# 1M x 4 Bit Static Random Access Memory

The MCM6249 is a 4,194,304 bit static random access memory organized as 1,048,576 words of 4 bits, fabricated using high–performance silicon–gate CMOS technology. Static design eliminates the need for external clocks or timing strobes, while CMOS circuitry reduces power consumption and provides for greater reliability.

The MCM6249 is equipped with chip enable (E) and output enable (G) pins, allowing for greater system flexibility and eliminating bus contention problems. Either input, when high, will force the outputs into high impedance.

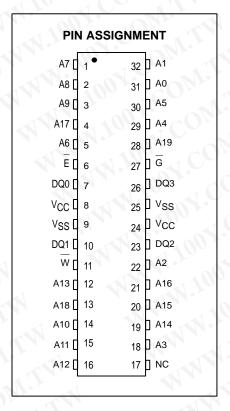
The MCM6249 is available in a 400 mil, 32-lead surface-mount SOJ package.

- Single 5 V ± 10% Power Supply
- Fast Access Time: 20/25/35 ns
- Equal Address and Chip Enable Access Time
- · All Inputs and Outputs are TTL Compatible
- Three–State Outputs
- Power Operation: 190/175/160 mA Maximum, Active AC

## **BLOCK DIAGRAM** A11 A10 A9 MEMORY MATRIX ROW 1024 ROWS x **DECODER** A8 4096 COLUMNS A6 A5 COLUMN I/O INPUT COLUMN DECODER DATA CONTROL DQ3 A17 A16 A15 A14 A19 Å3 DQ0 W DQ3

## MCM6249





Mr.	PIN NAMES
<u>W</u> <u>G</u> E DQ0 – DQ3 NC	
-	Ground

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#### TRUTH TABLE (X = Don't Care)

E	G	W	Mode	I/O Pin	Cycle	Current
Н	X	Х	Not Selected	High-Z		I <sub>SB1</sub> , I <sub>SB2</sub>
L	Н	Н	Output Disabled	High-Z	- 1	ICCA
L	Ļ	Н	Read	D <sub>out</sub>	Read	ICCA
L	X	L	Write	High-Z	Write	ICCA

#### **ABSOLUTE MAXIMUM RATINGS** (See Note)

Rating	Symbol	Value	Unit
Power Supply Voltage Relative to VSS	Vcc	- 0.5 to + 7.0	V
Voltage Relative to VSS for Any Pin Except VCC	V <sub>in</sub> , V <sub>out</sub>	- 0.5 to V <sub>CC</sub> + 0.5	V
Output Current (per I/O)	l <sub>out</sub>	± 20	mA
Power Dissipation	PD	1.0	W
Temperature Under Bias	T <sub>bias</sub>	- 10 to + 85	°C
Operating Temperature	TA	0 to + 70	°C
Storage Temperature — Plastic	T <sub>stg</sub>	- 55 to + 150	°C

NOTE: Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Functional operation should be restricted to RECOMMENDED OPER-ATING CONDITIONS. Exposure to higher than recommended voltages for extended periods of time could affect device reliability.

This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum rated voltages to these high impedance circuits.

This CMOS memory circuit has been designed to meet the dc and ac specifications shown in the tables, after thermal equilibrium has been established. The circuit is in a test socket or mounted on a printed circuit board and transverse air flow of at least 500 linear feet per minute is maintained.

#### DC OPERATING CONDITIONS AND CHARACTERISTICS

( $V_{CC}$  = 5.0 V  $\pm$  10%,  $T_A$  = 0 to + 70°C, Unless Otherwise Noted)

#### **RECOMMENDED OPERATING CONDITIONS**

Parameter	Symbol	Min	Тур	Max	Unit
Supply Voltage (Operating Voltage Range)	Vcc	4.5	5.0	5.5	V
Input High Voltage	VIH	2.2	_	V <sub>CC</sub> + 0.3	V
Input Low Voltage	VIL	- 0.5*	_	0.8	V

<sup>\*</sup> $V_{IL}$  (min) = -0.5 V dc;  $V_{IL}$  (min) = -2.0 V ac (pulse width  $\leq 2.0$  ns).

#### DC CHARACTERISTICS

Parameter	Symbol	Min	Max	Unit
Input Leakage Current (All Inputs, V <sub>in</sub> = 0 to V <sub>CC</sub> )	l <sub>lkg(l)</sub>		± 1.0	μΑ
Output Leakage Current (E = V <sub>IH</sub> , V <sub>Out</sub> = 0 to V <sub>CC</sub> )	I <sub>lkg</sub> (O)		± 1.0	μА
Output Low Voltage (I <sub>OL</sub> = + 8.0 mA)	VOL	V =	0.4	V
Output High Voltage (I <sub>OH</sub> = – 4.0 mA)	VOH	2.4	_	V

#### **POWER SUPPLY CURRENTS**

Parameter			Min	Тур	Max	Unit
AC Active Supply Current (I <sub>out</sub> = 0 mA, V <sub>CC</sub> = max)	MCM6249-20: t <sub>AVAV</sub> = 20 ns MCM6249-25: t <sub>AVAV</sub> = 25 ns MCM6249-35: t <sub>AVAV</sub> = 35 ns	lcc	<u> </u>	175 160 145	190 175 160	mA
AC_Standby Current (V <sub>CC</sub> = max, E = V <sub>IH</sub> , No other restrictions on other inputs)	MCM6249-20: t <sub>AVAV</sub> = 20 ns MCM6249-25: t <sub>AVAV</sub> = 25 ns MCM6249-35: t <sub>AVAV</sub> = 35 ns	I <sub>SB1</sub>	<u> </u>	50 40 35	60 50 40	mA
CMOS Standby Current (E $\geq$ V <sub>CC</sub> - 0.2 V $\geq$ V <sub>CC</sub> - 0.2 V) (V <sub>CC</sub> = max, f = 0 MH:		I <sub>SB2</sub>		10	15	mA

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## $\textbf{CAPACITANCE} \ (\textit{f} = 1.0 \ \textrm{MHz}, \ \textrm{dV} = 3.0 \ \textrm{V}, \ \textrm{T}_{\mbox{A}} = 25 \ \textrm{^{\circ}C}, \ \textrm{Periodically Sampled Rather Than 100\% Tested})$

Parameter	Symbol	Тур	Max	Unit	
Input Capacitance	All Inputs Except Clocks and DQs E, G, W	C <sub>in</sub> C <sub>ck</sub>	4 5	6 8	pF
Input/Output Capacitance	DQ	C <sub>I/O</sub>	5	8	pF

#### **AC OPERATING CONDITIONS AND CHARACTERISTICS**

(V<sub>CC</sub> =  $5.0 \text{ V} \pm 10\%$ , T<sub>A</sub> =  $0 \text{ to} + 70^{\circ}\text{C}$ , Unless Otherwise Noted)

Input Pulse Levels 0 to 3.0 V	Output Timing Measurement Reference Level 1.5 V
Input Rise/Fall Time	Output Load See Figure 1a
Input Timing Measurement Reference Level 1.5 V	

#### **READ CYCLE TIMING** (See Note 1)

1001.		МСМ6	249–20	мсм6	249–25	мсм6	249–35		
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
Read Cycle Time	t <sub>AVAV</sub>	20	-	25		35	0	ns	2, 3
Address Access Time	tAVQV		20	_	25	M.	35	ns	
Enable Access Time	tELQV	<u> </u>	20	_	25		35	ns	4
Output Enable Access Time	<sup>t</sup> GLQV	-	6	_	8		10	ns	$\sqrt{O}_{\Sigma}$
Output Hold from Address Change	tAXQX	5		5	_	5	N	ns	
Enable Low to Output Active	tELQX	5	<b>)</b> –	5	_ <	5	4)	ns	5, 6, 7
Output Enable Low to Output Active	tGLQX	0		0	_	0	N —	ns	5, 6, 7
Enable High to Output High–Z	t <sub>EHQZ</sub>	0	9	0	10	0	12	ns	5, 6, 7
Output Enable High to Output High–Z	tGHQZ	0	9	0	10	0	12	ns	5, 6, 7
Power Up Time	<sup>t</sup> ELICCH	0	$0_{\overline{A}_{*}}$	0	_	0		ns	100
Power Down Time	tEHICCL		20	-	25	_	35	ns	

#### NOTES:

- 1. W is high for read cycle.
- 2. Product sensitivities to noise require proper grounding and decoupling of power supplies as well as minimization or elimination of bus contention conditions during read and write cycles.
- 3. All read cycle timings are referenced from the last valid address to the first transitioning address.
- 4. Addresses valid prior to or coincident with E going low/E going high.
- At any given voltage and temperature, t<sub>EHQZ</sub> max < t<sub>ELQX</sub> min, and t<sub>GHQZ</sub> max < t<sub>GLQX</sub> min, both for a given device and from device to device.
- 6. Transition is measured  $\pm$  500 mV from steady–state voltage with load of Figure 1b.
- 7. This parameter is sampled and not 100% tested.
- 8. Device is continuously selected ( $E \le V_{IL}$ ,  $G \le V_{IL}$ ).

## 

Figure 1. AC Test Loads

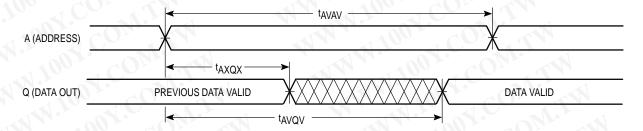
#### **TIMING LIMITS**

The table of timing values shows either a minimum or a maximum limit for each parameter. Input requirements are specified from the external system point of view. Thus, address setup time is shown as a minimum since the system must supply at least that much time. On the other hand, responses from the memory are specified from the device point of view. Thus, the access time is shown as a maximum since the device never provides data later than that time.

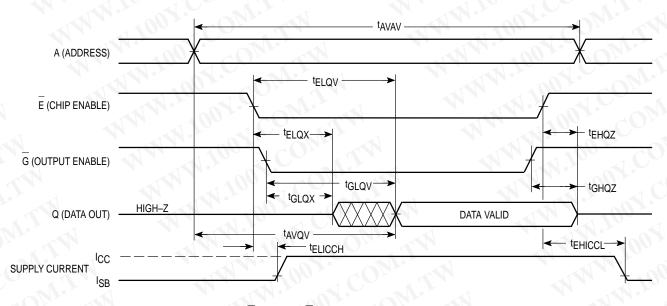
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#### READ CYCLE 1 (See Note 8)



## READ CYCLE 2 (See Note)



NOTE: Addresses valid prior to or coincident with E going low/E going high.

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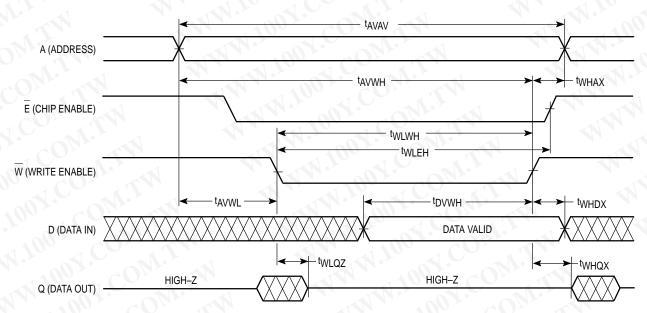
#### WRITE CYCLE 1 (W Controlled, See Notes 1, 2, and 3)

100 CON LA		мсм6	249–20	МСМ6	249–25	мсм6	249–35		
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
Write Cycle Time	t <sub>AVAV</sub>	20	= 1	25	1 E	35		ns	4
Address Setup Time	tAVWL	0	11.	0		0	=	ns	
Address Valid to End of Write	tAVWH	15	=	17	4	20	\ . <del>\</del>	ns	
Write Pulse Width	tWLWH,	15		17		20	7.7	ns	
Data Valid to End of Write	tDVWH	10		10	10	15	- (	ns	
Data Hold Time	twHDX	0	=	0	01	0	$\Phi_{Z_{A}}$	ns	
Write Low to Data High-Z	tWLQZ	0	9	0	10	0	15	ns	5,6,7
Write High to Output Active	tWHQX	5		5	<del>4</del>	5	G	ns	5,6,7
Write Recovery Time	tWHAX	0	_	0	1 7	0		ns	

#### NOTES:

- 1. A write occurs during the overlap of E low and W low.
- Product sensitivities to noise require proper grounding and decoupling of power supplies as well as minimization or elimination of bus contention conditions during read and write cycles.
- 3. If G goes low coincident with or after W goes low, the output will remain in a high-impedance state.
- 4. All write cycle timings are referenced from the last valid address to the first transitioning address.
- 5. Transition is measured  $\pm$  500 mV from steady–state voltage with load of Figure 1b.
- 6. This parameter is sampled and not 100% tested.
- 7. At any given voltage and temperature, tWLQZ max < tWHQX min both for a given device and from device to device.

## WRITE CYCLE 1 (W Controlled, See Notes 1, 2, and 3)



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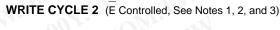
MCM6249

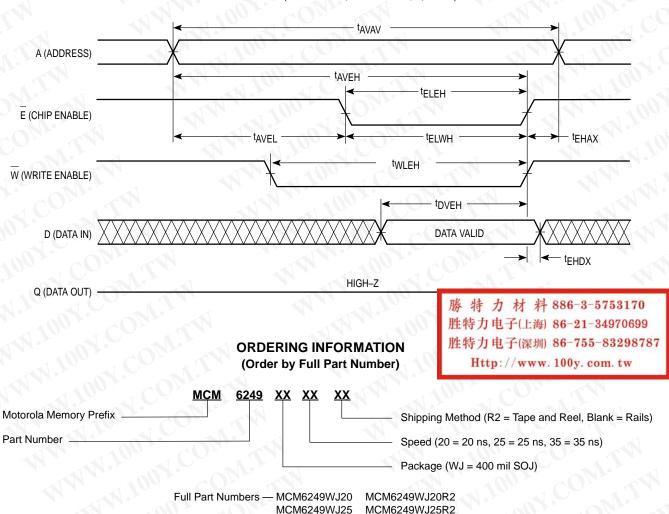
WRITE CYCLE 2 (E Controlled, See Notes 1, 2, and 3)

100 CO P		мсм6	249–20	МСМ6	249–25	мсм6	249–35		
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
Write Cycle Time	t <sub>AVAV</sub>	20	<b>=</b> 1	25	1 🖯	35		ns	4
Address Setup Time	t <sub>AVEL</sub>	0	11.	0	- ~	0	=1	ns	
Address Valid to End of Write	t <sub>AVEH</sub>	15	7	17	4	20	\. <u>\</u>	ns	
Enable Pulse Width	tELEH, tELWH	15		17		20	1	ns	5,6
Write Pulse Width	tWLEH	15		17	10	20	_ (	ns	
Data Valid to End of Write	†DVEH	10	-	10	0	15		ns	
Data Hold Time	tEHDX	0		0	N =	0	-	ns	
Write Recovery Time	t <sub>EHAX</sub>	0		0	<del>-</del> 3	0	G	ns	

#### NOTES:

- 1. A write occurs during the overlap of E low and W low.
- 2. Product sensitivities to noise require proper grounding and decoupling of power supplies as well as minimization or elimination of bus contention conditions during read and write cycles.
- 3. If G goes low coincident with or after W goes low, the output will remain in a high-impedance state.
- 4. All write cycle timing is referenced from the last valid address to the first transitioning address.
- 5. If E goes low coincident with or after W goes low, the output will remain in a high impedance condition.
- 6. If E goes high coincident with or before W goes high, the output will remain in a high impedance condition.





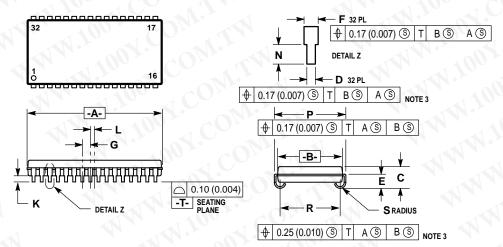
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MCM6249WJ35

MCM6249WJ35R2

#### PACKAGE DIMENSIONS

**WJ PACKAGE** 400 MIL SOJ **CASE 857A-02** 



#### NOTES

- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982. CONTROLLING DIMENSION: INCH.

- TO BE DETERMINED AT PLANE -T-.
  DIMENSION A & B DO NOT INCLUDE MOLD PROTRUSION. MOLD PROTRUSION SHALL NOT EXCEED 0.15 (0.006) PER SIDE.
- DIMENSION A & B INCLUDE MOLD MISMATCH AND ARE DETERMINED AT THE PARTING LINE.
- 857A-01 IS OBSOLETE, NEW STANDARD 857A-02.

	MILLIM	ETERS	INC	HES
DIM	DIM MIN MAX		MIN	MAX
Α	20.83	21.08	0.820	0.830
В	10.03	10.29	0.395	0.405
C	3.26	3.75	0.128	0.148
D	0.41	0.50	0.016	0.020
E	2.24	2.48	0.088	0.098
F	0.67	0.81	0.026	0.032
G	1.27	BSC	0.05	0 BSC
K	0.89	1.14	0.035	0.045
L	0.64	BSC	0.02	5 BSC
N	0.76	1.14	0.030	0.045
Р	11.05	11.30	0.435	0.445
R	9.27	9.52	0.365	0.375
S	0.77	1.01	0.030	0.040

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