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SIZE		10 100X ON TW		.21	
Model No.		TS2611N11E11	TS2641N11E64	TS2651N111E78	
Туре		BRX	BRX	BRT	
Primary		R1-R2	R1-R2	S1-S3,S2-S4	
Input Voltage/Frequency		AC7Vrms 10kHz	AC7Vrms 10kHz	AC3.5Vrms 4kHz	
Transformation Ratio		0.5 ± 10%	0.5 ± 5%	0.3 ± 5%	
Electrical Error		± 0.5° Max.	± 10' Max.	± 10' Max.	
Residual Voltage		50mVrms Max.	20mVrms Max.	WW.100 2. COM. 17	
Phase Shift		+5° Nom.	-5° Max.	WW.1001.COM.IT	
Impedance	ZRO	160 Ω Nom.	190 Ω	51+j90Ω Nom.	
	Zrs	COM.TW WY	W.100Y.CONLTW	44+j76Ω Nom.	
	Zso	CONTRA WI	300Ω	102+j150Ω Nom.	
	Zss	130 Ω Nom.	270Ω	WWWWWWWWWWW	
Operating Temperature		-30 ~ +100°C	-10 ~ +100°C	-10 ~ +150°C	
Max.Operating Speed		100s-1	83.3s ⁻¹	133.3s-1	
Mass		0.1kg Max.	0.3kg Nom.	0.305kg Nom.	
Output Type		Normal	Normal + θ CCW	ER1-R2=K(-ES1-S3SIN θ -ES2-S4COS θ)	

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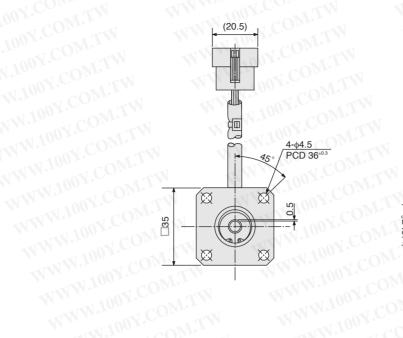
100X.CO

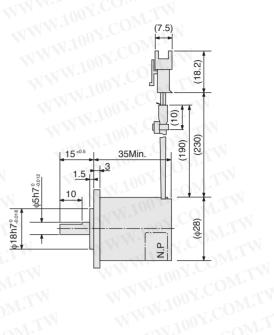
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V.100X.CO

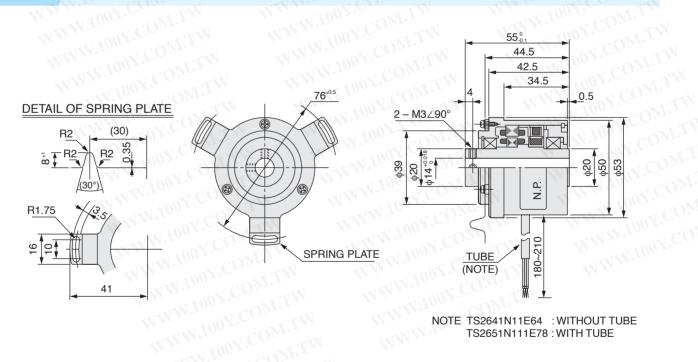




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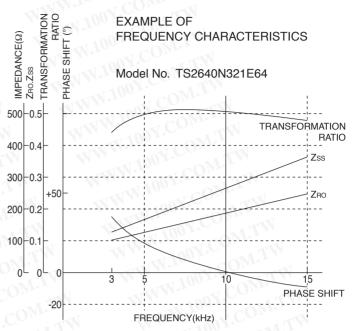
COMTW





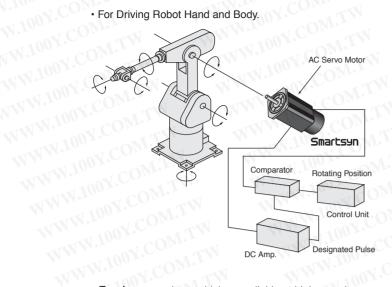
APPLICATION NOTES

- The supply voltage is a rated value, and a resolver can accept a voltage from 3V to approx. 1.2 times as high as the rating. However, the supply frequency should only be altered within ±5% lest it should affect the accuracy. Electrical parameters largely vary as the frequency varies as shown on the right.
- When a noise source is in vicinity, or when signal transfer distance is long, twisted/shielded pair cables should be used. When a noise still exists on the signals, they should be received by a differential amplifier.
- In BRX resolver, the two output voltages should be connected to the same amount of loads each other, or the voltages will get disproportionate, thus affect the accuracy.
- When an intense magnetic field surrounds a resolver, it may not work properly with its magnetic flux affected.
- When a resolver is used in a high humidity as close to 100% Rh for a long time, waterproof structure should be considered lest its insulation materials should deteriorate.
- All resolvers in the catalog are 1× (2 poles) resolvers.
 For winding modifications to other speeds, please consult us.

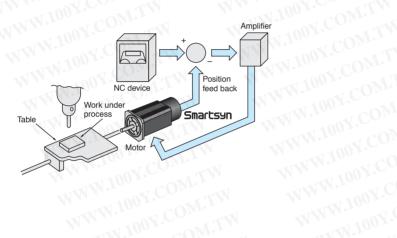


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For Driving Robot Hand and Body.



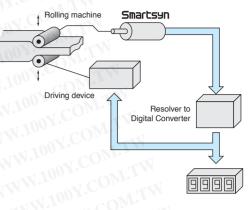
• Smartsyn resolvers which are reliable at high speed are suitable for numerical control systems.



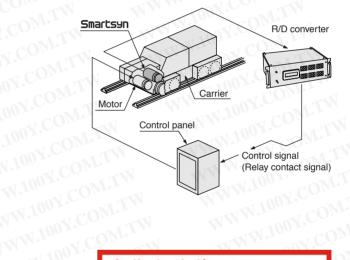
· Applicable to the roller positioning control of rolling mills.

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Detection of traveling position of automatic carrier



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