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May 1999

LM7171 Very High

Speed,

High

Output

Current,

Voltage

Feedback

Amplifie

National Semiconductor

LM7171 Very High Speed, High Output Current, Voltage Feedback Amplifier

General Description

The LM7171 is a high speed voltage feedback amplifier that has the slewing characteristic of a current feedback amplifier; yet it can be used in all traditional voltage feedback amplifier configurations. The LM7171 is stable for gains as low as +2 or -1. It provides a very high slew rate at $4100V/\mu$ s and a wide unity-gain bandwidth of 200 MHz while consuming only 6.5 mA of supply current. It is ideal for video and high speed signal processing applications such as HDSL and pulse amplifiers. With 100 mA output current, the LM7171 can be used for video distribution, as a transformer driver or as a laser diode driver.

Operation on $\pm 15V$ power supplies allows for large signal swings and provides greater dynamic range and signal-to-noise ratio. The LM7171 offers low SFDR and THD, ideal for ADC/DAC systems. In addition, the LM7171 is specified for $\pm 5V$ operation for portable applications.

The LM7171 is built on National's advanced VIPTM III (Vertically integrated PNP) complementary bipolar process.

Features

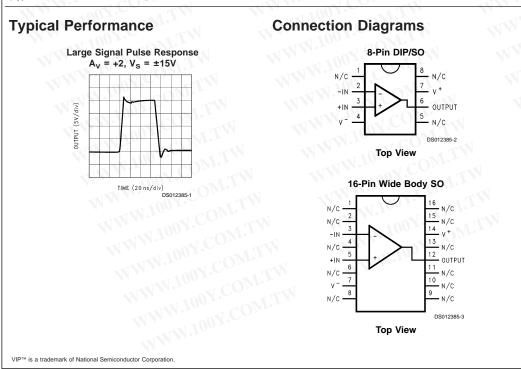
(Typical Unless Otherwise Noted)



- Very High Slew Rate: 4100V/µs
- Wide Unity-Gain Bandwidth: 200 MHz
- -3 dB Frequency @ A_V = +2: 220 MHz
- Low Supply Current: 6.5 mA
- High Open Loop Gain: 85 dB
- High Output Current: 100 mA
- Differential Gain and Phase: 0.01%, 0.02°
- Specified for ±15V and ±5V Operation

Applications

- HDSL and ADSL Drivers
- Multimedia Broadcast Systems
- Professional Video Cameras
- Video Amplifiers
- Copiers/Scanners/FaxHDTV Amplifiers
- Pulse Amplifiers and Peak Detectors
- CATV/Fiber Optics Signal Processing



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Ordering In	formation	WWW.	ONY.COM	NT.
Package	Temperature Ran	ge	Transport	NS
WT	Industrial –40°C to +85°C	Military –55°C to +125°C	Media	Drawin
8-Pin DIP	LM7171AIN, LM7171BIN	WW N	Rails	N08E
8-Pin CDIP	LM7171AMJ-QML LM7171AMJ-QMLV	5962-95536	Rails	J08A
10-Pin Ceramic SOIC	LM7171AMWG-QML LM7171AMWG-QMLV	5962-95536	Trays	WG10
8-Pin	LM7171AIM, LM7171BIM		Rails	M08A
Small Outline	LM7171AIMX, LM7171BIMX	M.I.T.	Tape and Reel	
16-Pin	LM7171AIWM, LM7171BIWM	WT.	Rails	M16E
Small Outline	LM7171AWMX, LM7171BWMX	Nr.	Tape and Reel	

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150°C

WWW.100Y.COM.TW WWW.100Y.COM.T Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

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ESD Tolerance (Note 2)	2.5 kV
Supply Voltage (V ⁺ -V ⁻)	36V
Differential Input Voltage (Note 11)	±10V
Output Short Circuit to Ground	
(Note 3)	Continuous
Storage Temperature Range	-65°C to +150°C

Maximum Junction Temperature (Note 4)

Operating Ratings (Note 1)

Supply Voltage	$5.5V \le V_S \le 36V$
Junction Temperature Range	
LM7171AI, LM7171BI	$-40^{\circ}C \le T_{J} \le +85^{\circ}C$
Thermal Resistance (θ_{JA})	
N Package, 8-Pin Molded DIP	108°C/W
M Package, 8-Pin Surface Mount	172°C/W
M Package, 16-Pin Surface Mount	95°C/W

±15V DC Electrical Characteristics

Unless otherwise specified, all limits guaranteed for $T_J = 25$ °C, V⁺ = +15V, V⁻ = -15V, V_{CM} = 0V, and R_L = 1 k Ω . Boldface limits apply at the temperature extremes

Symbol	Parameter	Conditions	Typ (Note 5)	LM7171AI Limit (Note 6)	LM7171BI Limit (Note 6)	Units
V _{os}	Input Offset Voltage	WWW.10	0.2	1	3 7	mV max
TC V _{os}	Input Offset Voltage Average Drift	WWW.	35	WTI	WW	µV/°C
I _B	Input Bias Current	N WWW	2.7	10 12	10 12	μA max
l _{os}	Input Offset Current	WW WW	0.1	4	4	μA max
R _{IN}	Input Resistance	Common Mode	40	TIM	N	MΩ
	WW.LOW COM	Differential Mode	3.3	1 COM	N.	
Ro	Open Loop Output Resistance	N WT	15	Y.COM.	WT	Ω
CMRR	Common Mode Rejection Ratio	$V_{CM} = \pm 10V$	105	85 80	75 70	dB min
PSRR	Power Supply Rejection Ratio	$V_{S} = \pm 15V$ to $\pm 5V$	90	85 80	75 70	dB min
V _{CM}	Input Common-Mode Voltage Range	CMRR > 60 dB	±13.35	1.100X.C	DM.TW	V
A _V	Large Signal Voltage Gain (Note 7)	$R_L = 1 k\Omega$	85	80 75	75 70	dB min
	WWW.100	R _L = 100Ω	81	75 70	70 66	dB min
Vo	Output Swing	$R_L = 1 k\Omega$	13.3	13 12.7	13 12.7	V min
	WWW.	100Y.COM.TW	-13.2	-13 -12.7	-13 - 12.7	V max
	WWW	R _L = 100Ω	11.8	10.5 9.5	10.5 9.5	V min
	WW	W.100 1. COM.1	-10.5	-9.5 -9	-9.5 -9	V max
	Output Current	Sourcing, $R_L = 100\Omega$	118	105	105	mA
	(Open Loop)	1007.	1.1	95	95	min
	(Note 8)	Sinking, $R_L = 100\Omega$	105	95 90	95 90	mA max

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WWW.100Y.COM	±15V DC Electrical Characteristics (Cor	

Unless otherwise specified, all limits guaranteed for $T_J = 25^{\circ}C$, V⁺ = +15V, V⁻ = -15V, V_{CM} = 0V, and R_L = 1 k Ω . Boldface limits apply at the temperature extremes

Symbol	Parameter	Conditions	Typ (Note 5)	LM7171AI Limit (Note 6)	LM7171BI Limit (Note 6)	Units
ONL	Output Current	Sourcing, $R_L = 100\Omega$	100	MW.	N.COM	mA
	(in Linear Region)	Sinking, $R_L = 100\Omega$	100	N.V.	NO2	
Isc	Output Short Circuit	Sourcing	140	AN.	001.	mA
	Current	Sinking	135	WW.		
Is	Supply Current	100Y. al.	6.5	8.5	8.5	mA
				9.5	9.5	max

±15V AC Electrical Characteristics

Symbol	Parameter	Conditions	Typ (Note 5)	LM7171AI Limit (Note 6)	LM7171BI Limit (Note 6)	Un
SR	Slew Rate (Note 9)	$A_V = +2, V_{IN} = 13 V_{PP}$	4100		.W.10	V/
11	N.CO.	$A_V = +2$, $V_{IN} = 10 V_{PP}$	3100			NOX.
W.10	Unity-Gain Bandwidth	TANK I C	200	6	NWW.	М
-11	-3 dB Frequency	$A_{V} = +2$	220			M
φ _m	Phase Margin	VIO	50	N	NN.	D
t _s	Settling Time (0.1%)	$A_{V} = -1, V_{O} = \pm 5V$ $R_{L} = 500\Omega$	42	W	WWW	r
t _p	Propagation Delay	$A_{V} = -2, V_{IN} = \pm 5V,$ $R_{L} = 500\Omega$	5	WT.	WW	n
AD	Differential Gain (Note 10)	WW	0.01	WT .		9
ф _D	Differential Phase (Note 10)	.W.I	0.02			D
NN.	Second Harmonic (Note 12)	f _{IN} = 10 kHz	-110	VT.I.	11	dl
	NW.10° CONL.	f _{IN} = 5 MHz	-75	New York	<	dE
N	Third Harmonic (Note 12)	f _{IN} = 10 kHz	-115	M.L		dE
	WWW.	f _{IN} = 5 MHz	-55	T	N	dE
e _n	Input-Referred Voltage Noise	f = 10 kHz	14	COM.T	N	<u>n</u> √F
i _n	Input-Referred Current Noise	f = 10 kHz	1.5	COM	LM	<u>p</u> √F

±5V DC Electrical Characteristics

100Y.COM. Unless otherwise specified, all limits guaranteed for $T_J = 25^{\circ}C$, $V^+ = +5V$, $V^- = -5V$, $V_{CM} = 0V$, and $R_L = 1 \text{ k}\Omega$. Boldface limits apply at the temperature extremes

Symbol	Parameter	Conditions	Typ (Note 5)	LM7171AI Limit (Note 6)	LM7171BI Limit (Note 6)	Units
V _{os} Input Offset Voltage	Input Offset Voltage	CONTRACT	0.3	1.5	3.5	mV
	W W 100	Y.C.		4	7	max
TC V_{OS}	Input Offset Voltage Average Drift	oY.COM.TW	35			µV/°C
I _B	Input Bias Current	0Y.C	3.3	10	10	μA
	WW.	v		12	12	max
los	Input Offset Current		0.1	4	4	μA

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WWW.100		lectrical Characteristics (Cor	
	Unless otherwise	specified, all limits guaranteed for $T_1 = 25^{\circ}C$	$V^+ = +5$

WWW.100

Unless otherwise specified, all limits guaranteed for T_J = 25°C, V⁺ = +5V, V⁻ = -5V, V_{CM} = 0V, and R_L = 1 k Ω . Boldface limits apply at the temperature extremes

Symbol	Parameter	Conditions	Typ (Note 5)	LM7171AI Limit (Note 6)	LM7171BI Limit (Note 6)	Units
-16	Nr.	WW. T COP	III	6	6	max
R _{IN}	Input Resistance	Common Mode	40		W.100	MΩ
	W	Differential Mode	3.3		1004	
Ro	Output Resistance	N.I.	15		NN.	Ω
CMRR	Common Mode	$V_{CM} = \pm 2.5 V$	104	80	70	dB
	Rejection Ratio	WWW.		75	65	min
PSRR	Power Supply	$V_{S} = \pm 15V$ to $\pm 5V$	90	85	75	dB
	Rejection Ratio	YOU YWY		80	70	min
V _{CM}	Input Common-Mode Voltage Range	CMRR > 60 dB	±3.2	W1	MMM.	100 ^Y .
Av	Large Signal Voltage	$R_{L} = 1 k\Omega$	78	75	70	dB
	Gain (Note 7)	- 10		70	65	min
		$R_L = 100\Omega$	76	72	68	dB
	.100 COM	NWW.		67	63	min
Vo	Output Swing	R _L = 1 kΩ	3.4	3.2	3.2	V
	W.100X.CO.M.T WW.100X.CO.M.T WW.100X.CO.M.	WWW W		3	3	min
		V	-3.4	-3.2	-3.2	V
		W W		-3	-3	max
		R _L = 100Ω	3.1	2.9	2.9	V
				2.8	2.8	min
	WW. ON.CO.	W WT	-3.0	-2.9	-2.9	V
	W.W.	M		-2.8	-2.8	max
4	Output Current	Sourcing, $R_L = 100\Omega$	31	29	29	mA
	(Open Loop) (Note 8)	Win W		28	28	min
	N.100	Sinking, $R_L = 100\Omega$	30	29	29	mA
	Yan WW	WTI		28	28	max
I _{sc}	Output Short Circuit	Sourcing	135	S.CO	N.	mA
	Current	Sinking	100	100 -	M.	
s	Supply Current	N.C.	6.2	8	8	mA
	V.100	L COM-		9	9	max

	AC Electrical Charact otherwise specified, T _J = 25°C, V ⁺ =		and $R_L = 1 k$	Ω.		
Symbol	Parameter	Conditions	Typ (Note 5)	LM7171AI Limit (Note 6)	LM7171BI Limit (Note 6)	Units
SR	Slew Rate (Note 9)	$A_V = +2, V_{IN} = 3.5 V_{PP}$	950	1	101.	V/µs
	Unity-Gain Bandwidth	COM-	125	NW.	N.CU	MHz
	-3 dB Frequency	A _V = +2	140	N.	100 -	MHz
φ _m	Phase Margin	1.001.00	57	AL.		Deg
t _s	Settling Time (0.1%)	$A_{V} = -1, V_{O} = \pm 1V,$ $R_{L} = 500\Omega$	56			ns
t _p	Propagation Delay	$A_{V} = -2, V_{IN} = \pm 1V,$ $R_{L} = 500\Omega$	6			ns
Ap	Differential Gain (Note 1)		0.02			%

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±5V	AC Electrical Charac	teristics (Continued)	WWW.IC WWW.IC WWW	胜华 胜华	将 刀 构 寺力电子(上 寺力电子(深 Http://ww	海) 86- 圳) 86-
Unless Symbol	otherwise specified, T _J = 25°C, V ⁺	$= +5V, V^{-} = -5V, V_{CM} = 0V$ Conditions	V, and R _L = 1 k Typ (Note 5)	Ω. LM7171AI Limit (Note 6)	LM7171BI Limit (Note 6)	Unit
φ _D	Differential Phase (Note 10)	Dr. N.I.	0.03	101		Deg
COM	Second Harmonic (Note 12)	f _{IN} = 10 kHz	-102		N	dBc
Mos	N.W.	f _{IN} = 5 MHz	-70	. WW.		dBc
	Third Harmonic (Note 12)	f _{IN} = 10 kHz	-110		001.	dBc
-1 COP	WWW WWW	f _{IN} = 5 MHz	51	WWW.	J.C.	dBc
e _n	Input-Referred Voltage Noise	f = 10 kHz	14	WWW	.100Y.C	nV √Hz
i _n C	Input-Referred Current Noise	f = 10 kHz	1.8	MM	N.100Y	pA √Hz

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications and the test conditions, see the Electrical Characteristics. Note 2: Human body model, 1.5 kΩ in series with 100 pF.

Note 3: Applies to both single-supply and split-supply operation. Continuous short circuit operation at elevated ambient temperature can result in exceeding the maximum allowed junction temperature of 150°C.

Note 4: The maximum power dissipation is a function of $T_{J(max)}$, θ_{JA} , and T_A . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(max)} - T_A)/\theta_{JA}$. All numbers apply for packages soldered directly into a PC board.

Note 5: Typifcal values represent the most likely parametric norm.

Note 6: All limits are guaranteed by testing or statistical analysis.

Note 7: Large signal voltage gain is the total output swing divided by the input signal required to produce that swing. For $V_S = \pm 15V$, $V_{OUT} = \pm 5V$. For $V_S = \pm 5V$, $V_{OUT} = \pm 1V$.

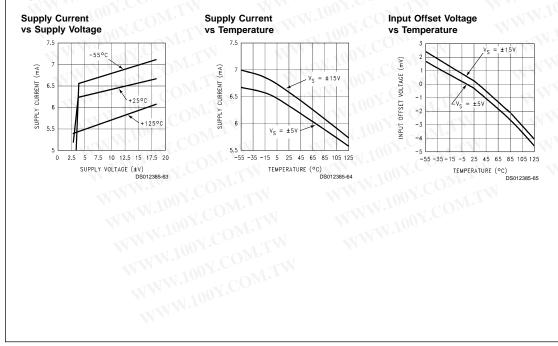
Note 8: The open loop output current is guaranteed, by the measurement of the open loop output voltage swing, using 100Ω output load.

Note 9: Slew Rate is the average of the raising and falling slew rates.

Note 10: Differential gain and phase are measured with $A_V = +2$, $V_{IN} = 1$ V_{PP} at 3.58 MHz and both input and output 75 Ω terminated. Note 11: Input differential voltage is applied at $V_S = \pm 15V$.

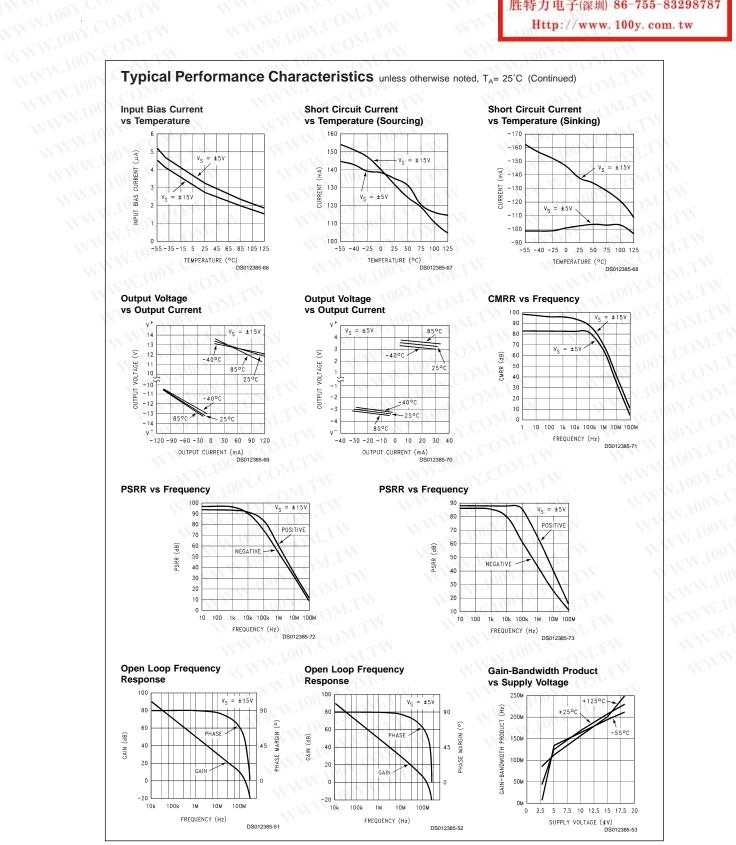
Note 12: Harmonics are measured with $V_{IN} = 1 V_{PP}$, $A_V = +2$ and $R_L = 100\Omega$.

Typical Performance Characteristics unless otherwise noted, TA= 25°C

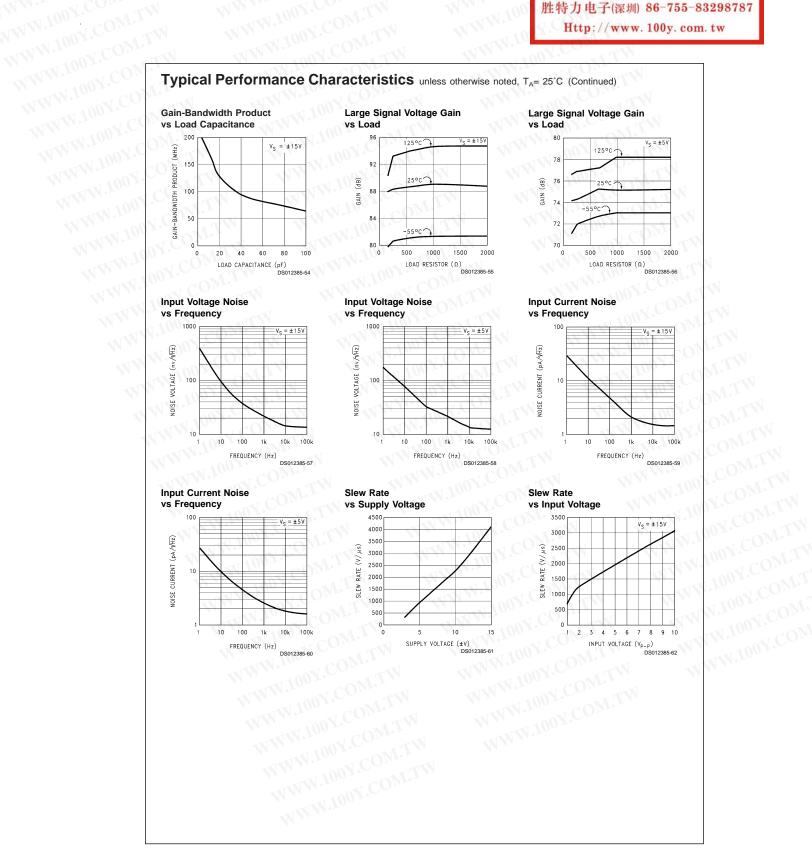


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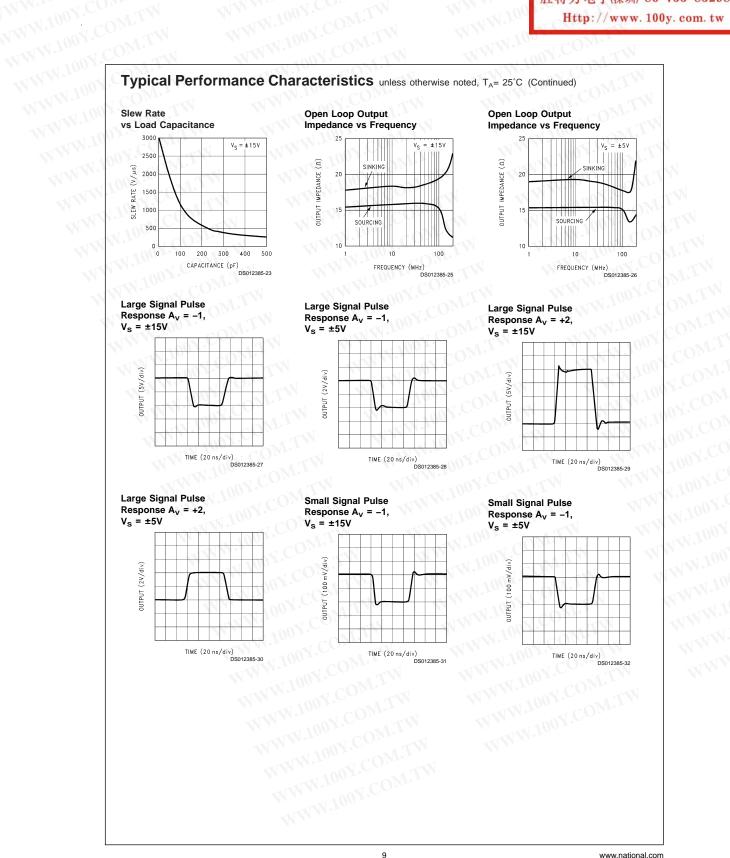
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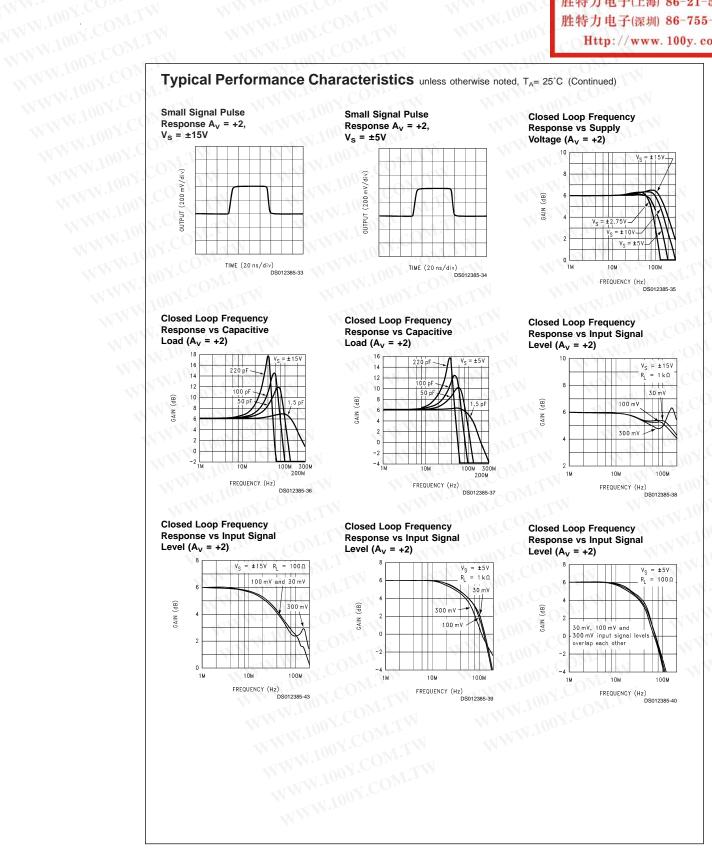


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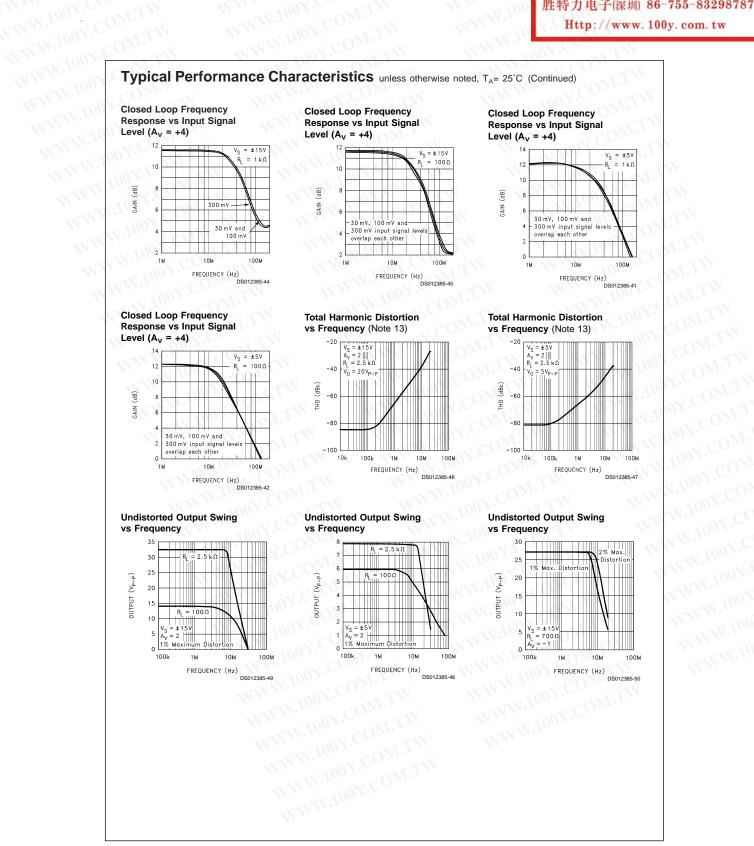


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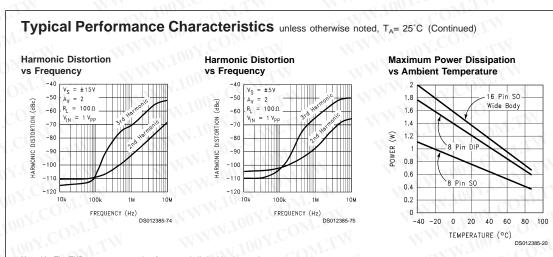
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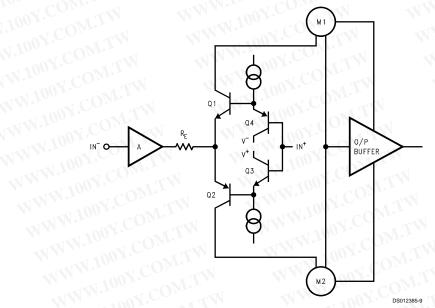


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Note 13: The THD measurement at low frequency is limited by the test instrument.

Simplified Schematic Diagram



Note: M1 and M2 are current mirrors.

Application Notes

LM7171 Performance Discussion

The LM7171 is a very high speed, voltage feedback amplifier. It consumes only 6.5 mA supply current while providing a unity-gain bandwidth of 200 MHz and a slew rate of 4100V/ μ s. It also has other great features such as low differential gain and phase and high output current.

The LM7171 is a true voltage feedback amplifier. Unlike current feedback amplifiers (CFAs) with a low inverting input impedance and a high non-inverting input impedance, both inputs of voltage feedback amplifiers (VFAs) have high impedance nodes. The low impedance inverting input in CFAs and a feedback capacitor create an additional pole that will lead to instability. As a result, CFAs cannot be used in traditional op amp circuits such as photodiode amplifiers, I-to-V converters and integrators where a feedback capacitor is required.

LM7171 Circuit Operation

The class AB input stage in LM7171 is fully symmetrical and has a similar slewing characteristic to the current feedback amplifiers. In the LM7171 Simplified Schematic, Q1 through Q4 form the equivalent of the current feedback input buffer, R_F the equivalent of the feedback resistor, and stage A buff-

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LM7171 Circuit Operation (Continued)

ers the inverting input. The triple-buffered output stage isolates the gain stage from the load to provide low output impedance.

LM7171 Slew Rate Characteristic

The slew rate of LM7171 is determined by the current available to charge and discharge an internal high impedance node capacitor. This current is the differential input voltage divided by the total degeneration resistor $R_{\rm E}$. Therefore, the slew rate is proportional to the input voltage level, and the higher slew rates are achievable in the lower gain configurations. A curve of slew rate versus input voltage level is provided in the "Typical Performance Characteristics".

When a very fast large signal pulse is applied to the input of an amplifier, some overshoot or undershoot occurs. By placing an external resistor such as 1 k Ω in series with the input of LM7171, the bandwidth is reduced to help lower the overshoot.

Slew Rate Limitation

If the amplifier's input signal has too large of an amplitude at too high of a frequency, the amplifier is said to be slew rate limited; this can cause ringing in time domain and peaking in frequency domain at the output of the amplifier.

In the "Typical Performance Characteristics" section, there are several curves of $A_v = +2$ and $A_v = +4$ versus input signal levels. For the $A_v = +4$ curves, no peaking is present and the LM7171 responds identically to the different input signal levels of 30 mV, 100 mV and 300 mV.

For the $A_V = +2$ curves, with slight peaking occurs. This peaking at high frequency (>100 MHz) is caused by a large input signal at high enough frequency that exceeds the amplifier's slew rate. The peaking in frequency response does not limit the pulse response in time domain, and the LM7171 is stable with noise gain of ≥+2.

Layout Consideration

PRINTED CIRCUIT BOARDS AND HIGH SPEED OP AMPS

There are many things to consider when designing PC boards for high speed op amps. Without proper caution, it is very easy to have excessive ringing, oscillation and other degraded AC performance in high speed circuits. As a rule, the signal traces should be short and wide to provide low inductance and low impedance paths. Any unused board space needs to be grounded to reduce stray signal pickup. Critical components should also be grounded at a common point to eliminate voltage drop. Sockets add capacitance to the board and can affect high frequency performance. It is better to solder the amplifier directly into the PC board without using any socket.

USING PROBES

Active (FET) probes are ideal for taking high frequency measurements because they have wide bandwidth, high input impedance and low input capacitance. However, the probe ground leads provide a long ground loop that will produce errors in measurement. Instead, the probes can be grounded directly by removing the ground leads and probe jackets and using scope probe jacks.

COMPONENT SELECTION AND FEEDBACK RESISTOR

It is important in high speed applications to keep all component leads short. For discrete components, choose carbon composition-type resistors and mica-type capacitors. Surface mount components are preferred over discrete components for minimum inductive effect.

Large values of feedback resistors can couple with parasitic capacitance and cause undesirable effects such as ringing or oscillation in high speed amplifiers. For LM7171, a feedback resistor of 510Ω gives optimal performance.

Compensation for Input Capacitance

The combination of an amplifier's input capacitance with the gain setting resistors adds a pole that can cause peaking or oscillation. To solve this problem, a feedback capacitor with a value



can be used to cancel that pole. For LM7171, a feedback capacitor of 2 pF is recommended. *Figure 1* illustrates the compensation circuit.

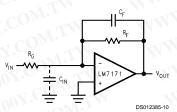


FIGURE 1. Compensating for Input Capacitance

Power Supply Bypassing

Bypassing the power supply is necessary to maintain low power supply impedance across frequency. Both positive and negative power supplies should be bypassed individually by placing 0.01 μF ceramic capacitors directly to power supply pins and 2.2 μF tantalum capacitors close to the power supply pins.

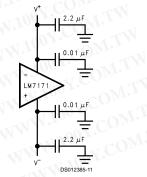


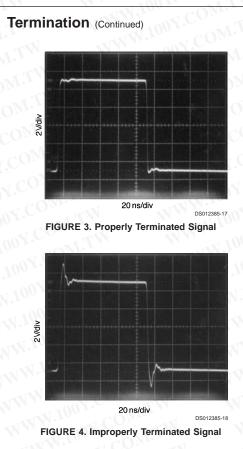
FIGURE 2. Power Supply Bypassing

Termination

In high frequency applications, reflections occur if signals are not properly terminated. *Figure 3* shows a properly terminated signal while *Figure 4* shows an improperly terminated signal.

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To minimize reflection, coaxial cable with matching characteristic impedance to the signal source should be used. The other end of the cable should be terminated with the same value terminator or resistor. For the commonly used cables, RG59 has 75Ω characteristic impedance, and RG58 has 50Ω characteristic impedance.

Driving Capacitive Loads

Amplifiers driving capacitive loads can oscillate or have ringing at the output. To eliminate oscillation or reduce ringing, an isolation resistor can be placed as shown below in *Figure* 5 The combination of the isolation resistor and the load capacitor forms a pole to increase stability by adding more phase margin to the overall system. The desired performance depends on the value of the isolation resistor; the bigger the isolation resistor, the more damped the pulse response becomes. For LM7171, a 50 Ω isolation resistor is recommended for initial evaluation. *Figure* 6 shows the LM7171 driving a 150 pF load with the 50 Ω isolation resistor.

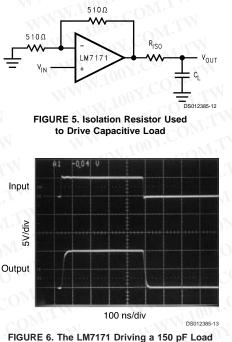


FIGURE 6. The LM7171 Driving a 150 pF Load with a 50 Ω Isolation Resistor

Power Dissipation

The maximum power allowed to dissipate in a device is defined as: $P_D = (T_{J(max)} - T_A)/\theta_{JA}$

Where

PD

is the power dissipation in a device

 $T_{J(max)}$ is the maximum junction temperature

T_A is the ambient temperature

 θ_{JA} is the thermal resistance of a particular package For example, for the LM7171 in a SO-8 package, the maximum power dissipation at 25°C ambient temperature is 730 mW.

Thermal resistance, θ_{JA} , depends on parameters such as die size, package size and package material. The smaller the die size and package, the higher θ_{JA} becomes. The 8-pin DIP package has a lower thermal resistance (108°C/W) than that of 8-pin SO (172°C/W). Therefore, for higher dissipation capability, use an 8-pin DIP package.

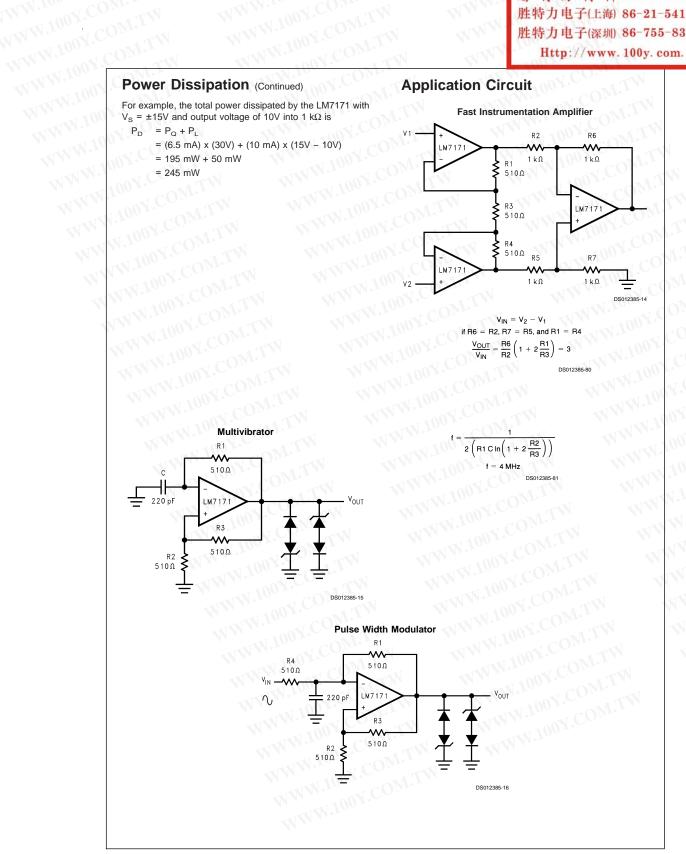
The total power dissipated in a device can be calculated as:

$$P_D = P_Q + P_L$$

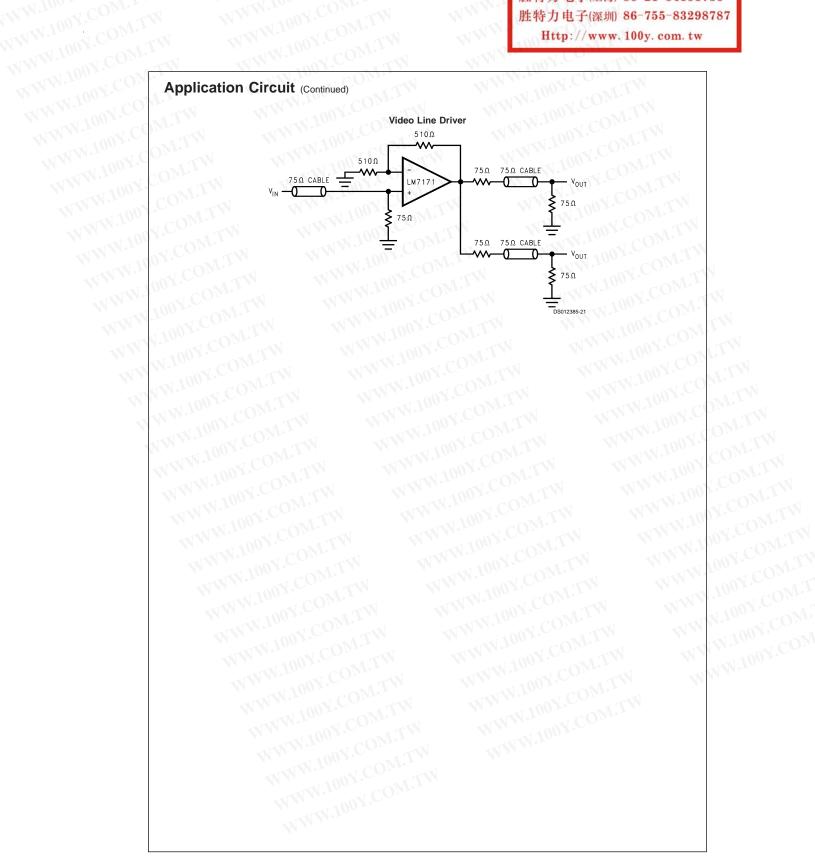
 P_Q is the quiescent power dissipated in a device with no load connected at the output. P_L is the power dissipated in the device with a load connected at the output; it is not the power dissipated by the load.

Furthermore,

- P_Q: = supply current x total supply voltage with no load
- P_L: = output current x (voltage difference between supply voltage and output voltage of the same side of supply voltage)



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A design kit is available for the LM7171. The design kit contains:

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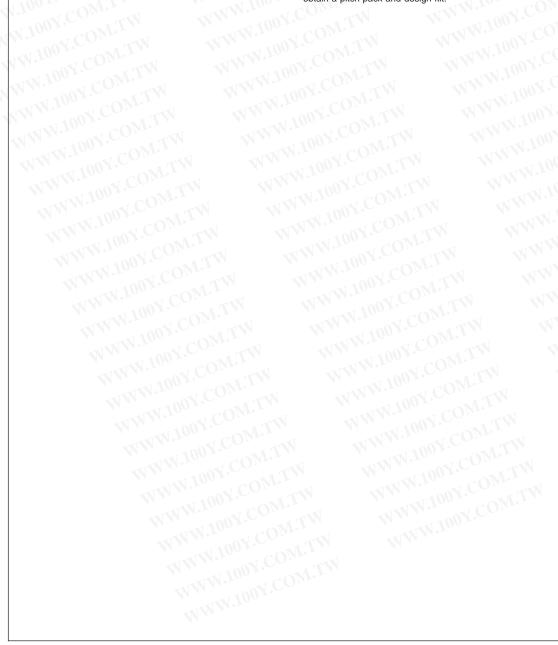
- High Speed Evaluation Board
- LM7171 in 8-pin DIP Package
- LM7171 Datasheet
- Pspice Macromodel DIskette With The LM7171 Macromodel
- Amplifier Selection Guide

Pitch Pack

A pitch pack is available for the LM7171. The pitch pack contains:

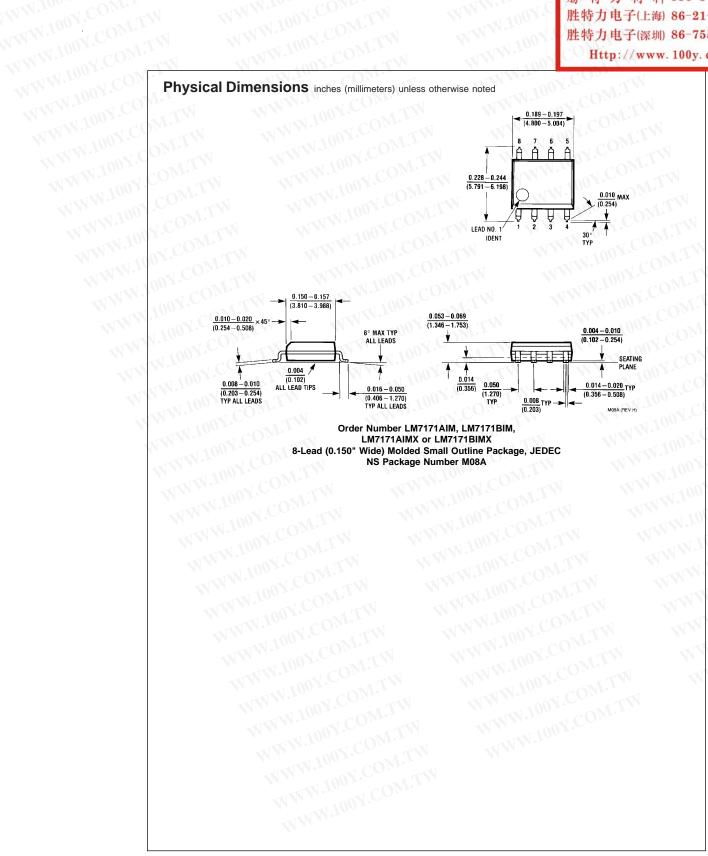
- LM7171 in 8-pin DIP Package
- LM7171 Datasheet
- Pspice Macromodel DIskette With The LM7171 Macromodel
- Amplifier Selection Guide

Contact your local National Semiconductor sales office to obtain a pitch pack and design kit.



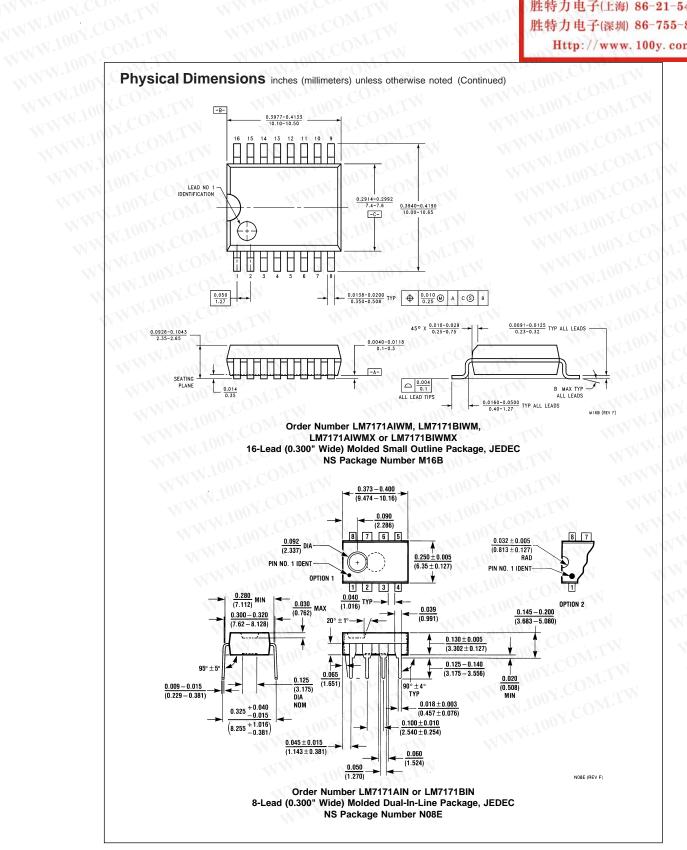
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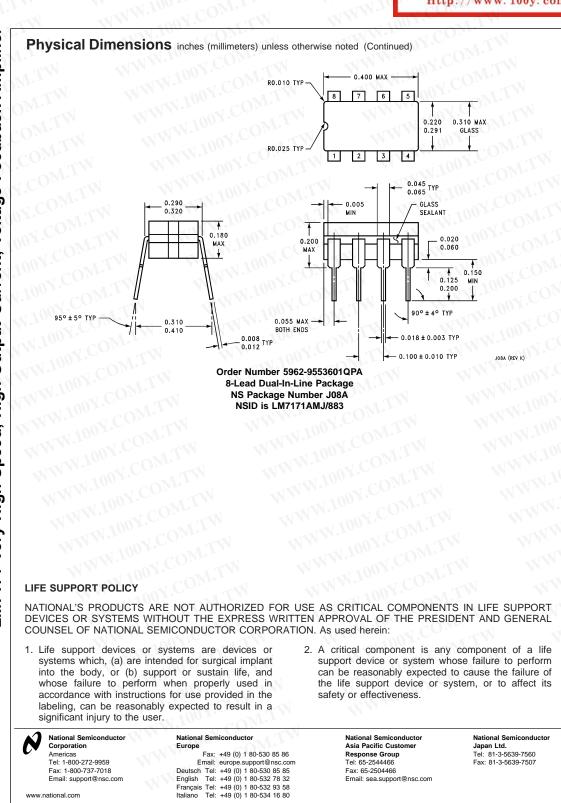


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