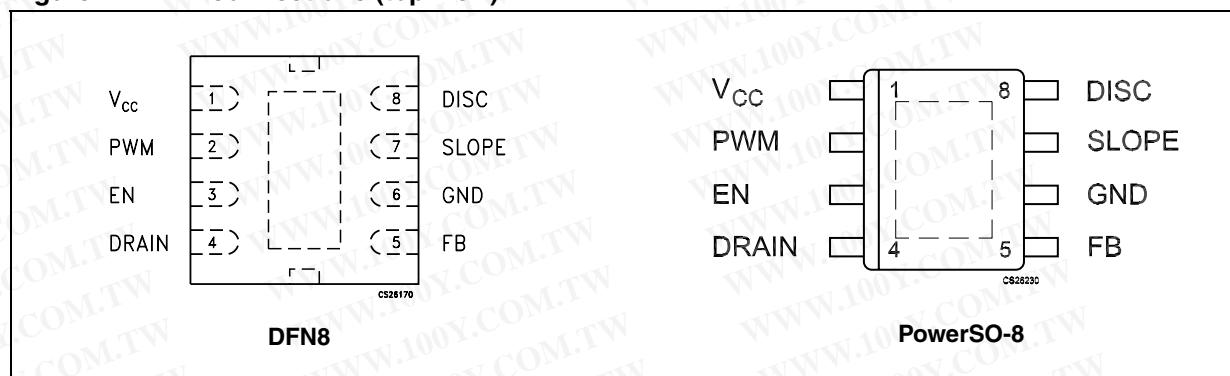


Table 2. Pin description

| Pin n° | Symbol | Note |
|--------|-----------------|--|
| 1 | V _{CC} | Supply voltage |
| 2 | PWM | PWM dimming input |
| 3 | EN | Shutdown pin |
| 4 | DRAIN | Internal N-MOSFET drain |
| 5 | FB | Feedback input. The control loop regulates the current in such a way that the average voltage at the FB input is 100 mV (nominal). The cathode of the LED and a resistor to ground to set the LED current should be connected at this point. |
| 6 | GND | Ground |
| 7 | SLOPE | Capacitor for slope control |
| 8 | DISC | Load disconnection flag (open drain) |
| | Exp-pad | Internally connected to ground. |

3 Maximum ratings

Table 3. Absolute maximum ratings

| Symbol | Parameter | Value | Unit |
|---------------|-----------------------------|--------------------------|------|
| V_{CC} | DC supply voltage | -0.3 to +45 | V |
| DRAIN | Drain pin | -0.3 to +45 | |
| PWM, EN, DISC | Logic pins | -0.3 to + V_{CC} + 0.3 | V |
| SLOPE, FB | Configuration pins | -0.3 to + 3.3 | V |
| ESD | Human body model (all pins) | ± 2 | kV |
| $T_J^{(1)}$ | Junction temperature | -40 to 150 | °C |
| T_{STG} | Storage temperature range | -55 to 150 | °C |

1. T_J is calculated from the ambient temperature T_A and the power dissipation P_D according the following formula:
 $T_J = T_A + (P_D \times R_{thJA})$. See [Figure 16](#) and [Figure 17](#) for details of max power dissipation for ambient temperatures higher than 25°C.

Note: *Absolute maximum ratings are those values beyond which damage to the device may occur. Functional operation under these conditions is not implied.*

Table 4. Thermal data

| Symbol | Parameter | DFN8 | Power SO-8 | Unit |
|------------|-------------------------------------|---------------------|-------------------|------|
| R_{thJC} | Thermal resistance junction-case | 10 | 12 | °C/W |
| R_{thJA} | Thermal resistance junction-ambient | 37.6 ⁽¹⁾ | 45 ⁽²⁾ | °C/W |

1. This value is referred to four-layer PCB, JEDEC standard test board.
2. With two sides, two planes PCB following EIA/JEDEC JESD51-7 standard.

4 Electrical characteristics

Table 5. Electrical characteristics ($V_{CC} = 12$ V; $I_O = 100$ mA; $T_J = -40$ °C to 125 °C; $V_{DRAIN} = 1$ V; $C_{DRAIN} = 1$ µF; $C_{BYP} = 100$ nF typical values are at $T_A = 25$ °C, unless otherwise specified)

| Symbol | Parameter | Test conditions | Min. | Typ. | Max. | Unit |
|----------------------------------|---|---|------|------|------|------|
| V_{CC} | Supply voltage range | | 4.5 | | 40 | V |
| | Output current range | | 1 | | 1500 | mA |
| I_O | Output current | $R_{FB} = 0.2$ Ω | | 500 | | mA |
| | Regulation (percentage with respect to $V_{CC}=12$ V) | $V_{CC} = 4.5$ to 40 V, $I_O = 100$ mA; $V_{DRAIN} = 1$ V | -1 | | +1 | % |
| V_{FB} | Feedback voltage | $I_O = 0$ to 1.5 A | 90 | 100 | 110 | mV |
| I_{CC} | Quiescent current (Measured on V_{CC} pin) | On Mode | | 450 | 750 | µA |
| | | Shutdown Mode; $V_{CC} = 5$ to 12 V | | | 1 | |
| | | Shutdown Mode; $V_{CC} = 12$ to 40 V | | | 3 | |
| V_{DROP} | Dropout voltage (V_{DRAIN} to GND) | $I_O = 100$ mA | | 0.12 | 0.16 | V |
| | | $I_O = 1.5$ A | | 0.58 | 0.9 | |
| $LEAK_{DRAIN}$ | Drain leakage current | Shutdown; $V_{DRAIN} = 40$ V | | | 10 | µA |
| T_R/T_F | Rise/Fall time of the current on PWM transition | $C_{SLOPE} = 10$ nF, $T_J = -40$ °C to 105 °C | | 800 | | µs |
| T_D | Delay on PWM signal (see <i>Figure 1</i>) | V_{PWM} rising, $V_{CC} = 12$ V $C_{SLOPE} = \text{floating}$ | | 3 | | µs |
| | | V_{PWM} falling, $V_{CC} = 12$ V $C_{SLOPE} = \text{floating}$ | | 1.2 | | |
| DISC | Low level voltage | $I_{SINK} = 5$ mA | | 0.2 | 0.5 | V |
| | Leakage current | $V_{DISC} = 5$ V | | | 1 | µA |
| | Load disconnection threshold (V_{DRAIN} -GND) | DISC Turn-ON | | 75 | | mV |
| | | DISC Turn-OFF | | 110 | | |
| Thermal Protection | Shutdown temperature | | | 155 | | °C |
| | Hysteresis | | | 25 | | |
| Logic Inputs (PWM and EN) | | | | | | |
| V_L | Input low level | | | | 0.4 | V |
| V_H | Input high level | | 1.2 | | | V |
| | EN, PWM leakage current | $V_{EN} = 5$ V; $V_{PWM} = 5$ V | | | 2 | µA |
| | EN input leakage current | $V_{EN} = 40$ V | | | 60 | |
| | PWM input leakage current | $V_{PWM} = 40$ V | | | 120 | |

Note: All devices 100 % production tested at $T_A = 25$ °C. Limits over the operating temperature range are guaranteed by design.

5 Timing

Figure 3. PWM and output current timing

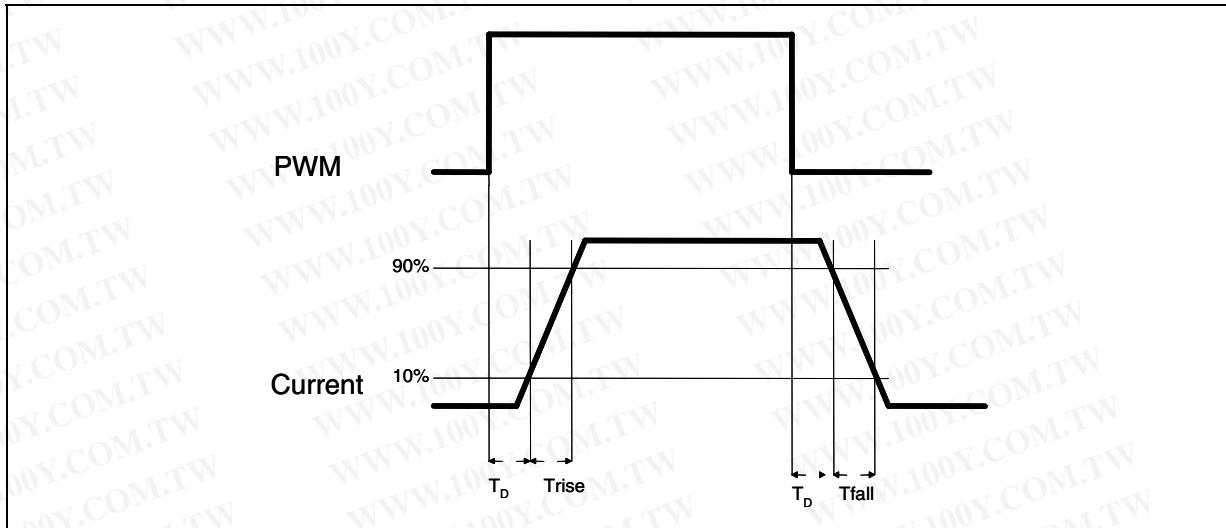
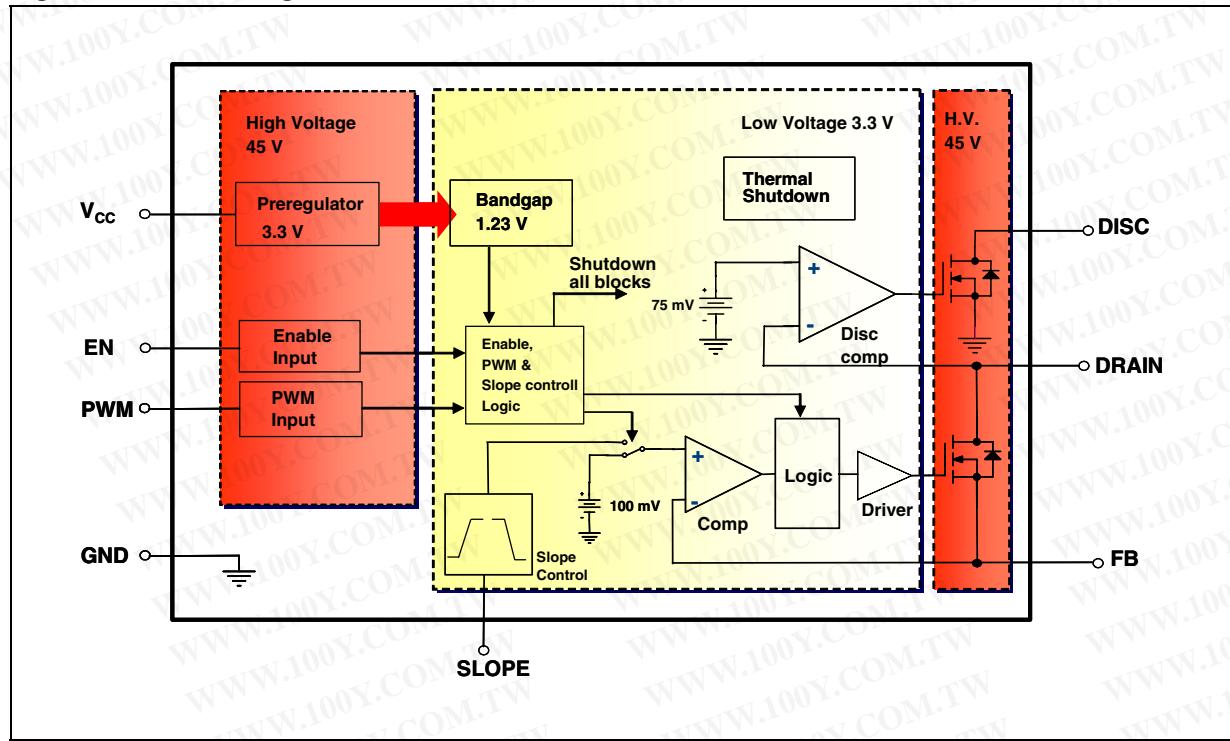


Figure 4. Block diagram



6 Typical performance characteristics

Figure 5. I_{DRAIN} vs V_{CC} , $T_A = 25^\circ C$

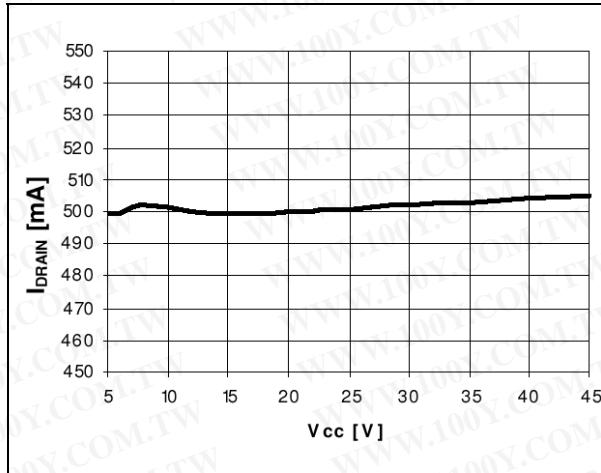


Figure 6. I_{DRAIN} vs R_{SET}

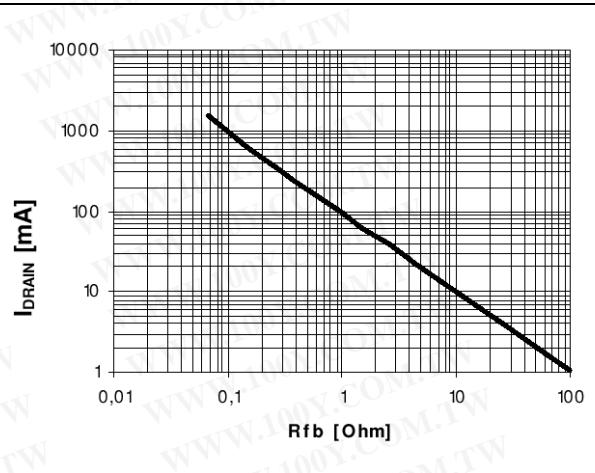


Figure 7. I_{DRAIN} vs Temperature

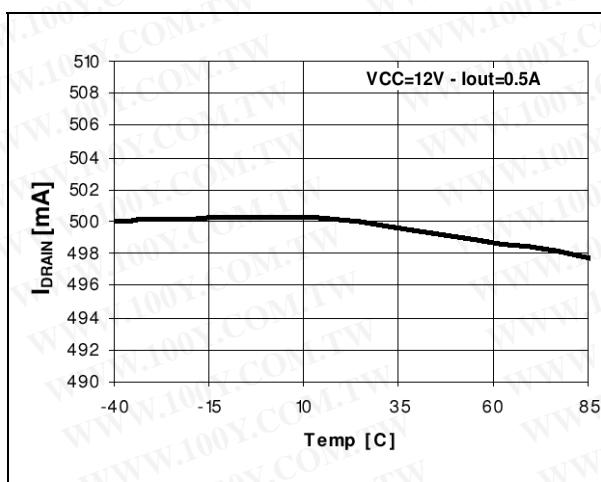


Figure 8. V_{DROP} (including V_{FB}) vs temperature

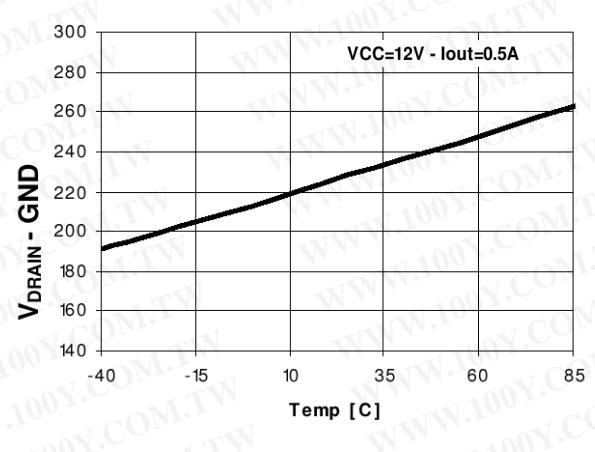


Figure 9. I_{CC} vs Temperature

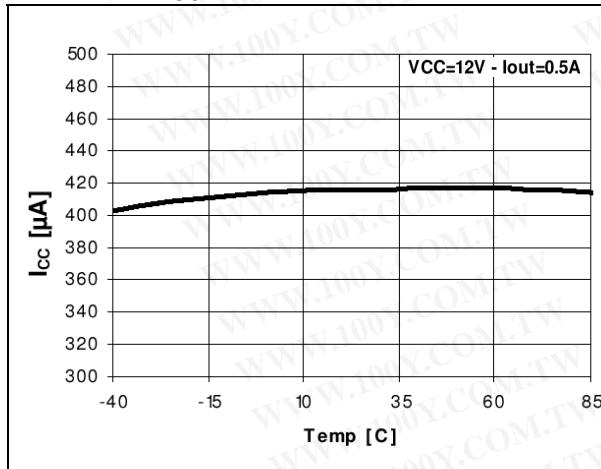


Figure 10. I_{CC} vs V_{CC}

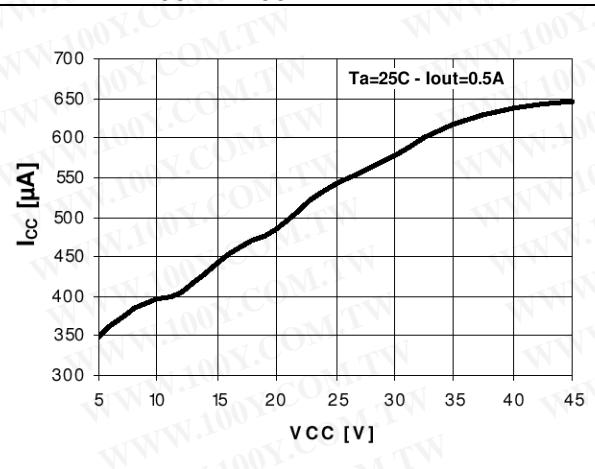
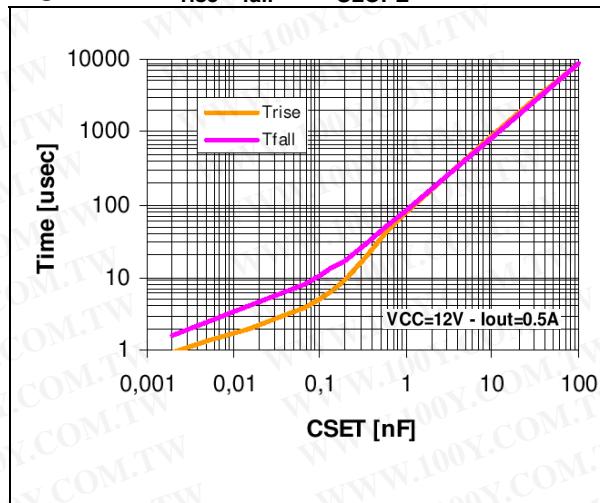
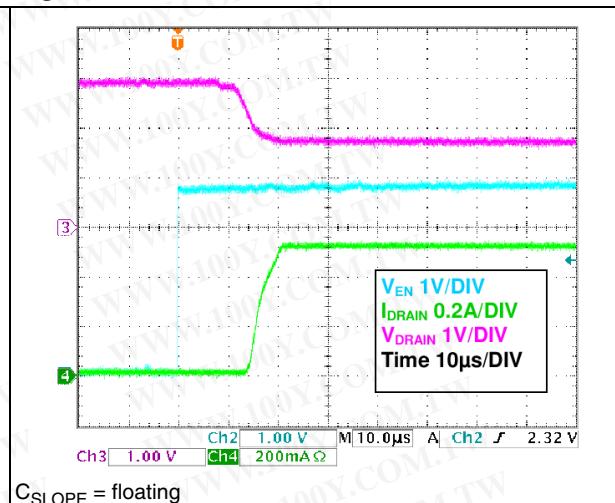
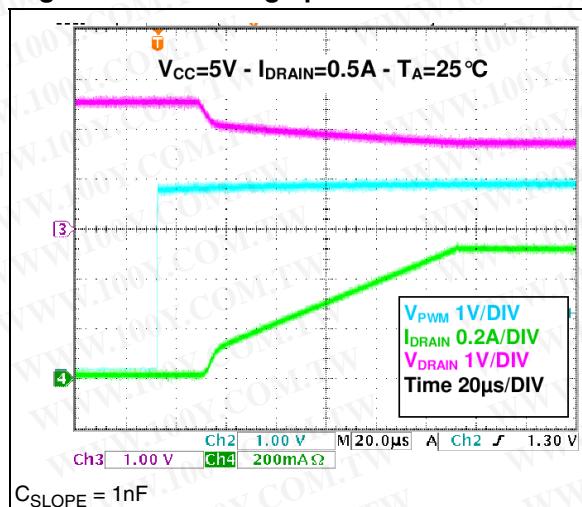
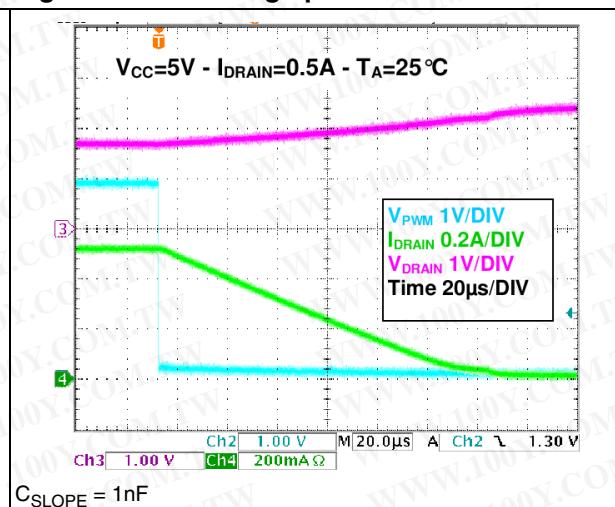


Figure 11. T_{rise}/T_{fall} vs C_{SLOPE} **Figure 12.** Turn-on time**Figure 13.** Dimming operation: Rise $C_{SLOPE} = 1nF$ **Figure 14.** Dimming operation: Fall $C_{SLOPE} = 1nF$

7 Detail description

The STCS1A is a BiCMOS constant current source designed to provide a precise constant current starting from a varying input voltage source. The main target is to replace discrete components solution for driving LEDs in low voltage applications such as 5 V, 12 V or 24 V giving benefits in terms of precision, integration and reliability.

7.1 Current setting

The current is set with an external sensing resistor connected to the FB pin. The feedback voltage is 100 mV, then a low resistor value can be chosen reducing power dissipation. A value between 1 for instance, should one need a 700 mA LEDs current, R_F should be selected according to the following equation:

For instance, should one need a 700 mA LEDs current, R_F should be selected according to the following equation:

$$R_F = V_{FB} / I_{LEDs} = 100 \text{ mV} / 700 \text{ mA} = 142 \text{ m}\Omega$$

7.2 Enable

When the enable pin is low the device completely off thus reducing current consumption to less than 1 μA . When in shutdown mode, the internal main switch is off.

7.3 PWM dimming

The PWM input allows implementing PWM dimming on the LED current; when the PWM input is high the main switch will be on and vice versa. A typical frequency range for the input is from few Hertz to 50 kHz. The maximum dimming frequency is limited by the minimum rise/fall time of the current (obtained with $C_{SLOPE} = 0$) which is around 4 μs each. Above 50 kHz the current waveforms starts assuming a triangular shape.

While the PWM input is switching, the overall circuitry remains on, this is needed in order to implement two important features: short delay time and controlled slope for the current.

Since the PWM pin is controlling just the main switch, the overall circuitry is always on and it is able to control the delay time between the PWM input signal and the output current in the range of few μs , this is important to implement synchronization among several light LED sources.

The rise and fall slope of the current is controlled by the C_{SLOPE} capacitor. The rise and fall time are linear dependent from the C_{SLOPE} capacitor value (see graph in typical characteristics). A controlled rise time has two main benefits: reducing EMI noise and avoid current spike at turn on.

When C_{SLOPE} is left floating, the internal switch is turned on at maximum speed, in this condition an overshoot can be present on the LED current before the system goes into regulation.

7.4 Diagnostic

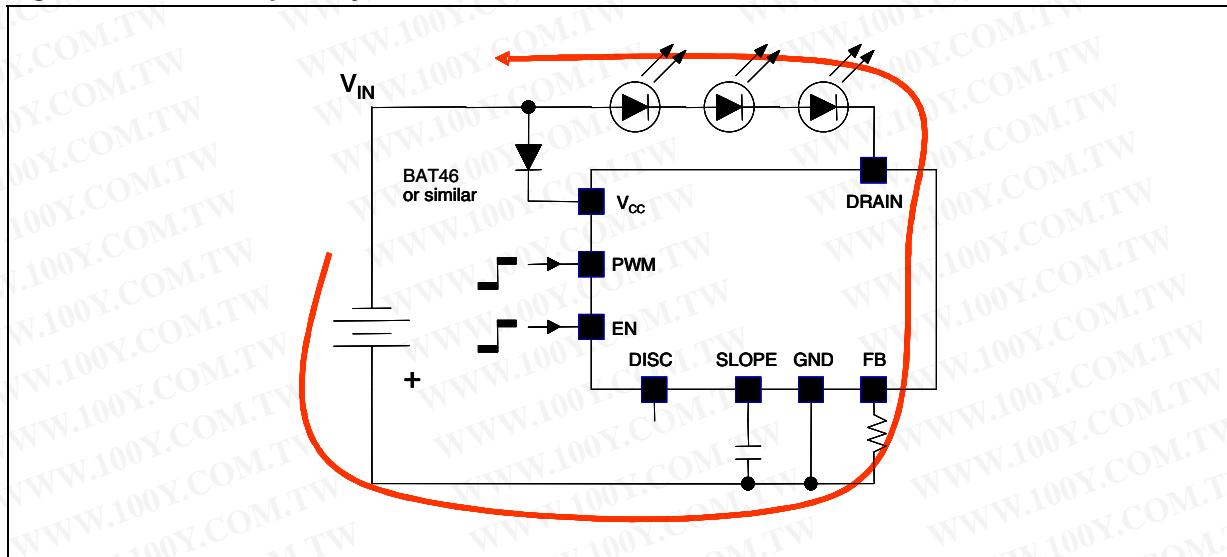
When STCS1A is in on mode (EN is high), the device is able to detect disconnection or fail of the LED string monitoring V_{DRAIN} pin. If V_{DRAIN} is lower than 75 mV the DISC pin is pulled low regardless the PWM pin status. This information can be used by the system to inform that some problem happens in the LEDs.

8 Application information

8.1 Reverse polarity protection

STCS1A must be protected from reverse connection of the supply voltage. Since the current sunk from V_{CC} pin is in the range of 450 μA a small diode connected to V_{CC} is able to protect the chip. Care must be taken for the whole application circuit, especially for the LEDs, in fact, in case a negative voltage is applied between V_{IN} and GND, a negative voltage will be applied to the LED string that must have a total breakdown voltage higher than the negative applied voltage in order to avoid any damage.

Figure 15. Reverse polarity condition



8.2 Thermal considerations

The STCS1A is able to control a LED current up to 1.5 A and able to sustain a voltage on the drain pin up to 40 V. Those operating conditions are however limited by thermal constraints, the thermal resistances shown in the *Thermal data* section are the typical ones, in particular R_{thJA} depends on the copper area and the number of layers of the printed circuit board under the pad. DFN8 and PowerSO-8 have an exposed die attach pad which enhances the thermal conductivity enabling high power application.

The power dissipation in the device can be calculated as follow:

$$P_D = (V_{DRAIN} - V_{FB}) \times I_{LED} + (V_{CC} \times I_{CC})$$

basing on this and on the thermal resistance and ambient temperature, the junction temperature can be calculated as:

$$T_J = R_{thJA} \times P_D + T_A$$

A typical application could be:

- Input voltage: 12 V;
- 3 white LEDs with an typical $V_F=3.6$ V;

- LEDs current: 500 mA;
- Package: DFN8 3x3 mm;
- $T_A = 50^\circ\text{C}$;

In this case $V_{\text{DRAIN}} = 12 - 3 \times 3.6 = 1.2 \text{ V}$

$$P_D = (1.2 - 0.1) \times 0.5 + 12 \times 0.5 \times 10^{-3} = 0.55 + 6 \times 10^{-3} = 556 \text{ mW}$$

The junction temperature will be:

$$T_J = 37.6 \times 0.556 + 50 = 70.9 \text{ }^\circ\text{C}$$

The following pictures show the maximum power dissipation according to the ambient temperature for both packages:

Figure 16. Maximum power dissipation vs T_A for DFN8 3x3 mm

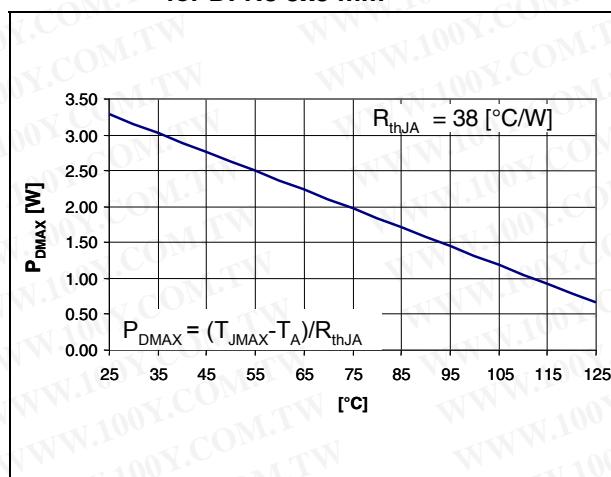
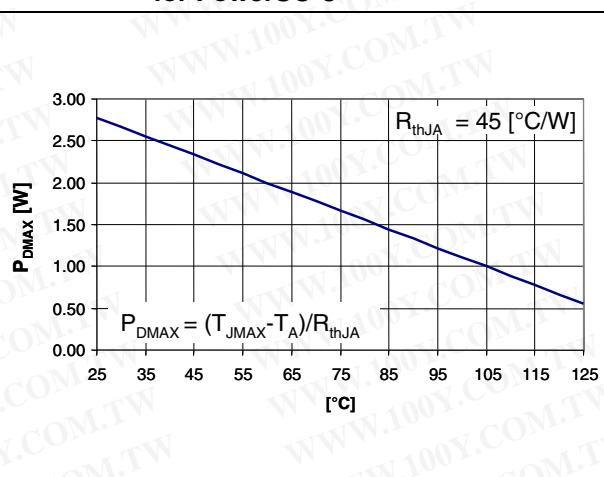


Figure 17. Maximum power dissipation vs T_A for PowerSO-8

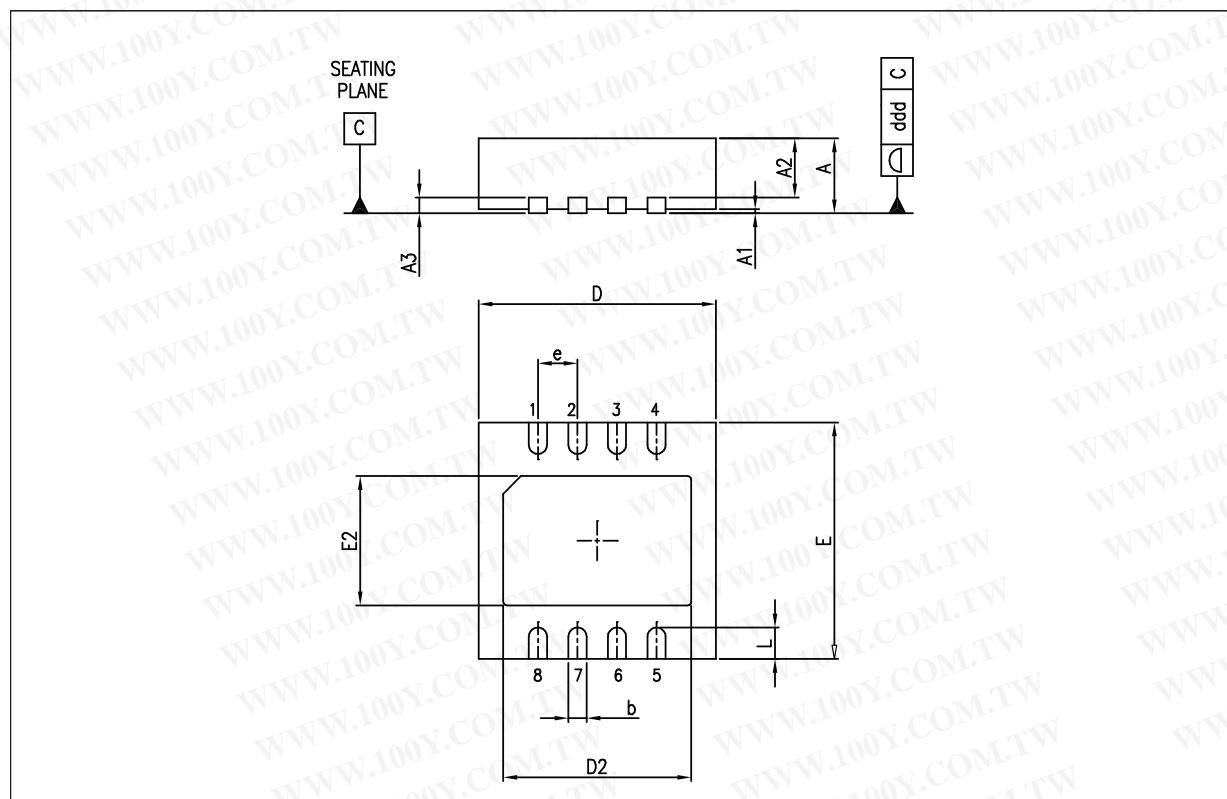


9 Package mechanical data

In order to meet environmental requirements, ST offers these devices in ECOPACK® packages. These packages have a lead-free second level interconnect. The category of second Level Interconnect is marked on the package and on the inner box label, in compliance with JEDEC Standard JESD97. The maximum ratings related to soldering conditions are also marked on the inner box label. ECOPACK is an ST trademark. ECOPACK specifications are available at: www.st.com.

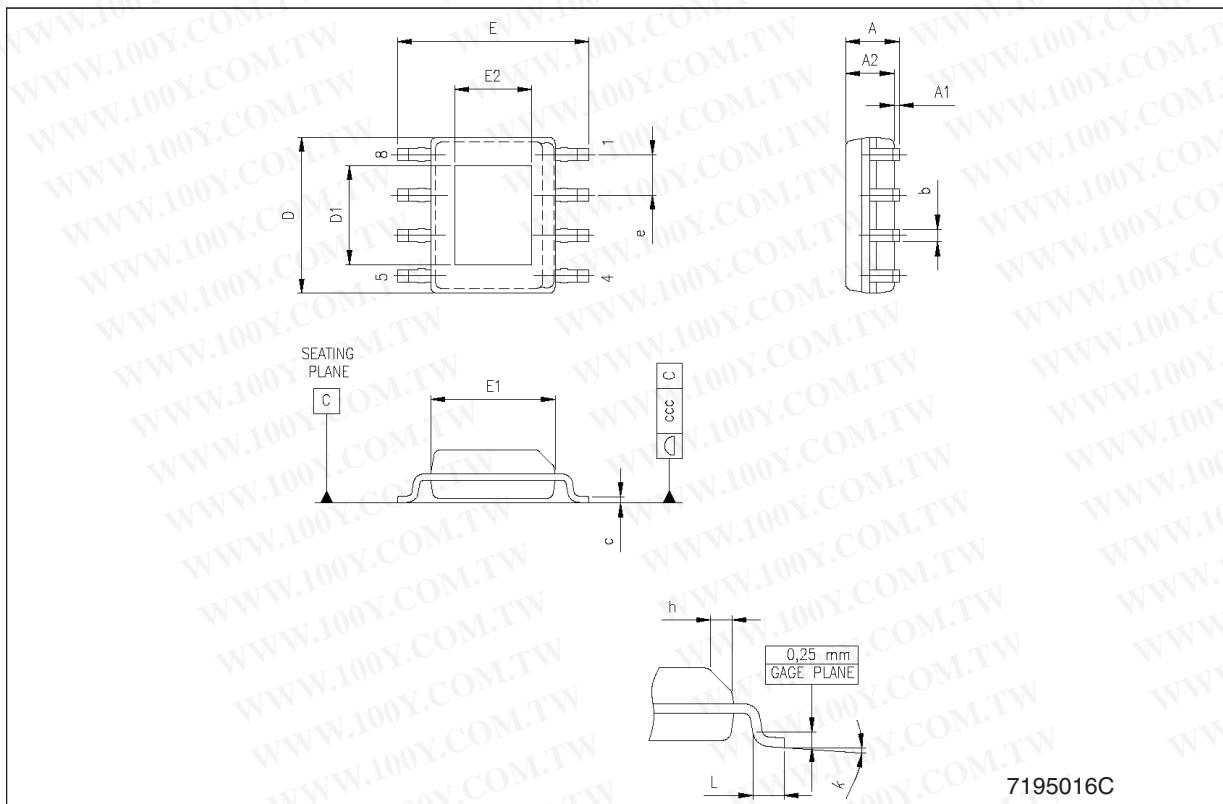
DFN8 (3x3 mm) mechanical data

| Dim. | mm. | | | mils. | | |
|------|------|------|------|-------|-------|------|
| | Min. | Typ. | Max. | Min. | Typ. | Max. |
| A | 0.80 | 0.90 | 1.00 | 31.5 | 35.4 | 39.4 |
| A1 | | 0.02 | 0.05 | | 0.8 | 2.0 |
| A2 | | 0.70 | | | 27.6 | |
| A3 | | 0.20 | | | 7.9 | |
| b | 0.18 | 0.23 | 0.30 | 7.1 | 9.1 | 11.8 |
| D | | 3.00 | | | 118.1 | |
| D2 | 2.23 | 2.38 | 2.48 | 87.8 | 93.7 | 97.7 |
| E | | 3.00 | | | 118.1 | |
| E2 | 1.49 | 1.64 | 1.74 | 58.7 | 64.6 | 68.5 |
| e | | 0.50 | | | 19.7 | |
| L | 0.30 | 0.40 | 0.50 | 11.8 | 15.7 | 19.7 |



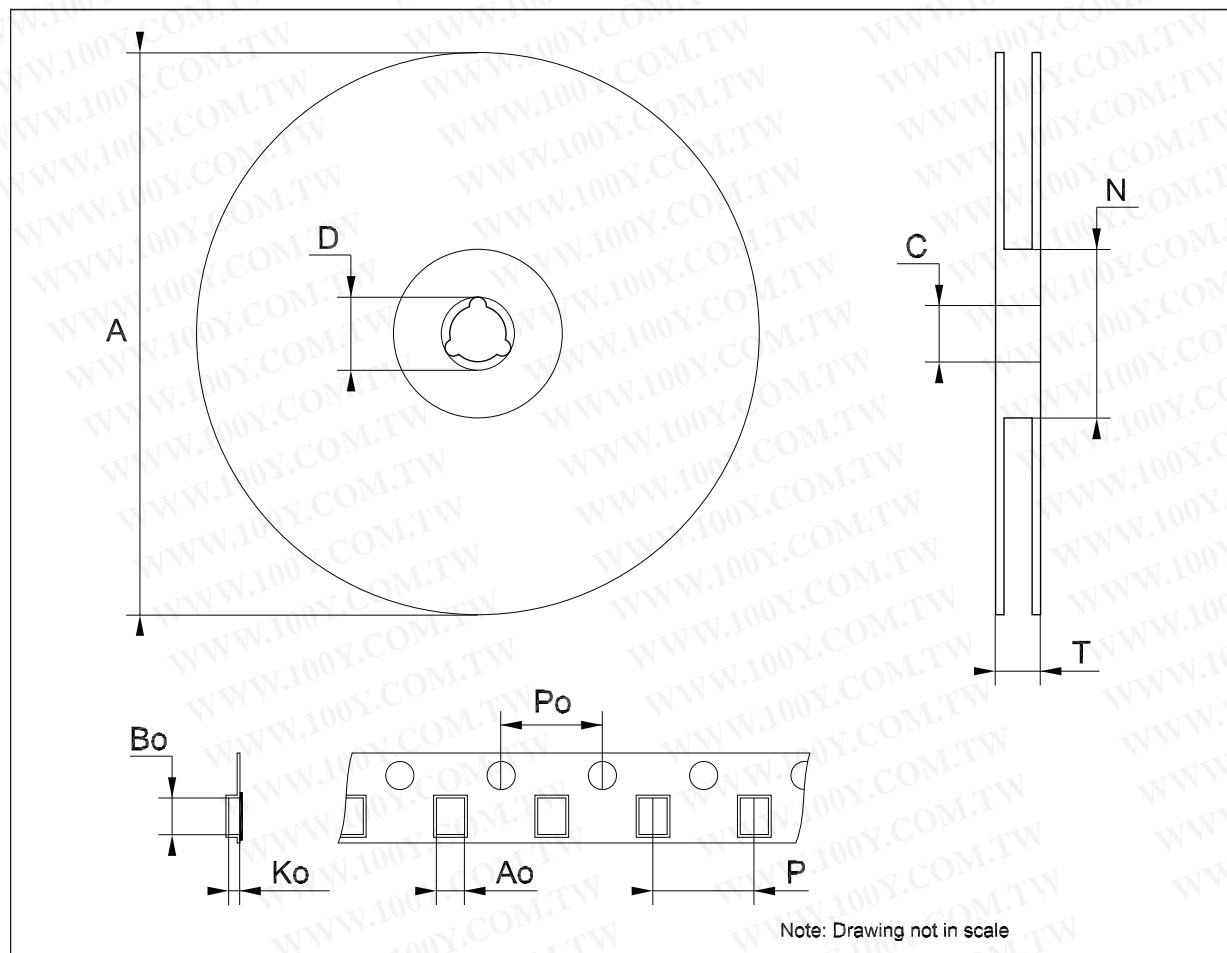
PowerSO-8 mechanical data

| Dim. | mm. | | | inch. | | |
|------|------|------|------|-------|-------|-------|
| | Min. | Typ. | Max. | Min. | Typ. | Max. |
| A | | | 1.70 | | | 0.067 |
| A1 | 0.00 | | 0.15 | 0.00 | | 0.006 |
| A2 | 1.25 | | | 0.049 | | 0.142 |
| b | 0.31 | | 0.51 | 0.012 | | 0.020 |
| c | 0.17 | | 0.25 | 0.007 | | 0.010 |
| D | 4.80 | 4.90 | 5.00 | 0.189 | 0.193 | 0.197 |
| D1 | 2.24 | 3.10 | 3.20 | 0.088 | 0.122 | 0.126 |
| E | 5.80 | 6.00 | 6.20 | 0.228 | 0.236 | 0.244 |
| E1 | 3.80 | 3.90 | 4.00 | 0.150 | 0.154 | 0.157 |
| E2 | 1.55 | 2.41 | 2.51 | 0.061 | 0.095 | 0.099 |
| e | | 1.27 | | | 0.050 | |
| h | 0.25 | | 0.50 | 0.010 | | 0.020 |
| L | 0.40 | | 1.27 | 0.016 | | 0.050 |
| k | 0° | | 8° | 0° | | 8° |
| ccc | | | 0.10 | | | 0.004 |



Tape & reel QFN_{xx}/DFN_{xx} (3x3) mechanical data

| Dim. | mm. | | | inch. | | |
|----------------|------|------|------|-------|-------|-------|
| | Min. | Typ. | Max. | Min. | Typ. | Max. |
| A | | | 180 | | | 7.087 |
| C | 12.8 | | 13.2 | 0.504 | | 0.519 |
| D | 20.2 | | | 0.795 | | |
| N | 60 | | | 2.362 | | |
| T | | | 14.4 | | | 0.567 |
| A _o | | 3.3 | | | 0.130 | |
| B _o | | 3.3 | | | 0.130 | |
| K _o | | 1.1 | | | 0.043 | |
| P _o | | 4 | | | 0.157 | |
| P | | 8 | | | 0.315 | |



10 Revision history

Table 6. Document revision history

| Date | Revision | Changes |
|-------------|----------|-------------------------------------|
| 19-Feb-2008 | 1 | Initial release. |
| 02-Jul-2008 | 2 | Modified: <i>Table 5 on page 6.</i> |

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