



MOTOROLA

MC14194B

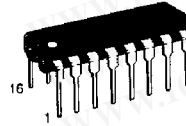
4-BIT BIDIRECTIONAL UNIVERSAL SHIFT REGISTER

The MC14194B is a 4-bit static shift register capable of operating in the parallel load, serial shift left, serial shift right, or hold mode. The asynchronous **Reset** input, when at a low level, overrides all other inputs, resets all stages, and forces all outputs low. When **Reset** is at a logic 1 level, the two mode control inputs, **S0** and **S1**, control the operating mode as shown in the truth table. Both serial and parallel operation are triggered on the positive-going transition of the **Clock** input. The **Parallel Data**, **Data Shift**, and mode control inputs must be stable for the specified setup and hold times before and after the positive-going **Clock** transition.

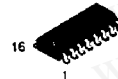
- Synchronous Right/Left Serial Operation
- Synchronous Parallel Load
- Asynchronous Hold (Do Nothing) Mode
- Functional Pin for Pin Equivalent of LS194



L SUFFIX
CERAMIC
CASE 620



P SUFFIX
PLASTIC
CASE 648



D SUFFIX
SOIC
CASE 751B

MAXIMUM RATINGS* (Voltages Referenced to V_{SS})

Symbol	Parameter	Value	Unit
V_{DD}	DC Supply Voltage	-0.5 to +18.0	V
V_{in}, V_{out}	Input or Output Voltage (DC or Transient)	-0.5 to $V_{DD} + 0.5$	V
I_{in}, I_{out}	Input or Output Current (DC or Transient), per Pin	± 10	mA
P_D	Power Dissipation, per Package†	500	mW
T_{stg}	Storage Temperature	-65 to +150	°C
T_L	Lead Temperature (8-Second Soldering)	260	°C

*Maximum Ratings are those values beyond which damage to the device may occur.

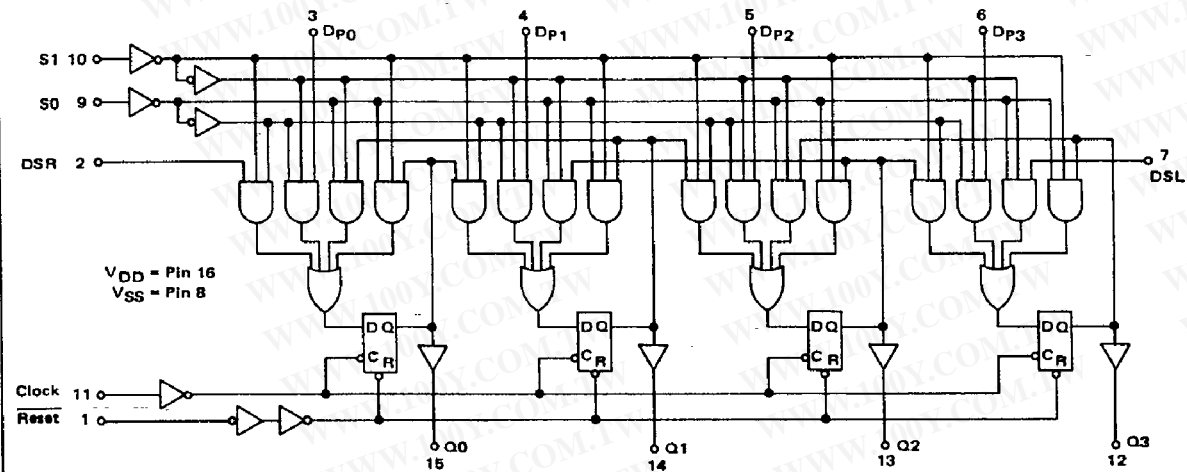
†Temperature Derating: Plastic "P and D/DW" Packages: -7.0 mW/°C From 65°C To 125°C
Ceramic "L" Packages: -12 mW/°C From 100°C To 125°C

ORDERING INFORMATION

MC14XXXBCP Plastic
MC14XXXBCL Ceramic
MC14XXXBD SOIC

$T_A = -55^\circ$ to 125°C for all packages.

LOGIC DIAGRAM



勝特力材料 886-3-5753170
勝特力电子(上海) 86-21-34970699
勝特力电子(深圳) 86-755-83298787
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MC14194B

ELECTRICAL CHARACTERISTICS (Voltages Referenced to V_{SS})

Characteristic	Symbol	V _{DD} V _{dC}	-55°C		25°C			125°C		Unit
			Min	Max	Min	Typ #	Max	Min	Max	
Output Voltage V _{in} = V _{DD} or 0	V _{OL}	5.0	—	0.05	—	0	0.05	—	0.05	V _{dC}
		10	—	0.05	—	0	0.05	—	0.05	
		15	—	0.05	—	0	0.05	—	0.05	
V _{in} = 0 or V _{DD}	V _{OH}	5.0	4.95	—	4.95	5.0	—	4.95	—	V _{dC}
		10	9.95	—	9.95	10	—	9.95	—	
		15	14.95	—	14.95	15	—	14.95	—	
Input Voltage (V _O = 4.5 or 0.5 V _{dC}) (V _O = 9.0 or 1.0 V _{dC}) (V _O = 13.5 or 1.5 V _{dC})	"0" Level V _{IL}	5.0	—	1.5	—	2.25	1.5	—	1.5	V _{dC}
		10	—	3.0	—	4.50	3.0	—	3.0	
		15	—	4.0	—	6.75	4.0	—	4.0	
	"1" Level V _{IH}	5.0	3.5	—	3.5	2.75	—	3.5	—	V _{dC}
		10	7.0	—	7.0	5.50	—	7.0	—	
		15	11	—	11	8.25	—	11	—	
Output Drive Current (V _{OH} = 2.5 V _{dC}) (V _{OH} = 4.6 V _{dC}) (V _{OH} = 9.5 V _{dC}) (V _{OH} = 13.5 V _{dC})	Source I _{OH}	5.0	-3.0	—	-2.4	-4.2	—	-1.7	—	mA _{dC}
		5.0	-0.64	—	-0.51	-0.88	—	-0.36	—	
		10	-1.6	—	-1.3	-2.25	—	-0.9	—	
	Sink I _{OL}	5.0	0.64	—	0.51	0.88	—	0.36	—	mA _{dC}
		10	1.6	—	1.3	2.25	—	0.9	—	
		15	4.2	—	3.4	8.8	—	2.4	—	
Input Current	I _{in}	15	—	±0.1	—	±0.00001	±0.1	—	±1.0	μA _{dC}
Input Capacitance (V _{in} = 0)	C _{in}	—	—	—	—	5.0	7.5	—	—	pF
Quiescent Current (Per Package)	I _{DD}	5.0	—	5.0	—	0.005	5.0	—	150	μA _{dC}
		10	—	10	—	0.010	10	—	300	
		15	—	20	—	0.015	20	—	600	
Total Supply Current**† (Dynamic plus Quiescent, Per Package) (C _L = 50 pF on all outputs, all buffers switching)	I _T	5.0	I _T = (0.95 μA/kHz) f + I _{DD}							μA _{dC}
		10	I _T = (1.90 μA/kHz) f + I _{DD}							
		15	I _T = (2.90 μA/kHz) f + I _{DD}							

#Data labelled "Typ" is not to be used for design purposes but is intended as an indication of the IC's potential performance.

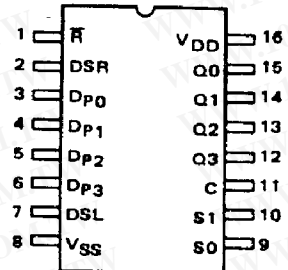
**The formulas given are for the typical characteristics only at 25°C.

†To calculate total supply current at loads other than 50 pF:

$$I_T(C_L) = I_T(50 \text{ pF}) + (C_L - 50) Vfk$$

where: I_T is in μA (per package), C_L in pF, V = (V_{DD} - V_{SS}) in volts, f in kHz is input frequency, and k = 0.002.

PIN ASSIGNMENT



This device contains protection circuitry to guard against damage due to high static voltages or electric fields. However, precautions must be taken to avoid applications of any voltage higher than maximum rated voltages to this high-impedance circuit. For proper operation, V_{in} and V_{out} should be constrained to the range V_{SS} ≤ (V_{in} or V_{out}) ≤ V_{DD}.

Unused inputs must always be tied to an appropriate logic voltage level (e.g., either V_{SS} or V_{DD}). Unused outputs must be left open.

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TRUTH TABLE

OPERATING MODE	INPUTS (Reset = 1)					OUTPUTS (@ $t_n + 1$)			
	S1	S0	DSR	DSL	Dp0-3	Q0	Q1	Q2	Q3
Hold	0	0	X	X	X	Q0	Q1	Q2	Q3
Shift Left	1	0	X	0	X	Q1	Q2	Q3	0
	1	0	X	1	X	Q1	Q2	Q3	1
Shift Right	0	1	0	X	X	0	Q0	Q1	Q2
	0	1	1	X	X	1	Q0	Q1	Q2
Parallel	1	1	X	X	0	0	0	0	0
	1	1	X	X	1	1	1	1	1

X = Don't Care

t_{n+1} = State after the next positive-going transition of the clock.

SWITCHING CHARACTERISTICS* ($C_L = 50$ pF, $T_A = 25^\circ\text{C}$)

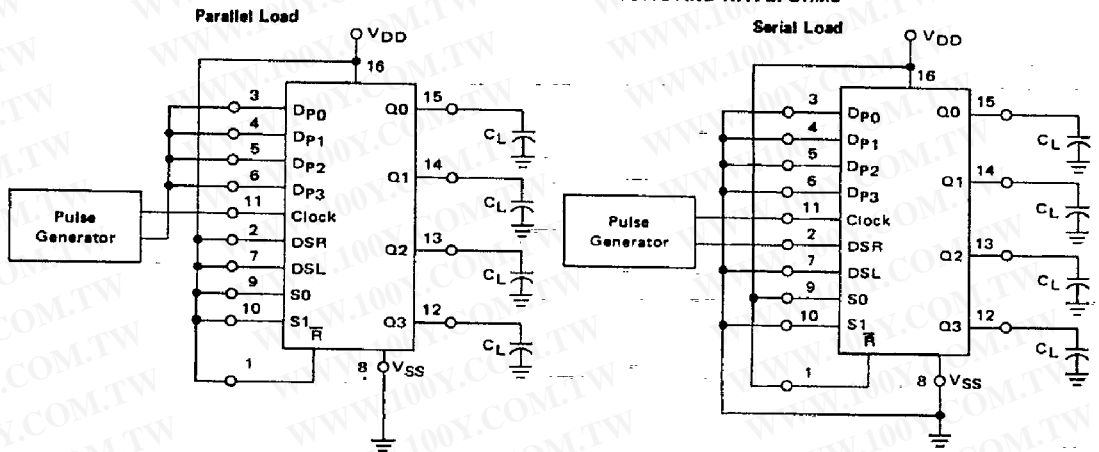
Characteristic	Symbol	VDD Vdc	Min	Typ #	Max	Unit
Output Rise and Fall Time $t_{TLH}, t_{THL} = (1.35 \text{ ns/pF}) C_L + 32 \text{ ns}$ $t_{TLH}, t_{THL} = (0.6 \text{ ns/pF}) C_L + 20 \text{ ns}$ $t_{TLH}, t_{THL} = (0.4 \text{ ns/pF}) C_L + 20 \text{ ns}$	t_{TLH}, t_{THL}	5.0 10 15	— — —	100 50 40	200 100 80	ns
Propagation Delay Time Clock to Q $t_{PLH}, t_{PHL} = (0.9 \text{ ns/pF}) C_L + 230 \text{ ns}$ $t_{PLH}, t_{PHL} = (0.36 \text{ ns/pF}) C_L + 92 \text{ ns}$ $t_{PLH}, t_{PHL} = (0.26 \text{ ns/pF}) C_L + 72 \text{ ns}$ Reset to Q $t_{PHL} = (0.9 \text{ ns/pF}) C_L + 305 \text{ ns}$ $t_{PHL} = (0.36 \text{ ns/pF}) C_L + 122 \text{ ns}$ $t_{PHL} = (0.26 \text{ ns/pF}) C_L + 97 \text{ ns}$	t_{PLH}, t_{PHL} t_{PHL}	5.0 10 15 5.0 10 15	— — — — — —	275 110 85 350 140 110	550 220 170 700 280 220	ns ns
Clock Pulse Width	t_{WH}	5.0 10 15	280 110 85	140 55 40	— — —	ns
Reset Pulse Width	t_{WH}	5.0 10 15	180 70 50	90 35 26	— — —	ns
Clock Pulse Frequency (Shift Right or Left Mode)	f_{cl}	5.0 10 15	— — —	3.6 9.0 12	1.8 4.5 6.0	MHz
Clock Pulse Rise and Fall Time	t_{TLH}, t_{THL}	5.0 10 15	— — —	— — —	15 5 4	μs
Setup Time Data to Clock Mode Control (S) to Clock	t_{su}	5.0 10 15 5.0 10 15	10 20 40 200 75 55	-8.0 0 9.0 100 36 27	— — — — — —	ns ns ns
Hold Time Data to Clock Mode Control (S) to Clock	t_h	5.0 10 15 5.0 10 15	180 50 35 0 0 0	90 25 10 -40 -27 -20	— — — — — —	ns ns ns
Reset Removal Time	t_{rem}	5.0 10 15	300 110 80	150 55 40	— — —	ns

*The formulas given are for the typical characteristics only at 25°C .

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FIGURE 1 – SWITCHING TIME TEST CIRCUITS AND WAVEFORMS



NOTE: Interchange DSR with DSL and S0 with S1 for testing shift left.

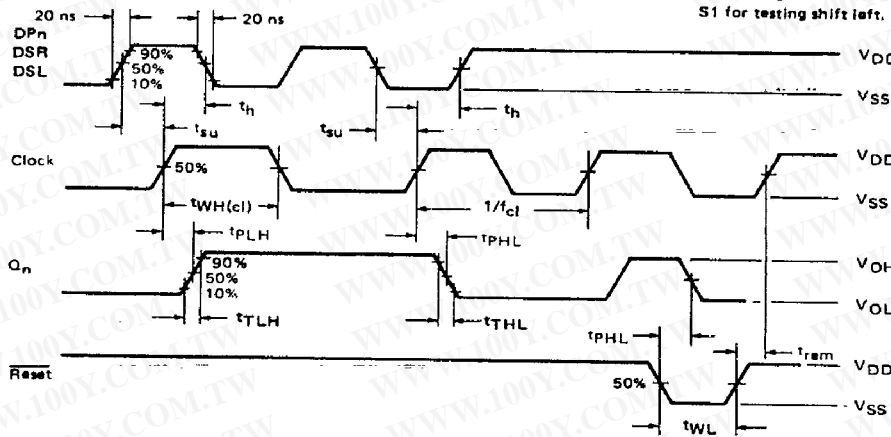
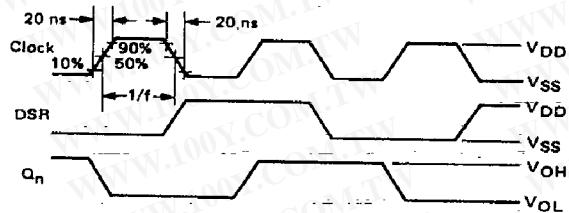
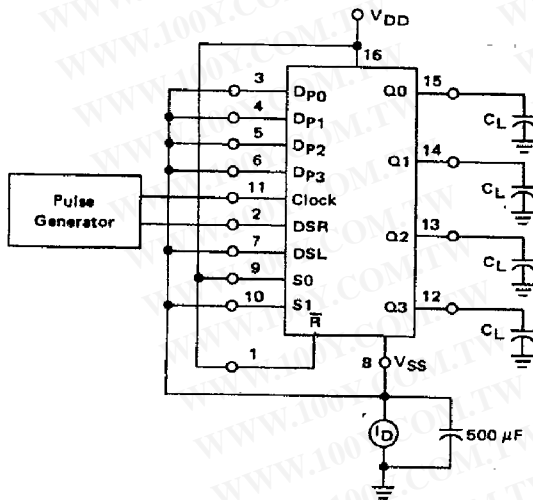


FIGURE 2 – DYNAMIC POWER DISSIPATION TEST CIRCUIT AND WAVEFORMS



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