

CAT93C46/56/57/66/86

1K/2K/2K/4K/16K-Bit Microwire Serial EEPROM



FEATURES

- High speed operation:
 - 93C46/56/57/66: 1MHz
 - 93C86: 3MHz
- Low power CMOS technology
- 1.8 to 6.0 volt operation
- Selectable x8 or x16 memory organization
- Self-timed write cycle with auto-clear
- Hardware and software write protection

- Power-up inadvertant write protection
- 1,000,000 Program/erase cycles
- 100 year data retention
- Commercial, industrial and automotive temperature ranges
- Sequential read (except CAT93C46)
- Program enable (PE) pin (CAT93C86 only)
- "Green" package option available

DESCRIPTION

The CAT93C46/56/57/66/86 are 1K/2K/2K/4K/16K-bit Serial EEPROM memory devices which are configured as either registers of 16 bits (ORG pin at V_{CC}) or 8 bits (ORG pin at GND). Each register can be written (or read) serially by using the DI (or DO) pin. The CAT93C46/56/57/66/86 are manufactured using Catalyst's advanced

CMOS EEPROM floating gate technology. The devices are designed to endure 1,000,000 program/erase cycles and have a data retention of 100 years. The devices are available in 8-pin DIP, 8-pin SOIC, 8-pin TSSOP and 8-pad TDFN packages.

PIN CONFIGURATION

TSSOP Package (U,Y) DIP Package (P, L) SOIC Package (J,W) SOIC Package (S,V) SOIC Package (K,X) CS 🗀 •1 CS 🗀 •1 □ vcc □ vcc NC (PE*) □ •1 ☐ ORG CS [☐ Vcc □ Vcc 7 NC ORG SK [2 SK [SK 🖂 2 ☐ NC (PE*) Vcc C □ GND SK 🗀 NC (PE*) ☐ NC (PE*) DI C 6 ☐ ORG 5 ☐ GND _ DO 3 6 ORG 3 6 ORG DI 🗆 GND 5 🖾 GND SK C DI 🗀 DO [☐ GND DO [

*Only For 93C86

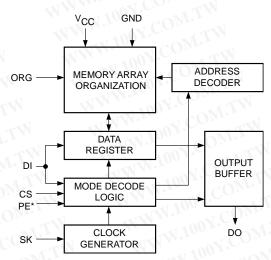
** TSSOP (U/Y) package only available for 93C46/56/57/66

PIN FUNCTIONS

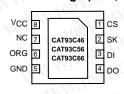
	ANY TOUS
Pin Name	Function
CS	Chip Select
SK	Clock Input
DI	Serial Data Input
DO	Serial Data Output
Vcc	+1.8 to 6.0V Power Supply
GND	Ground
ORG	Memory Organization
NC	No Connection
PE*	Program Enable

Note: When the ORG pin is connected to VCC, the x16 organization is selected. When it is connected to ground, the x8 pin is selected. If the ORG pin is left unconnected, then an internal pullup device will select the x16 organization.

BLOCK DIAGRAM



TDFN Package (RD4, ZD4)



Bottom View

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ABSOLUTE MAXIMUM RATINGS*

Temperature Under Bias55°	C to +125°C
Storage Temperature65°	C to +150°C
Voltage on any Pin with Respect to Ground ⁽¹⁾ 2.0V to	+V _{CC} +2.0V
V _{CC} with Respect to Ground2	.0V to +7.0V
Package Power Dissipation Capability (T _A = 25°C)	1.0W
Lead Soldering Temperature (10 secs)	300°C
Output Short Circuit Current(2)	100 mA

*COMMENT

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions outside of those listed in the operational sections of this specification is not implied. Exposure to any absolute maximum rating for extended periods may affect device performance and reliability.

RELIABILITY CHARACTERISTICS

ead Solde	ring Temperature (10	secs) 300°C	ity.			
output Sho	rt Circuit Current ⁽²⁾	100 mA				
ELIABILI	TY CHARACTERIST	ics Cont. Tr				
Symbol	Parameter	Reference Test Method	Min	Тур	Max	Units
N _{END} (3)	Endurance	MIL-STD-883, Test Method 1033	1,000,000	1001.	$0_{M,I,I}$	Cycles/Byte
T _{DR} (3)	Data Retention	MIL-STD-883, Test Method 1008	100	1.100 X.	OMITY	Years
V _{ZAP} ⁽³⁾	ESD Susceptibility	MIL-STD-883, Test Method 3015	2000	N 100Y.	COM.T	Volts
I _{LTH} (3)(4)	Latch-Up	JEDEC Standard 17	100	1003	OM.	mA

D.C. OPERATING CHARACTERISTICS

 V_{CC} = +1.8V to +6.0V, unless otherwise specified.

Symbol	Parameter	Test Conditions	Min	Тур	Max	Units
I _{CC1}	Power Supply Current (Operating Write)	$f_{SK} = 1MHz$ $V_{CC} = 5.0V$	CLA	WWW	3.00	mA
I _{CC2}	Power Supply Current (Operating Read)	$f_{SK} = 1MHz$ $V_{CC} = 5.0V$	W.TW	MM	500	μА
I _{SB1}	Power Supply Current (Standby) (x8 Mode)	CS = 0V ORG=GND	WIN	WW	10	μА
I _{SB2} (5)	Power Supply Current (Standby) (x16Mode)	CS=0V ORG=Float or V _{CC}	COM.TW	W	0,00	μΑ
lu 🕥	Input Leakage Current	$V_{IN} = 0V \text{ to } V_{CC}$	OWITH		11.100	μΑ
ILO	Output Leakage Current (Including ORG pin)	$V_{OUT} = 0V \text{ to } V_{CC},$ $CS = 0V$	COM.TW	N	1 1 10 N	μА
V _{IL1}	Input Low Voltage	$4.5V \le V_{CC} < 5.5V$	-0.1	XX	0.8	VC
V _{IH1}	Input High Voltage	$4.5V \le V_{CC} < 5.5V$	2	- 41	V _{CC} + 1	Joo A
V _{IL2}	Input Low Voltage	1.8V ≤ V _{CC} < 4.5V	MO O M	II	Vcc x 0.2	1.10V
V _{IH2}	Input High Voltage	4.8V ≤ V _{CC} < 4.5V	Vcc x 0.7	LTN	Vcc+1	VIV
V _{OL1}	Output Low Voltage	$4.5V \le V_{CC} < 5.5V$ $I_{OL} = 2.1 \text{mA}$	N.100X.CO	M.TW	0.4	VV. V00
V _{OH1}	Output High Voltage	$4.5V \le V_{CC} < 5.5V$ $I_{OH} = -400\mu A$	2.4	OM.TW	4/	M.A.
V _{OL2}	Output Low Voltage	$1.8V \le V_{CC} < 4.5V$ $I_{OL} = 1 \text{mA}$	MM.100X	.co _{M.T}	0.2	WWW
V _{OH2}	Output High Voltage	$1.8V \le V_{CC} < 4.5V$ $I_{OH} = -100\mu A$	Vcc - 0.2	Y.COM	IW	V

Note:

- The minimum DC input voltage is -0.5V. During transitions, inputs may undershoot to -2.0V for periods of less than 20 ns. Maximum DC voltage on output pins is V_{CC} +0.5V, which may overshoot to V_{CC} +2.0V for periods of less than 20 ns.
 Qutput shorted for no more than one second. No more than one output shorted at a time.
- This parameter is tested initially and after a design or process change that affects the parameter. Latch-up protection is provided for stresses up to 100 mA on address and data pins from -1V to V_{CC} +1V.
- (5) Standby Current (ISB₂)=0μA (<900nA) for 93C46/56/57/66, (ISB₂)=2μA for 93C86.

PIN CAPACITANCE

Symbol	Test	Conditions	Min	Тур	Max	Units
C _{OUT} (3)	Output Capacitance (DO)	V _{OUT} =0V	TOMITY		5	pF
C _{IN} (3)	Input Capacitance (CS, SK, DI, ORG)	V _{IN} =0V	T.M.T		5	pF

INSTRUCTION SET

Instruction	Device	Start	Opcode	Add	ress	TWVD	ata	Comments	PE(2)
T.MOT	Type	Bit	1.100X.	x8	x16	x8	x16	OM.TV	
READ	93C46	W1	10	A6-A0	A5-A0	MA	1 100 X.	Read Address AN-A0	
A COM.	93C56 ⁽¹⁾	-1	10	A8-A0	A7-A0		You Y	COLTY	
. COM',	93C66	1	10	A8-A0	A7-A0		M.In.	COM	
OY.CO	93C57	1	10	A7-A0	A6-A0		100	· COM.TW	
VA. COM.	93C86	1	10	A10-A0	A9-A0		100	N.CO.	Χ
ERASE	93C46	1 -	11	A6-A0	A5-A0	V	MAL	Clear Address AN-A0	
100 - (0)	93C56 ⁽¹⁾	1	11	A8-A0	A7-A0		NIN N.	COM.	
1007.	93C66	1	11	A8-A0	A7-A0		- XIXI	100 r. COW. I.	
OON.CO	93C57	1	11	A7-A0	A6-A0		MM.	100X.CO	
W. Tuo C	93C86	1	11	A10-A0	A9-A0		WWW	LOON.COM TW	I
WRITE	93C46	1	01	A6-A0	A5-A0	D7-D0	D15-D0	Write Address AN-A0	
, 100 x.	93C56 ⁽¹⁾	1	01	A8-A0	A7-A0	D7-D0	D15-D0	M.Ing COM.	
M. M.	93C66	1	01 🕥	A8-A0	A7-A0	D7-D0	D15-D0	1100Y. OM.TV	
TWW.IO	93C57	1	01	A7-A0	A6-A0	D7-D0	D15-D0	MM. OX.COM. TI	
1 1 100	93C86	. 1	01	A10-A0	A9-A0	D7-D0	D15-D0	MM.Ing COM.	
EWEN	93C46	1	00	11XXXXX	11XXXX			Write Enable	
MM	93C56	1	00	11XXXXXXX	11XXXXXX		4	100x.	
WW.	93C66	1	00	11XXXXXXX	11XXXXXX		V	MMM. OUX.CO.	
W	93C57	1	00	11XXXXXX	11XXXXX		-«1	LINN. TOO	
MW.	93C86	1	00	11XXXXXXXXX	11XXXXXXXXX	T.Mor	N	W. 1001.	X
EWDS	93C46	1	00	00XXXXX	00XXXX		TW	Write Disable	
WW	93C56	(1)	00	00XXXXXXX	00XXXXXX		W	MM 100X.C	
11.	93C66	1	00	00XXXXXXX	00XXXXXX			TWW.IO	
W	93C57	1 1	00	00XXXXXX	00XXXXX		V.T.V	1001.	
1/	93C86	10	00	00XXXXXXXX	00XXXXXXXX	MY.CO	WTI	WW 100Y	X
ERAL	93C46	1	00	10XXXXX	10XXXX		Divi	Clear All Addresses	
	93C56	001	00	10XXXXXXX	10XXXXXX		$O_{M^{*}r}$	TINN.100	
	93C66	101	00	10XXXXXXX	10XXXXXX		M.T	M 1 100	
	93C57	1	00	10XXXXXX	10XXXXX		Con	M MM	
	93C86	1.11	00	10XXXXXXXXX	10XXXXXXXX	N.700	$_{1}$ CO $_{M}$.	WWW.I	od.
WRAL	93C46	110	00	01XXXXX	01XXXX	D7-D0	D15-D0	Write All Addresses	Ino.
	93C56	1	00	01XXXXXXX	01XXXXXX	D7-D0	D15-D0	T.M. M.	
	93C66	11	00	01XXXXXXX	01XXXXXX	D7-D0	D15-D0	TW WW	
	93C57	1	00	01XXXXXX	01XXXXX	D7-D0	D15-D0	Mr.	
	93C86	1	00	01XXXXXXXXX	01XXXXXXXX	D7-D0	D15-D0	W.I.M.	N.10

Note:

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⁽¹⁾ Address bit A8 for 256x8 ORG and A7 for 128x16 ORG are "Don't Care" bits, but must be kept at either a "1" or "0" for READ, WRITE and ERASE commands.

Applicable only to 93C86

⁽³⁾ This parameter is tested initially and after a design or process change that affects the parameter. WWW.100Y.COM.TW

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A.C. CHARACTERISTICS (93C46/56/57/66)

		TW	N	1700_{3}		nits			
M.TW		LTW.		c = /-6V		c = V-6V	1	cc = /-5.5V	
SYMBOL	PARAMETER	Test Conditions	Min	Max	Min	Max	Min	Max	Unit
tcss	CS Setup Time	OMITH	200	NA TAN	100	COM	50		ns
tcsн	CS Hold Time	COM.TW	0		1.00		0		ns
t _{DIS}	DI Setup Time	WI.MO	400	MAI	200	¥.0	100	1	ns
t _{DIH}	DI Hold Time	Y.COM.TW	400	MA	200	07.0	100	. < 1	ns
t _{PD1}	Output Delay to 1	OY.COM.TY	N	1	- 1 N.	0.5	OM.	0.25	μs
t _{PD0}	Output Delay to 0	C _L = 100pF	N	1	TATAN	0.5	COM	0.25	μs
t _{HZ} ⁽¹⁾	Output Delay to High-Z	100 X (3)	LM	400	NY	200	- CO1	100	ns
t _{EW}	Program/Erase Pulse Width	V.100X.CON	TI	10	11/1/	10	7.00	10	ms
t _{CSMIN}	Minimum CS Low Time	W.100Y.CO	1.1	- 1	0.5	JW.10	0.25	M_{LL}	μs
tskHi	Minimum SK High Time	W.100Y.C	11	1	0.5	1.WW	0.25	OW.T	μs
tsklow	Minimum SK Low Time	W.100Y.C.	0.11.7		0.5	. WW	0.25	COM	μs
tsv	Output Delay to Status Valid	W.100X.	COM	1		0.5	1001	0.25	μs
SK _{MAX}	Maximum Clock Frequency	NN 100X	DC	250	DC	500	DC	1000	kHz

A.C. CHARACTERISTICS (93C86)

W.	M.1001. COM.11	WW.I	0 2 C	$0_{M.r}$	Lir	nits	M.70	ov.C	OM.
1	WWW.100X.COM.TW	Test		cc = V-6V		c = V-6V		cc = /-5.5V	OW.
SYMBOL	PARAMETER	Conditions	Min	Max	Min	Max	Min	Max	Units
tcss	CS Setup Time	WW	200	I.Co.	100	4	50	N 100	ns
tcsH	CS Hold Time		0	O.Y.Co.	0		0	-XX 10	ns
t _{DIS}	DI Setup Time		200	00 Y.C.	100		50	-W.1	ns
tDIH	DI Hold Time		200	100 Y.C	100	N	50	N Y	ns
t _{PD1}	Output Delay to 1		MALA	100%		0.5	1	0.15	μs
t _{PD0}	Output Delay to 0	C _L = 100pF	MIN	100	Cos	0.5		0.15	μs
t _{HZ} ⁽¹⁾	Output Delay to High-Z	(3)	WW	400	Y.CO	200		100	ns
t _{EW}	Program/Erase Pulse Width		W	5	OY.CO	5		5	ms
tcsmin	Minimum CS Low Time		1 1	W V 1	0.5	OM.T	0.15	W	μs
tskhi	Minimum SK High Time		1 1		0.5	-0M.	0.15		μs
tsklow	Minimum SK Low Time		1	MM	0.5	OM	0.15		μs
tsv	Output Delay to Status Valid			1	N 100	0.5	LTW	0.1	μs
SK _{MAX}	Maximum Clock Frequency		DC	500	DC	1000	DC	3000	kHz

NOTE:

⁽¹⁾ This parameter is tested initially and after a design or process change that affects the parameter.

	MIN WWW	1100 Y.COM	TW
POWER-UP TI	MING (1)(2)		
SYMBOL	PARAMETER	Max	Units
t _{PUR}	Power-up to Read Operation	101)	ms
t _{PUW}	Power-up to Write Operation	107.0	ms

NOTE:

- This parameter is tested initially and after a design or process change that affects the parameter. (1)
- t_{PUR} and t_{PUW} are the delays required from the time \dot{V}_{CC} is stable until the specified operation can be initiated.
- The input levels and timing reference points are shown in "AC Test Conditions" table. (3)

A.C. TEST CONDITIONS

nput Rise and Fall Times	≤ 50ns	WWW.100
nput Pulse Voltages	0.4V to 2.4V	$4.5 \text{V} \leq \text{V}_{\text{CC}} \leq 5.5 \text{V}$
Γiming Reference Voltages	0.8V, 2.0V	4.5V ≤ V _{CC} ≤ 5.5V
nput Pulse Voltages	0.2V _{CC} to 0.7V _{CC}	1.8V ≤ V _{CC} ≤ 4.5V
Γiming Reference Voltages	0.5V _{CC}	1.8V ≤ V _{CC} ≤ 4.5V

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DEVICE OPERATION

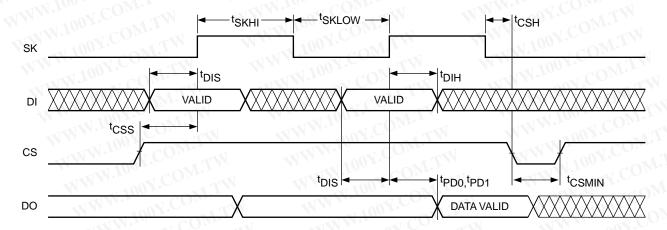
The CAT93C46/56(57)66/86 is a 1024/2048/4096/ 16,384-bit nonvolatile memory intended for use with industry standard microprocessors. The CAT93C46/56/ 57/66/86 can be organized as either registers of 16 bits or 8 bits. When organized as X16, seven 9-bit instructions for 93C46; seven 10-bit instructions for 93C57; seven 11-bit instructions for 93C56 and 93C66; seven 13-bit instructions for 93C86; control the reading, writing and erase operations of the device. When organized as X8, seven 10-bit instructions for 93C46; seven 11-bit instructions for 93C57; seven 12-bit instructions for 93C56 and 93C66: seven 14-bit instructions for 93C86: control the reading, writing and erase operations of the device. The CAT93C46/56/57/66/86 operates on a single power supply and will generate on chip, the high voltage required during any write operation.

Instructions, addresses, and write data are clocked into

the DI pin on the rising edge of the clock (SK). The DO pin is normally in a high impedance state except when reading data from the device, or when checking the ready/busy status after a write operation.

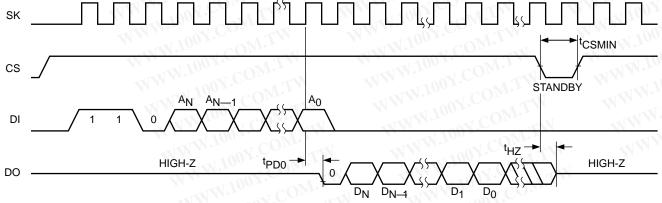
The ready/busy status can be determined after the start of a write operation by selecting the device (CS high) and polling the DO pin; DO low indicates that the write operation is not completed, while DO high indicates that the device is ready for the next instruction. If necessary, the DO pin may be placed back into a high impedance state during chip select by shifting a dummy "1" into the DI pin. The DO pin will enter the high impedance state on the falling edge of the clock (SK). Placing the DO pin into the high impedance state is recommended in applications where the DI pin and the DO pin are to be tied together to form a common DI/O pin.

Figure 1. Sychronous Data Timing



93C46/56/57/66/86 F03

Figure 2a. Read Instruction Timing (93C46)



93C46/56/57/66/86 F04

The format for all instructions sent to the device is a logical "1" start bit, a 2-bit (or 4-bit) opcode, 6-bit (93C46)/ /7-bit (93C57)/ 8-bit (93C56 or 93C66)/10-bit (93C86) (an additional bit when organized X8) and for write operations a 16-bit data field (8-bit for X8 organizations).

Note: This note is applicable only to 93C86. The Write, Erase, Write all and Erase all instructions require PE=1. If PE is left floating, 93C86 is in Program Enabled mode. For Write Enable and Write Disable instruction PE=don't care.

Read

Upon receiving a READ command and an address (clocked into the DI pin), the DO pin of the CAT93C46/ 56/57/66/86 will come out of the high impedance state and, after sending an initial dummy zero bit, will begin shifting out the data addressed (MSB first). The output data bits will toggle on the rising edge of the SK clock and are stable after the specified time delay (tPD0 or tPD1).

For the CAT93C56/57/66/86, after the initial data word has been shifted out and CS remains asserted with the SK clock continuing to toggle, the device will automatically increment to the next address and shift out the next data word in a sequential READ mode. As long as CS is continuously asserted and SK continues to toggle, the device will keep incrementing to the next address automatically until it reaches to the end of the address space, then loops back to address 0. In the sequential READ mode, only the initial data word is preceded by a dummy zero bit. All subsequent data words will follow without a dummy zero bit.

Write

After receiving a WRITE command, address and the data, the CS (Chip Select) pin must be deselected for a minimum of t_{CSMIN}. The falling edge of CS will start the self clocking clear and data store cycle of the memory location specified in the instruction. The clocking of the SK pin is not necessary after the device has entered the self clocking mode. The ready/busy status of the CAT93C46/56/57/66/86 can be determined by selecting the device and polling the DO pin. Since this device features Auto-Clear before write, it is NOT necessary to erase a memory location before it is written into.



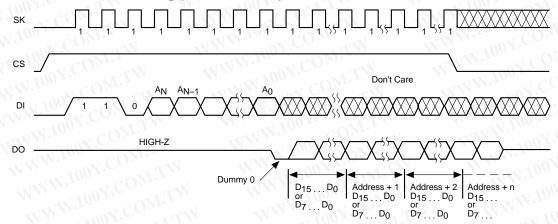
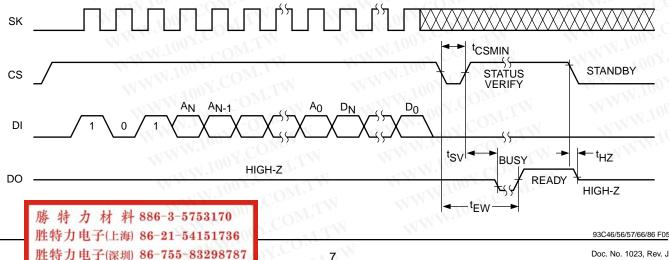


Figure 3. Write Instruction Timing

Http://www. 100y. com. tw



Erase

Upon receiving an ERASE command and address, the CS (Chip Select) pin must be deasserted for a minimum of tcsmin. The falling edge of CS will start the self clocking clear cycle of the selected memory location. The clocking of the SK pin is not necessary after the device has entered the self clocking mode. The ready/busy status of the CAT93C46/56/57/66/86 can be determined by selecting the device and polling the DO pin. Once cleared, the content of a cleared location returns to a logical "1" state.

Erase/Write Enable and Disable

The CAT93C46/56/57/66/86 powers up in the write disable state. Any writing after power-up or after an EWDS (write disable) instruction must first be preceded by the EWEN (write enable) instruction. Once the write instruction is enabled, it will remain enabled until power to the device is removed, or the EWDS instruction is sent. The EWDS instruction can be used to disable all CAT93C46/56/57/66/86 write and clear instructions, and will prevent any accidental writing or clearing of the device. Data can be read normally from the device regardless of the write enable/disable status.

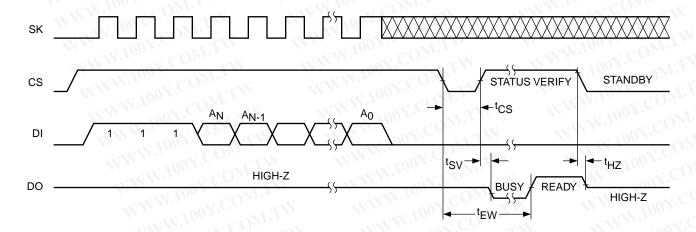
Erase All

Upon receiving an ERAL command, the CS (Chip Select) pin must be deselected for a minimum of tcsmin. The falling edge of CS will start the self clocking clear cycle of all memory locations in the device. The clocking of the SK pin is not necessary after the device has entered the self clocking mode. The ready/busy status of the CAT93C46/56/57/66/86 can be determined by selecting the device and polling the DO pin. Once cleared, the contents of all memory bits return to a logical "1" state.

Write All

Upon receiving a WRAL command and data, the CS (Chip Select) pin must be deselected for a minimum of t_{CSMIN}. The falling edge of CS will start the self clocking data write to all memory locations in the device. The clocking of the SK pin is not necessary after the device has entered the self clocking mode. (Note 1.) The ready/ busy status of the CAT93C46/56/57/66/86 can be determined by selecting the device and polling the DO pin. It is not necessary for all memory locations to be cleared before the WRAL command is executed.

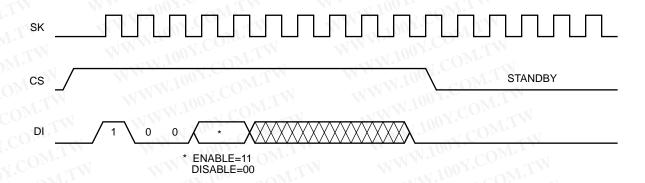




93C46/56/57/66/86 F0

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Figure 5. EWEN/EWDS Instruction Timing



93C46/56/57/66/86 F07

93C46/56/57/66/86 F08

Figure 6. ERAL Instruction Timing

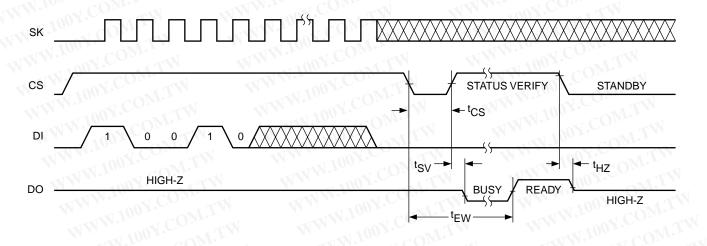
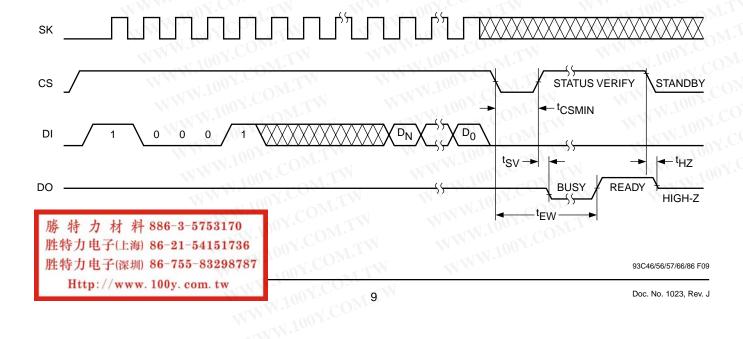
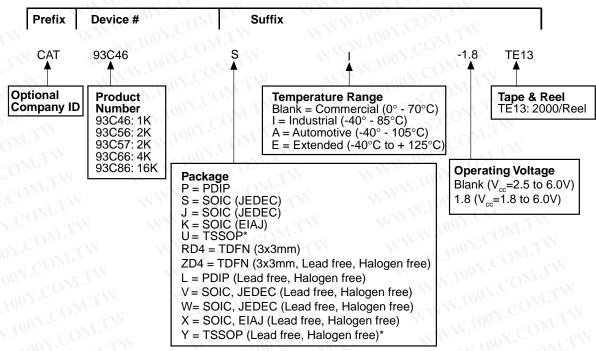


Figure 7. WRAL Instruction Timing



ORDERING INFORMATION



*CAT93C46/56/57/66 only

Notes:

- (1) The device used in the above example is a 93C46SI-1.8TE13 (SOIC, Industrial Temperature, 1.8 Volt to 6 Volt Operating Voltage, Tape & Reel)
- (2) TSSOP (U/Y) package only available for 93C46/56/57/66

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