

## Overview of Speed Controllers

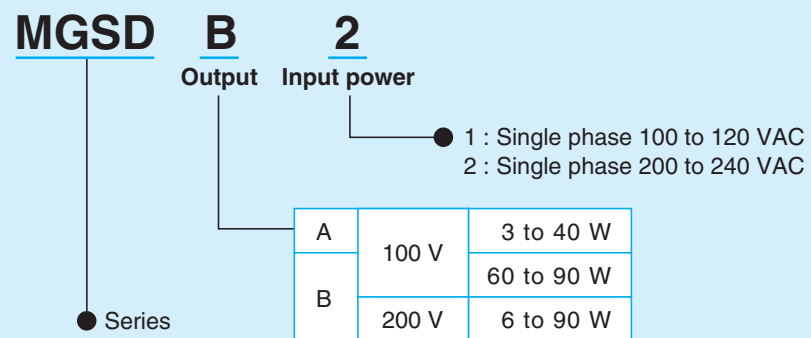
- These controllers vary speed of compact geared motors.
- The lineup of the speed controllers is divided into the following 4 types to meet various applications and configuration.

- 1. Separate type speed controller** Speed controller of the basic configuration
- 2. 48 mm sq. (1.89 inch sq.) speed controller** Separate speed controller housed in 48 mm sq. (1.89 inch sq.) DIN size
- 3. Unit type speed controller** A set of a motor and speed controller: Both can be connected through a single-touch connector.
- 4. Inverter** Speed controller for 3-phase motor

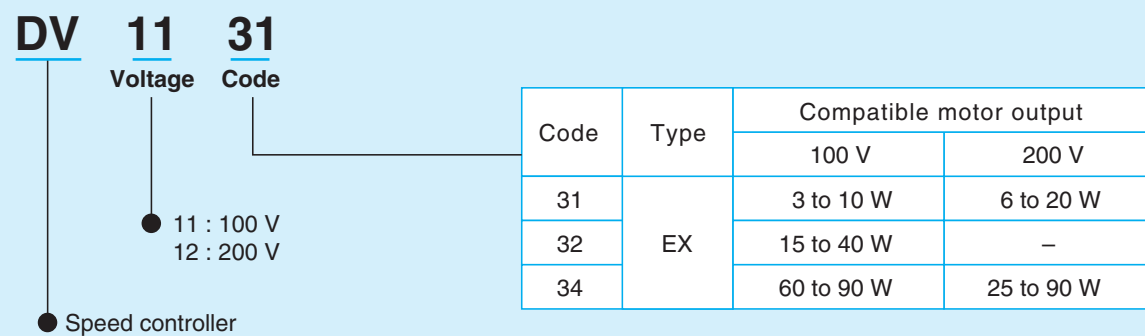
## Product designation

- Separate type speed controller

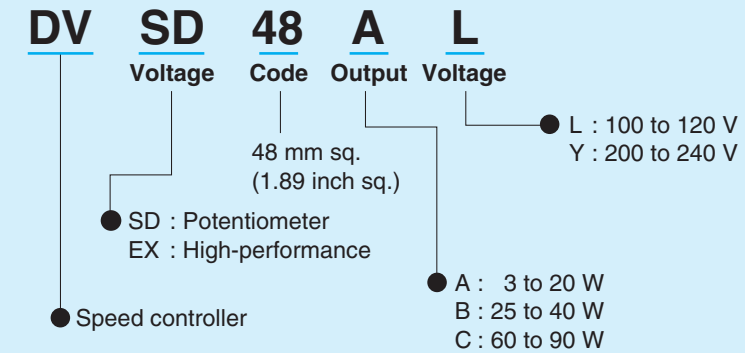
### • MGSD type



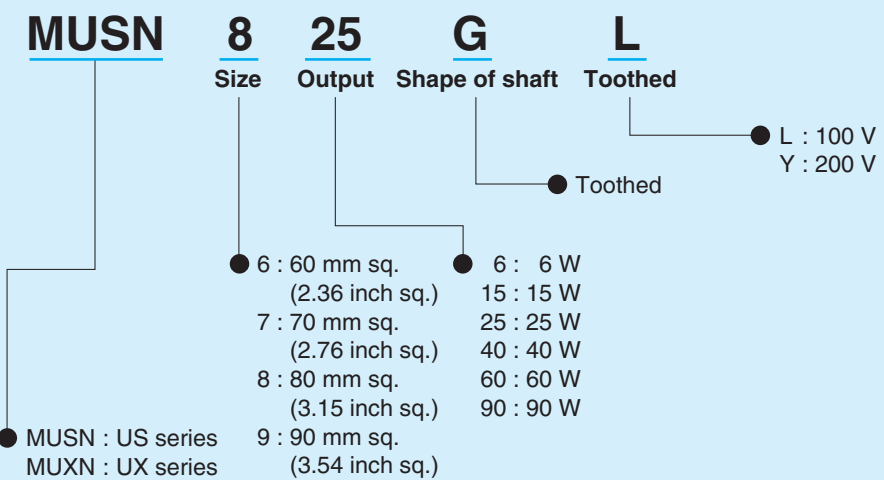
### • EX type



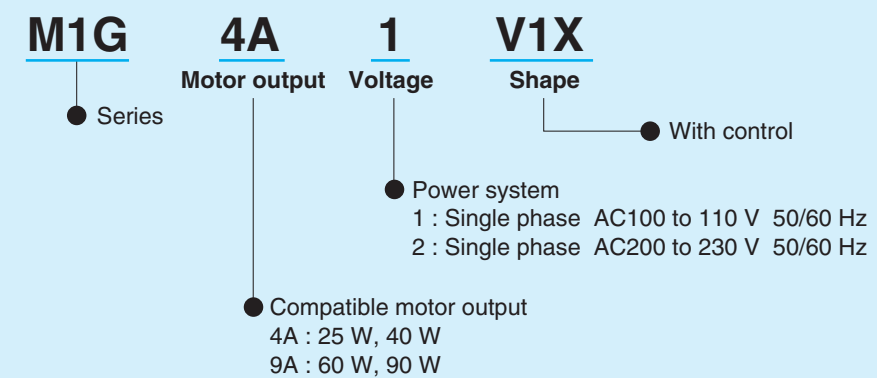
### • 48 mm sq. (1.89 inch sq.) speed controller



### • Unit type speed controller



### • Inverter



# Speed controller

勝特力材料 886-3-5753170  
 勝特力电子(上海) 86-21-54151736  
 勝特力电子(深圳) 86-755-83298787  
[Http://www.100y.com.tw](http://www.100y.com.tw)

## • Possible combination of speed controller and motor

Size	Output (W)	Motor		Voltage (V)	Speed controller			
		Certified	Part No.		MGSD type	EX type	SD48 type	EX48 type
60 mm sq. (2.36 inch sq.)	3	-----	M61X3GV4L	100	MGSDA1 ★	DV1131	DVSD48AL	DVEX48AL
		-----	M61X6GV4L	100	MGSDA1 ★	DV1131	DVSD48AL	DVEX48AL
	6	-----	M61X6GV4Y	200	MGSDB2 ★	DV1231	DVSD48AY	DVEX48AY
		★	M61X6GV4LG(A)	100	MGSDA1 ★	-----	-----	-----
		★	M61X6GV4DG(A)	110/115	MGSDA1 ★	-----	-----	-----
		★	M61X6GV4YG(A)	200	MGSDB2 ★	-----	-----	-----
		★	M61X6GV4GG(A)	220/230	MGSDB2 ★	-----	-----	-----
70 mm sq. (2.76 inch sq.)	10	-----	M71X10GV4L	100	MGSDA1 ★	DV1131	DVSD48AL	DVEX48AL
		-----	M71X10GV4Y	200	MGSDB2 ★	DV1231	DVSD48AY	DVEX48AY
	15	-----	M71X15GV4L	100	MGSDA1 ★	DV1132	DVSD48AL	DVEX48AL
		-----	M71X15GV4Y	200	MGSDB2 ★	DV1231	DVSD48AY	DVEX48AY
		★	M71X15GV4LG(A)	100	MGSDA1 ★	-----	-----	-----
		★	M71X15GV4DG(A)	110/115	MGSDA1 ★	-----	-----	-----
		★	M71X15GV4YG(A)	200	MGSDB2 ★	-----	-----	-----
★	M71X15GV4GG(A)	220/230	MGSDB2 ★	-----	-----	-----		
80 mm sq. (3.15 inch sq.)	15	-----	M81X15GV4L	100	MGSDA1 ★	DV1132	DVSD48AL	DVEX48AL
		-----	M81X15GV4Y	200	MGSDB2 ★	DV1231	DVSD48AY	DVEX48AY
	25	-----	M81X25GV4L	100	MGSDA1 ★	DV1132	DVSD48BL	DVEX48BL
		-----	M81X25GV4Y	200	MGSDB2 ★	DV1234	DVSD48BY	DVEX48BY
		★	M81X25GV4LG(A)	100	MGSDA1 ★	-----	-----	-----
		★	M81X25GV4DG(A)	110/115	MGSDA1 ★	-----	-----	-----
		★	M81X25GV4YG(A)	200	MGSDB2 ★	-----	-----	-----
★	M81X25GV4GG(A)	220/230	MGSDB2 ★	-----	-----	-----		
90 mm sq. (3.54 inch sq.)	40	-----	M91X40GV4L	100	MGSDA1 ★	DV1132	DVSD48BL	DVEX48BL
		-----	M91X40GV4Y	200	MGSDB2 ★	DV1234	DVSD48BY	DVEX48BY
		★	M91X40GV4LG(A)	100	MGSDA1 ★	-----	-----	-----
		★	M91X40GV4DG(A)	110/115	MGSDA1 ★	-----	-----	-----
		★	M91X40GV4YG(A)	200	MGSDB2 ★	-----	-----	-----
	★	M91X40GV4GG(A)	220/230	MGSDB2 ★	-----	-----	-----	
	60	-----	M91Z60GV4L	100	MGSDB1 ★	DV1134	DVSD48CL	DVEX48CL
-----		M91Z60GV4Y	200	MGSDB2 ★	DV1234	DVSD48CY	DVEX48CY	
★		M91Z60GV4LG(A)	100	MGSDB1 ★	-----	-----	-----	
★		M91Z60GV4DG(A)	110/115	MGSDB1 ★	-----	-----	-----	
★		M91Z60GV4YG(A)	200	MGSDB2 ★	-----	-----	-----	
90	-----	M91Z90GV4L	100	MGSDB1 ★	DV1134	DVSD48CL	DVEX48CL	
	-----	M91Z90GV4Y	200	MGSDB2 ★	DV1234	DVSD48CY	DVEX48CY	
	★	M91Z90GV4LG(A)	100	MGSDB1 ★	-----	-----	-----	
	★	M91Z90GV4DG(A)	110/115	MGSDB1 ★	-----	-----	-----	
	★	M91Z90GV4YG(A)	200	MGSDB2 ★	-----	-----	-----	
★	M91Z90GV4GG(A)	220/230	MGSDB2 ★	-----	-----	-----		

\* When using a speed controller operative under a wide range of supply voltage (MGSD, SD48, EX48), the mating motor should be selected according to the voltage of the power supply to be used.

★ Conforming to international standards : CE

★ MGSD speed controllers are compliant with and CE.

\* The models with a motor model number to which "A" is suffixed are not equipped with a capacitor cap. The models with a motor model number to which "A" is suffixed are not sold or available in Japan.

\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

Size	Output (W)	Motor		Voltage (V)	Speed controller			
		Certified	Part No.		MGSD type	EX type	SD48 type	EX48 type
60 mm sq. (2.36 inch sq.)	3	-----	M6RX4GV4L	100	MGSDA1 ★	DV1131	DVSD48AL	DVEX48AL
		-----	M6RX6GV4L	100	MGSDA1 ★	DV1131	DVSD48AL	DVEX48AL
	6	-----	M6RX6GV4Y	200	MGSDB2 ★	DV1231	DVSD48AY	DVEX48AY
		★	M6RX6GV4LG(A)	100	MGSDA1 ★	-----	-----	-----
		★	M6RX6GV4DG(A)	110/115	MGSDA1 ★	-----	-----	-----
		★	M6RX6GV4YG(A)	200	MGSDB2 ★	-----	-----	-----
		★	M6RX6GV4GG(A)	220/230	MGSDB2 ★	-----	-----	-----
70 mm sq. (2.76 inch sq.)	10	-----	M7RX10GV4L	100	MGSDA1 ★	DV1131	DVSD48AL	DVEX48AL
		-----	M7RX10GV4Y	200	MGSDB2 ★	DV1231	DVSD48AY	DVEX48AY
	15	-----	M7RX15GV4L	100	MGSDA1 ★	DV1132	DVSD48AL	DVEX48AL
		-----	M7RX15GV4Y	200	MGSDB2 ★	DV1231	DVSD48AY	DVEX48AY
		★	M7RX15GV4LG(A)	100	MGSDA1 ★	-----	-----	-----
		★	M7RX15GV4DG(A)	110/115	MGSDA1 ★	-----	-----	-----
		★	M7RX15GV4YG(A)	200	MGSDB2 ★	-----	-----	-----
★	M7RX15GV4GG(A)	220/230	MGSDB2 ★	-----	-----	-----		
80 mm sq. (3.15 inch sq.)	15	-----	M8RX20GV4L	100	MGSDA1 ★	DV1132	DVSD48AL	DVEX48AL
		-----	M8RX20GV4Y	200	MGSDB2 ★	DV1231	DVSD48AY	DVEX48AY
	25	-----	M8RX25GV4L	100	MGSDA1 ★	DV1132	DVSD48BL	DVEX48BL
		-----	M8RX25GV4Y	200	MGSDB2 ★	DV1234	DVSD48BY	DVEX48BY
		★	M8RX25GV4LG(A)	100	MGSDA1 ★	-----	-----	-----
		★	M8RX25GV4DG(A)	110/115	MGSDA1 ★	-----	-----	-----
		★	M8RX25GV4YG(A)	200	MGSDB2 ★	-----	-----	-----
★	M8RX25GV4GG(A)	220/230	MGSDB2 ★	-----	-----	-----		
90 mm sq. (3.54 inch sq.)	40	-----	M9RX40GV4L	100	MGSDA1 ★	DV1132	DVSD48BL	DVEX48BL
		-----	M9RX40GV4Y	200	MGSDB2 ★	DV1234	DVSD48BY	DVEX48BY
		★	M9RX40GV4LG(A)	100	MGSDA1 ★	-----	-----	-----
		★	M9RX40GV4DG(A)	110/115	MGSDA1 ★	-----	-----	-----
		★	M9RX40GV4YG(A)	200	MGSDB2 ★	-----	-----	-----
	★	M9RX40GV4GG(A)	220/230	MGSDB2 ★	-----	-----	-----	
	60	-----	M9RZ60GV4L	100	MGSDB1 ★	DV1134	DVSD48CL	DVEX48CL
-----		M9RZ60GV4Y	200	MGSDB2 ★	DV1234	DVSD48CY	DVEX48CY	
★		M9RZ60GV4LG(A)	100	MGSDB1 ★	-----	-----	-----	
★		M9RZ60GV4DG(A)	110/115	MGSDB1 ★	-----	-----	-----	
★		M9RZ60GV4YG(A)	200	MGSDB2 ★	-----	-----	-----	
★	M9RZ60GV4GG(A)	220/230	MGSDB2 ★	-----	-----	-----		
Variable speed motor with electromagnetic brake	60 mm sq. (2.36 inch sq.)	-----	M6RX6GBV4L	100	MGSDA1 ★	DV1131	DVSD48AL	DVEX48AL
		-----	M6RX6GBV4Y	200	MGSDB2 ★	DV1231	DVSD48AY	DVEX48AY
	70 mm sq. (2.76 inch sq.)	-----	M7RX15GBV4L	100	MGSDA1 ★	DV1132	DVSD48AL	DVEX48AL
		-----	M7RX15GBV4Y	200	MGSDB2 ★	DV1231	DVSD48AY	DVEX48AY
	80 mm sq. (3.15 inch sq.)	-----	M8RX25GBV4L	100	MGSDA1 ★	DV1132	DVSD48BL	DVEX48BL
-----		M8RX25GBV4Y	200	MGSDB2 ★	DV1234	DVSD48BY	DVEX48BY	
90 mm sq. (3.54 inch sq.)	-----	M9RX40GBV4L	100	MGSDA1 ★	DV1132	DVSD48BL	DVEX48BL	
	-----	M9RX40GBV4Y	200	MGSDB2 ★	DV1234	DVSD48BY	DVEX48BY	

\* When using a speed controller operative under a wide range of supply voltage (MGSD, SD48, EX48), the mating motor should be selected according to the voltage of the power supply to be used.

★ Conforming to international standards : CE ★ MGSD speed controllers are compliant with and CE.

\* The models with a motor model number to which "A" is suffixed are not equipped with a capacitor cap. The models with a motor model number to which "A" is suffixed are not sold or available in Japan.

\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

Speed controller

Brake Unit

Options

Index



MGSD type



EX type

## • Features

### <MGSD type>

- Internal speed changer  
Motor speed can be adjusted from the speed setting knob on the front panel.  
Not necessary to install and connect an external speed changer to the controller.
- Electric brake enables instantaneous stop.
- Compact 8P plug-in configuration.
- Variable installation options are available.  
Terminal blocks, sockets and other various options (from Matsushita Electric Works, Ltd.) for panel board can be used.
- Compliant with international standards:

### <EX type>

- Soft-start/soft-down  
Time can be adjusted up to 5 seconds.  
Excellent soft-start/soft-down linearity.
- Selectable response  
High-stable and high-response can be selected with the internal changeover switch to meet the characteristic of the application.  
(Factory setting: high-response)
- Excellent instantaneous stop capability
- Parallel operation  
Two or more motors can be controlled from a single control knob.
- Can link with various control systems  
Can control motor(s) in conjunction with different controlling systems such as sequencer. The voltage signal can also be used as control signal.

## • Standard specification (EX type)

Characteristic	Part No.	EX type				
		DV1131	DV1132	DV1134	DV1231	DV1234
Rated voltage		Single phase 100 VAC			Single phase 200 VAC	
Operating voltage range		±10% (at rated voltage)				
Power frequency		50/60 Hz				
Rated current		0.4 A	1 A	2.0 A	0.3 A	1 A
Compatible motor output *1		3 to 10 W	15 to 40 W	60 to 0 W	6 to 20 W	25 to 90 W
Operation change		High-response			High-stability	
Speed control range		90 to 1400 min <sup>-1</sup> / 90 to 1700 min <sup>-1</sup>		50 to 1400 min <sup>-1</sup> / 50 to 1700 min <sup>-1</sup>		
Speed variation		5% or more			3% or less	
Speed setting		From external controller, e.g. external speed changer *3				
Braking*2		Active while electric braking current is flowing.				
Electric braking time		5 sec typ. The braking current will be turned off before the 5-second limit as the motor stops. (Braking current is 2 to 3 times the rated current.)				
Parallel operation		Enabled				
Soft-start/soft-down capability		Available (typically up to 5 sec (0 to max. speed))				
Operating temperature range		-10 to 50°C				
Storage temperature		-20 to 60°C				

\*1 Applicable to Matsushita compact speed variable geared motors. Select motors with applicable output.

\*2 Electric braking has no mechanical brake holding mechanism.

To provide brake holding, use our C&B motor or variable speed motor containing electromagnetic brake.

When braking a load having excessively high inertia, durability and life expectancy of motor shaft and gear should be taken into consideration. Use the motor within the allowable inertia.

\*3 EX type is supplied with the external speed changer.

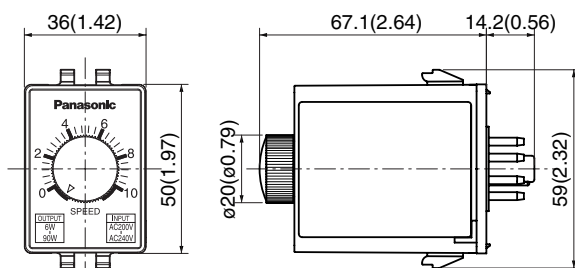
## • Standard specification (MGSD type)

	MGSDA1	MGSDB1	MGSDB2
Supply voltage	Single phase 100 to 120 VAC		Single phase 200 to 240 VAC
Supply voltage tolerance	±10% (at rated voltage)		
Power frequency	50/60 Hz		
Rated input current	1.0 A	2.0 A	1.0 A
Compatible motor output	3 to 40 W	60 to 90 W	6 to 90 W
Speed control range	50Hz : 90 to 1400 min <sup>-1</sup> 60Hz : 90 to 1700 min <sup>-1</sup>		
Speed regulation (against load)	5% : 1000 min <sup>-1</sup> , Typical variation at 80% rated torque		
Speed setting	Internal		
Braking *1	Activated while electric braking current is flowing.		
Electric braking time	0.5 sec (typ.): Amount of braking current is 2 to 3 times the rated current.		
Parallel operation	Not applicable		
Product weight	80 g		

\*1 Electric braking has no mechanical holding mechanism.

## • Outline drawing

### MGSD type

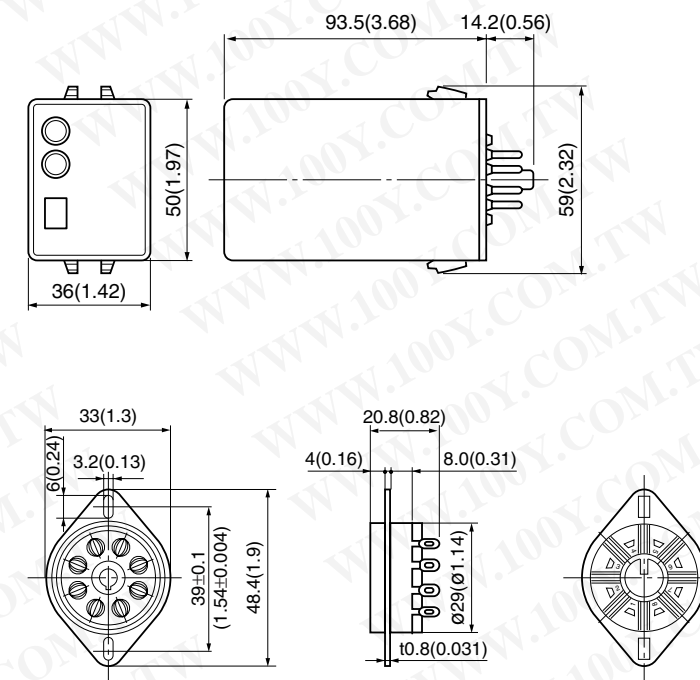


Socket is not supplied with the product.  
Use octal pin socket (DV0P4560), option,  
or Socket (AW68102) recommended by  
Matsushita Electric Works, Ltd.

Unit: mm (inch)

## • Outline drawing

### EX type



Socket (accessory)

Unit: mm (inch)

\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

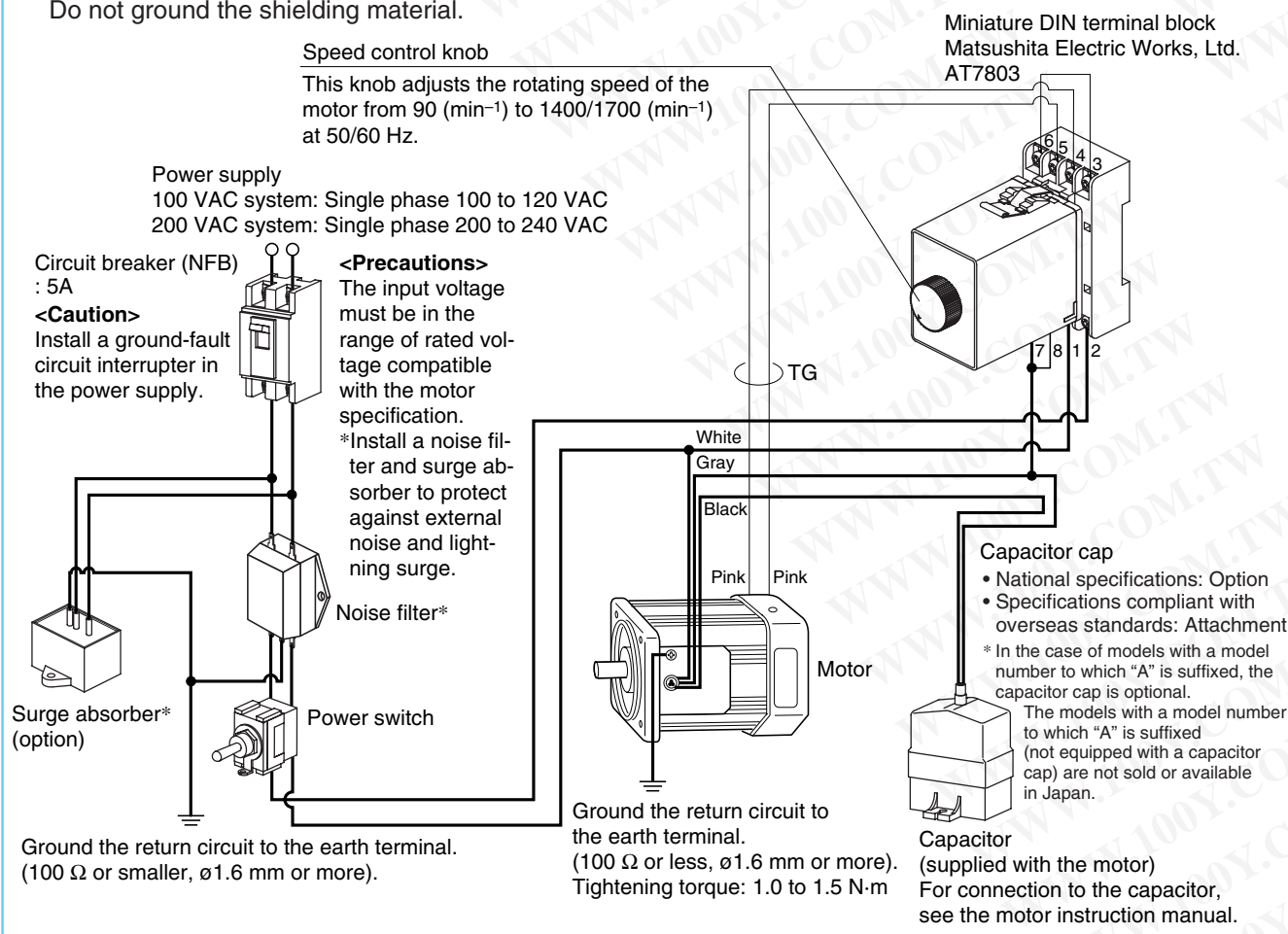
\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

## • Connection diagram list

Connection diagram	Function	Speed controller	Page
1	Wiring diagram (for unidirectional rotation)	MGSD type	C- 8
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6	Wiring to electromagnetic brake (40 W or smaller)	MGSD type	C-12
7	Wiring diagram (for unidirectional rotation)	EX type	C-13
8	Speed change only	EX type	C-14
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17	Wiring of cooling fan motor (F) and motor with thermal protector (TP)	EX type	C-20
18	Wiring to electromagnetic brake	EX type	C-20

## 1 Wiring diagram (for unidirectional rotation)

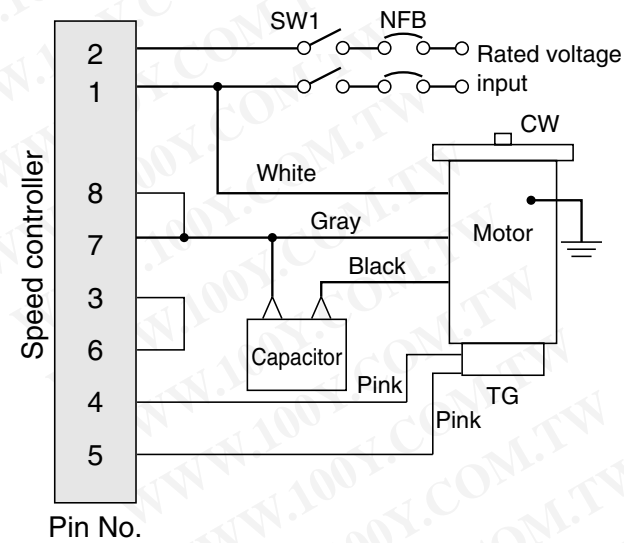
- The motor revolving speed can be set from the speed setting knob on the panel.
  - The thick continuous lines represent main circuit. Use conductor of size 0.75 mm<sup>2</sup> or larger for the main line.
  - The thin continuous lines represent signal circuit. Use conductor of size 0.3 mm<sup>2</sup> or larger in the signal circuit.
- When the distance from the tachometer generator (TG) is long, use shielded twisted pair cable.  
 Do not ground the shielding material.



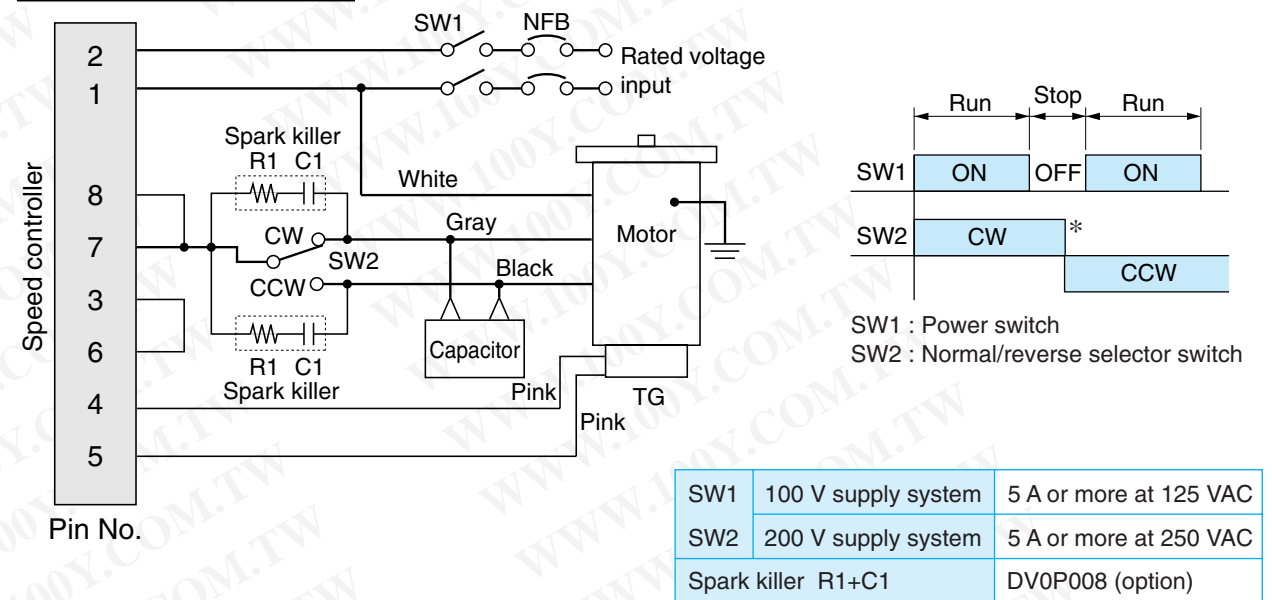
\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

## 2 Speed change only

### Unidirectional rotation



### Normal/reverse rotation



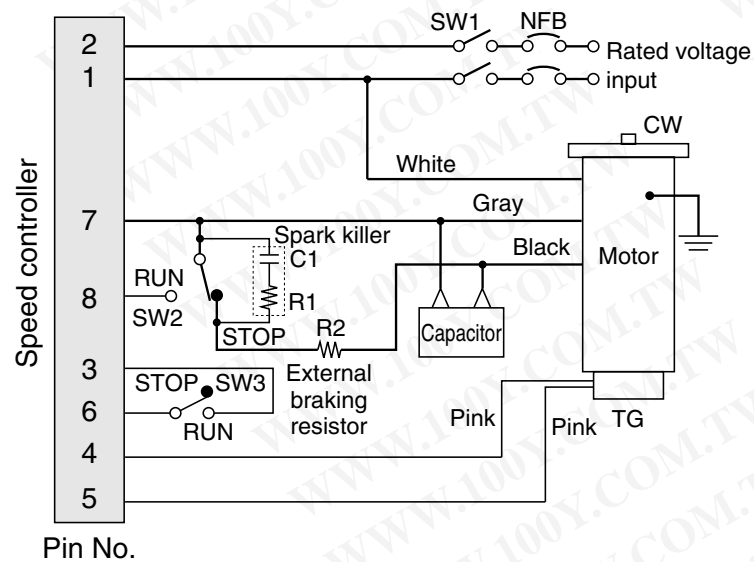
### <Precautions>

- To change rotating direction of induction motor:  
 Provide a motor halt period. Switch over SW2 after complete stop of the motor.
- To change rotating direction of reversible motor:  
 A motor halt period is not necessary. Switch over SW2 while keeping SW1 turned ON. When configuring SW2 with relay contacts, use a relay having large gap between contacts (e.g. HG/HP relay from Matsushita Electric Works, Ltd.) to prevent malfunction due to short-circuited capacitor.
- For motors for cooling fan and motors with thermal protector, also refer to page C-12.
- When using independent relay contacts for SW2 to change over normal/reverse, interlock both contacts so that they will not close simultaneously.
- The spark killer consisting of R1 and C1 must be used to protect the relay contacts.

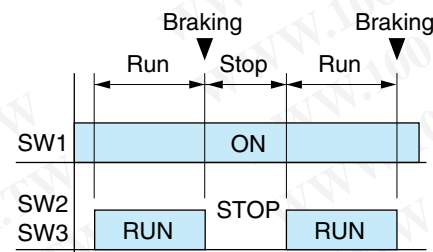
\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

## 3 Unidirectional rotation and electric brake

25 W or smaller

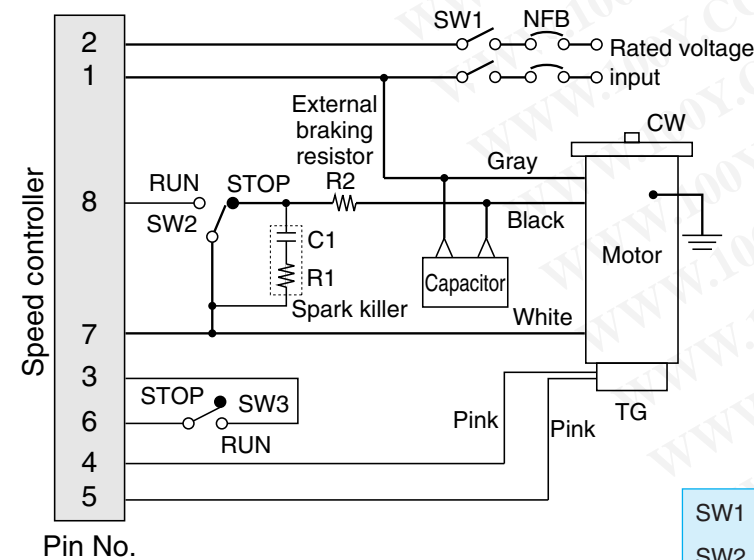


• Connection according to this wiring diagram causes the motor to rotate clockwise when viewed from the motor shaft end. To run the motor counterclockwise, interchange the connecting point of black and gray leads.



SW1 : Power switch  
 SW2 : RUN/STOP switch  
 SW3 : Brake start switch

40 W or larger



SW1	100 V supply system	5 A or more at 125 VAC
SW2	200 V supply system	5 A or more at 250 VAC
SW3	DC10 V 10 mA	
Spark killer R1+C1	DV0P008 (option)	
External braking resistor R2	DV0P003 (option)	

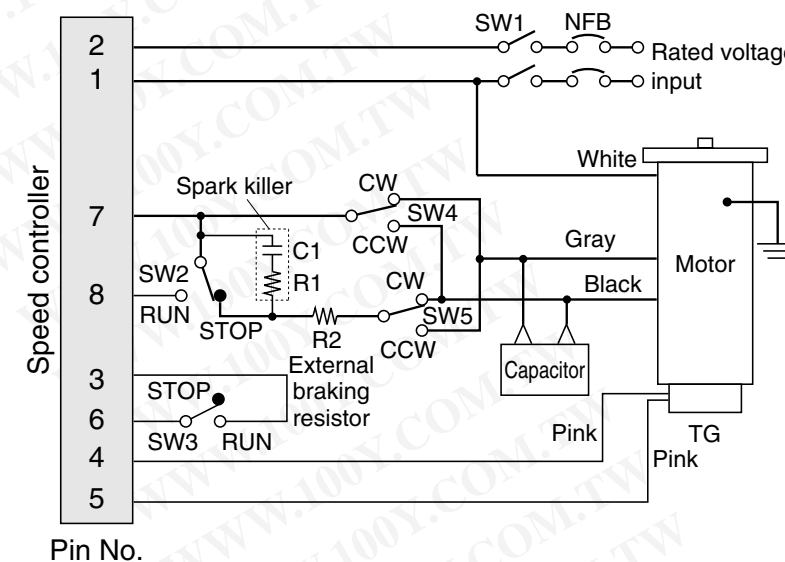
### <Precautions>

- When SW2 and SW3 are switched from RUN to STOP, electric braking is applied for approx. 0.5 sec, and the motor stops instantly. Difference in switching time between SW2 and SW3 must be 0.1 sec or shorter. If SW2 (SW3) is in RUN position while SW3 (SW2) is in STOP, abnormal operation occurs (full speed rotation for a short time) and motor temperature rises excessively.
- The number of start/stop operations must be 6/min. or less.
- For motors for cooling fan and motors with thermal protector, also refer to page C-12.
- The spark killer consisting of R1 and C1 must be used to protect the relay contacts.
- R2 limits flow of discharging current upon short-circuiting of the capacitor during braking.

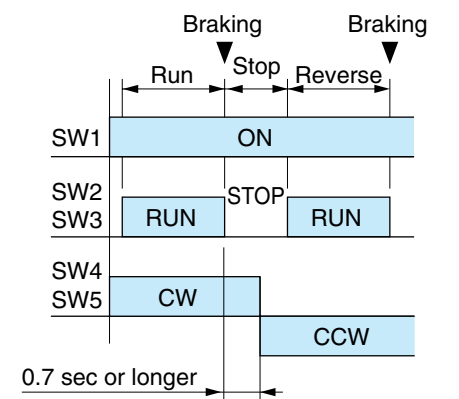
\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

## 4 Normal/reverse

25 W or smaller

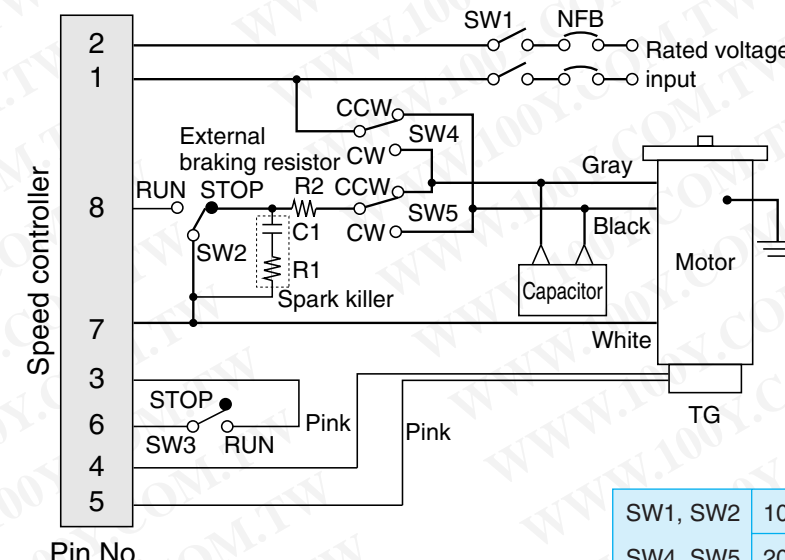


Rotating direction viewed from shaft end	
CW	Clockwise
CCW	Counterclockwise



SW1 : Power switch  
 SW2 : RUN/STOP switch  
 SW3 : Braking start switch  
 SW4 : Normal/reverse selector switch

40 W or larger



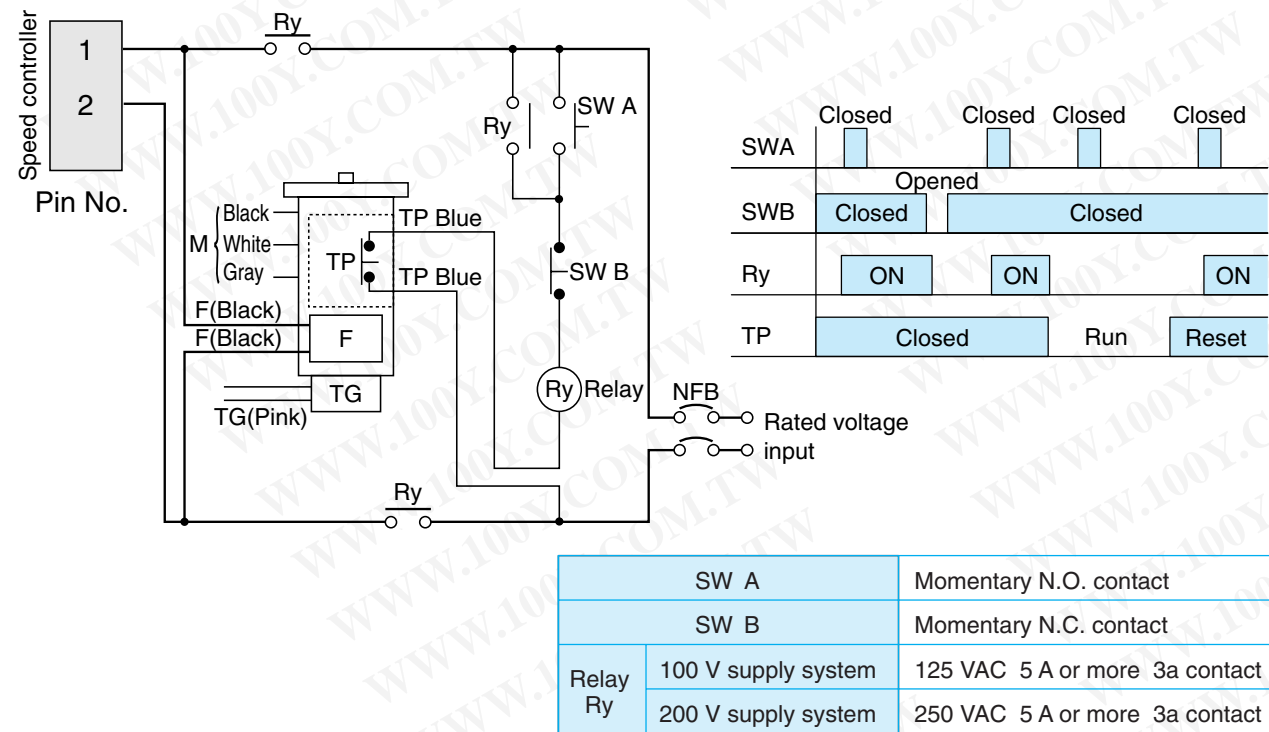
SW1, SW2	100 V supply system	5 A or more at 125 VAC
SW4, SW5	200 V supply system	5 A or more at 250 VAC
SW3	DC10 V 10m A	
Spark killer R1+C1	DV0P008 (option)	
External braking resistor R2	DV0P003 (option)	

### <Precautions>

- When SW2 and SW3 are switched from RUN to STOP, electric braking is applied for approx. 0.5 sec, and the motor stops instantly. (Do not operate SW4 and SW5 until the motor stops.) Difference in switching time between SW2 and SW3 must be 0.1 sec or smaller. If SW2 (SW3) is in RUN position while SW3 (SW2) is in STOP, abnormal operation occurs (full speed rotation for a short time) and motor temperature rises excessively.
- Do not change the motor rotating direction (SW4, SW5) while the motor is running.
- The number of start/stop operations must be 6/min. or less.
- For motors for cooling fan and motors with thermal protector, also refer to page C-12.
- The spark killer consisting of R1 and C1 must be used to protect the relay contacts.

\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

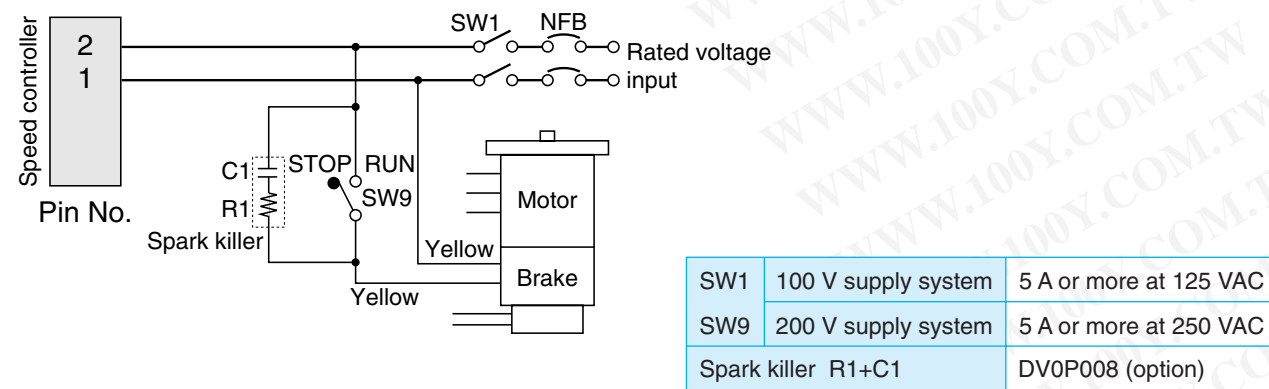
5 Wiring of cooling fan motor (F) or motor with thermal protector (TP)



- <Precautions>**
- The thermal protector (TP) is an automatic reset type. To prevent hazards caused by restarting, connect the TP as shown above. Don't connect TP directly to the power supply.
  - Once the TP operates, cooling period is required before the operation can restart.
  - Connect the cooling fan motor (F) across pins 1 and 2 on the power terminal.
  - Motor (M) and tachometer generator (TG) should be connected according to corresponding wiring diagram shown later.

6 Wiring to electromagnetic brake (40 W or smaller)

- Variable speed motor with electromagnetic brake should be wired as shown below.



- <Precautions>**
- Operate SW9 simultaneously with RUN/STOP switching of other switches, if any. Placing other switch to RUN position while the brake is active (SW9 at STOP position) causes the motor to generate heat.
  - For remaining wirings, refer to corresponding wiring diagram.

\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

7 Wiring diagram (for unidirectional rotation)

- The thick continuous lines represent main circuit. Use conductor of size 0.75 mm<sup>2</sup> or larger for the main line.
- The thin continuous lines represent signal circuit. Use conductor of size 0.3 mm<sup>2</sup> or larger in the signal circuit. When the distance from the tachometer generator (TG) is long, use shielded twisted pair cable.

• Soft-start/down control

Soft-start and soft-down times can be adjusted by a single setting. Use this feature to protect the load from shock caused by sharp speed change at startup and shutdown of the motor. To disable the soft operation, turn the control fully clockwise.

• Maximum speed control

Use this control to adjust the revolving speed when the external speed changer is set at the top speed. Adjust the speed to 1400 (min<sup>-1</sup>) or below at 50 Hz; or 1700 (min<sup>-1</sup>) or below at 60 Hz.

• Operation changeover switch

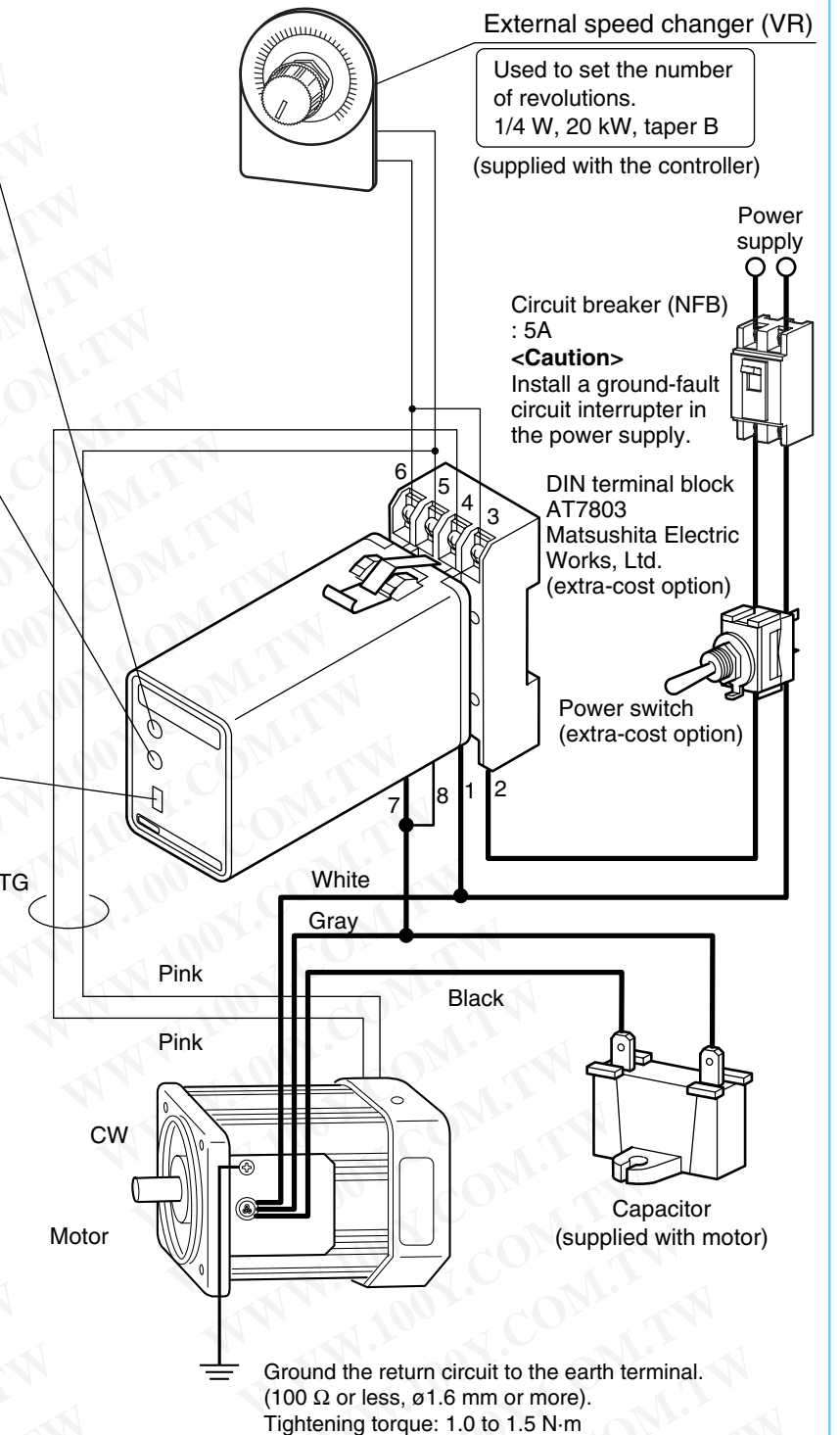
Select "high-stable" or "high-response":

**<High-stable>**

- Keeps the rotation speed variation low against variation in load.
- Enables a wide range of speed control.
- Suitable for capability control.
- May fail to maintain constant rotation speed upon sharp load change.

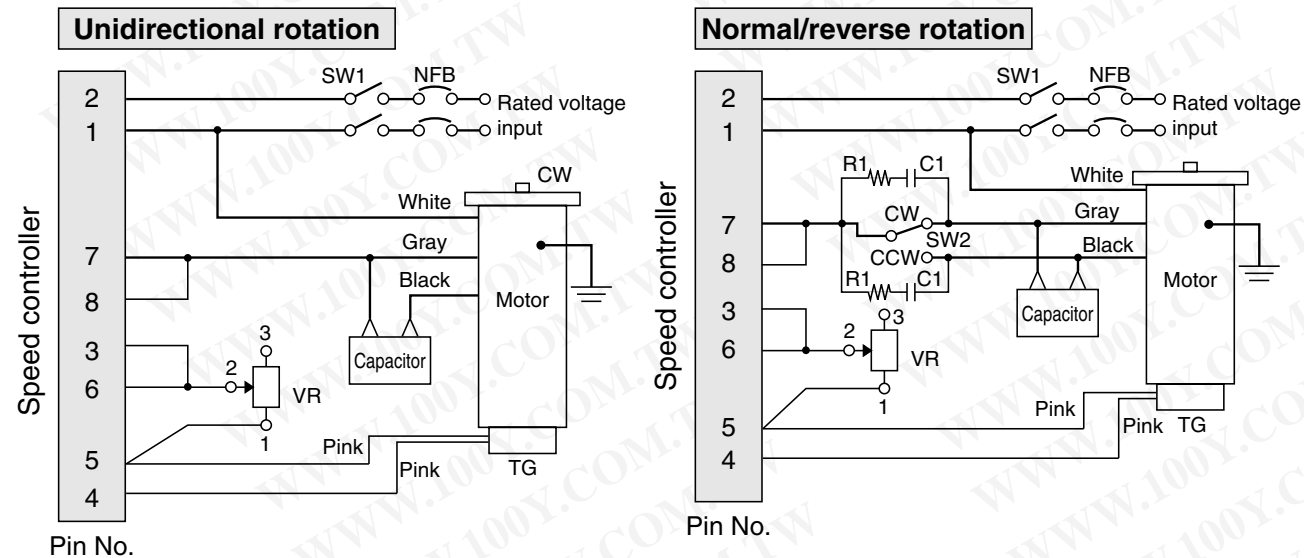
**<High-response>**

- Enables quick response with low hunting.
- Suitable for positioning application.
- May fail to keep rotation speed variation low against variation in load.
- Not suitable for controlling wide range of speed.

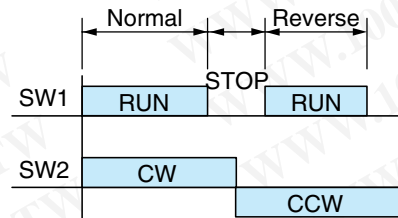


\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

## 8 Speed change only



This wiring diagram causes the motor to rotate clockwise when viewed from the motor shaft end. To run the motor counterclockwise, interchange the connecting point of black and gray leads.



SW1 : Power switch  
 SW2 : Normal/reverse selector switch

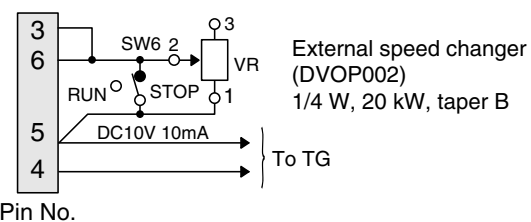
SW1	100 V supply system	5 A or more at 125 VAC
SW2	200 V supply system	5 A or more at 250 VAC
R1+C1	DV0P008 (option)	

### <Precautions>

- To change rotating direction of induction motor: Provide a motor halt period. Switch over SW2 after complete stop of the motor.
- To change rotating direction of reversible motor: A motor halt period is not necessary. Switch over SW2 while keeping SW1 turned ON. When configuring SW2 with relay contacts, use a relay having large gap between contacts (e.g. HG/HP relay from Matsushita Electric Works, Ltd.) to prevent malfunction due to short-circuited capacitor.
- For motors for cooling fan and motors with thermal protector, also refer to page C-20.
- When using independent relay contacts for SW2 to change over normal/reverse, interlock both contacts so that they will not close simultaneously.
- The spark killer consisting of R1 and C1 must be used to protect the relay contacts.

### Start/stop control with small signal

- With the external speed changer connected, the motor can be started/stopped with a small signal through SW6 contact while the power switch SW1 (see diagram above) is on. The SW6 provides shorter start-up time than SW1.

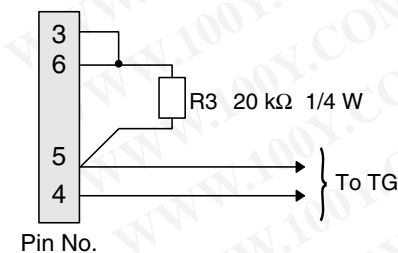


### <Precautions>

- Power (SW1) should be turned on at least 0.5 sec before turning on of the start signal (SW6).
- When the motor is not operated for a prolonged time, turn off power switch (SW1).

### Operation from maximum speed control

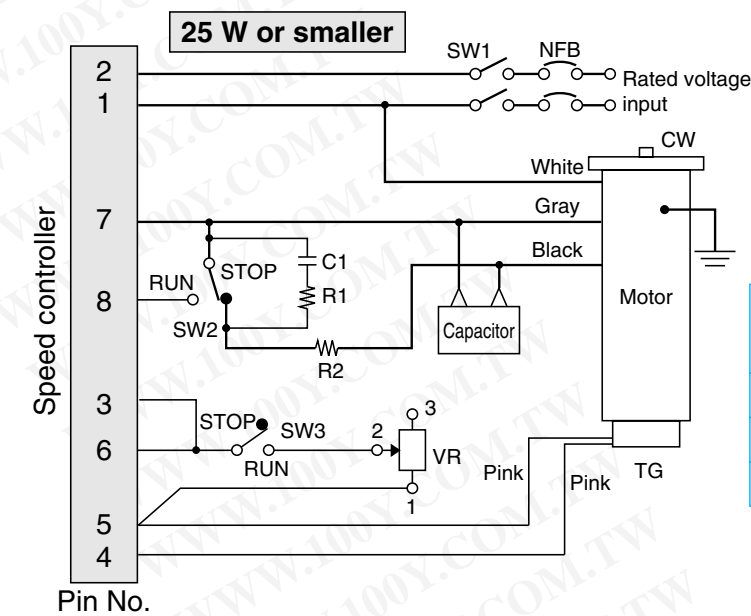
- When no external speed changer is required, the speed can be adjusted from the maximum speed control.



### <Precautions>

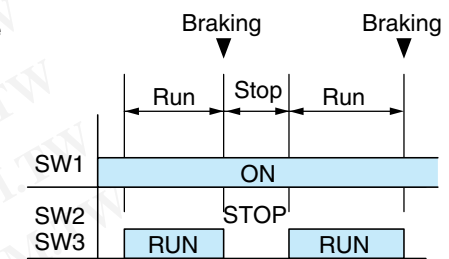
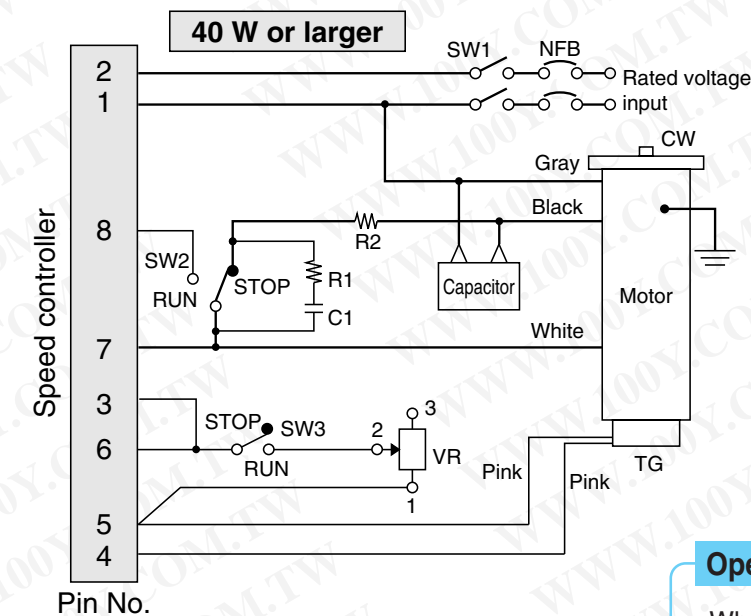
- Connect a fixed resistor (R3) in place of external speed changer (VR).

## 9 Unidirectional rotation and electric brake



- Connection according to this wiring diagram causes the motor to rotate clockwise when viewed from the motor shaft end. To run the motor counterclockwise, interchange the connecting point of black and gray leads.

SW1	100 V supply system	5 A or more at 125 VAC
SW2	200 V supply system	5 A or more at 250 VAC
SW3	DC10 V 10 mA	
R1+C1	DV0P008 (option)	
R2	DV0P003 (option)	



SW1 : Power switch  
 SW2 : RUN/STOP switch  
 SW3 : Brake start switch

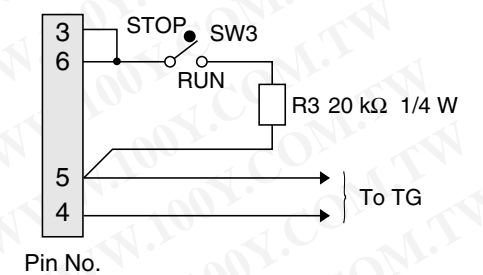
Pin No.

### <Precautions>

- When SW2 and SW3 are switched from RUN to STOP, electric braking is applied for approx. 5 sec, or until the motor stops. SW2 and SW3 must be operated simultaneously. Otherwise, abnormal operation occurs (full speed rotation for a short time), causing the motor temperature rises excessively.
- The number of start/stop cycles must be 6/min. or less.
- When using cooling fan motor or motor with thermal protector, also see page C-20.
- Insert R1 and C1 to protect relay contact.
- R2 restricts discharge current in case of capacitor short circuit during braking.

### Operation from maximum speed control

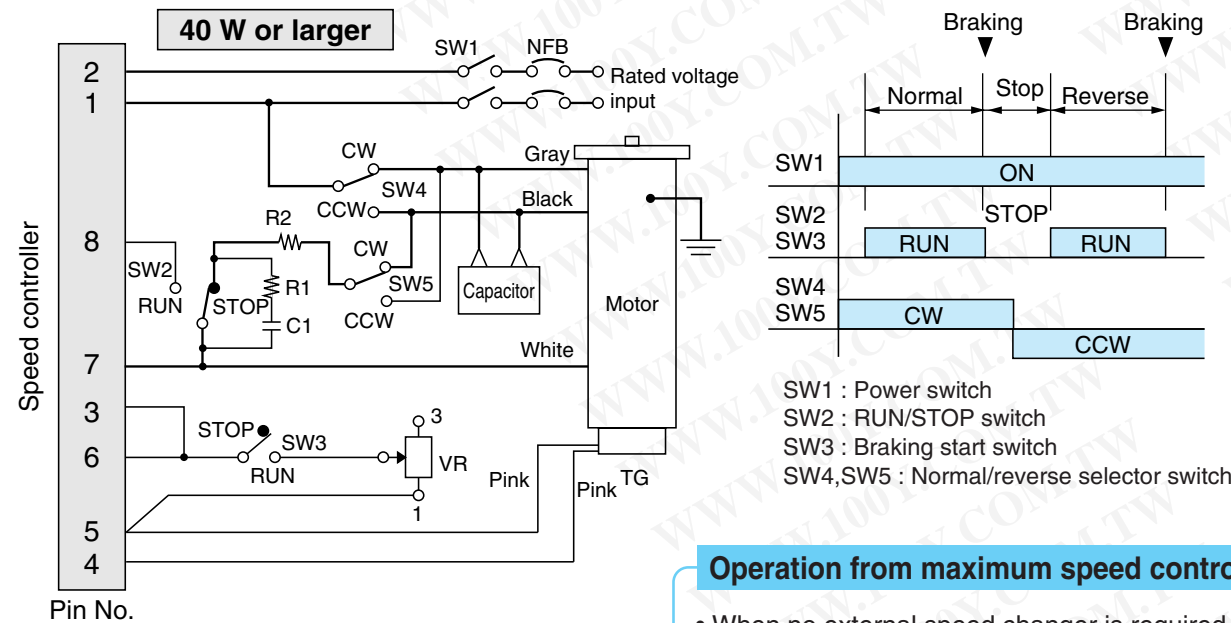
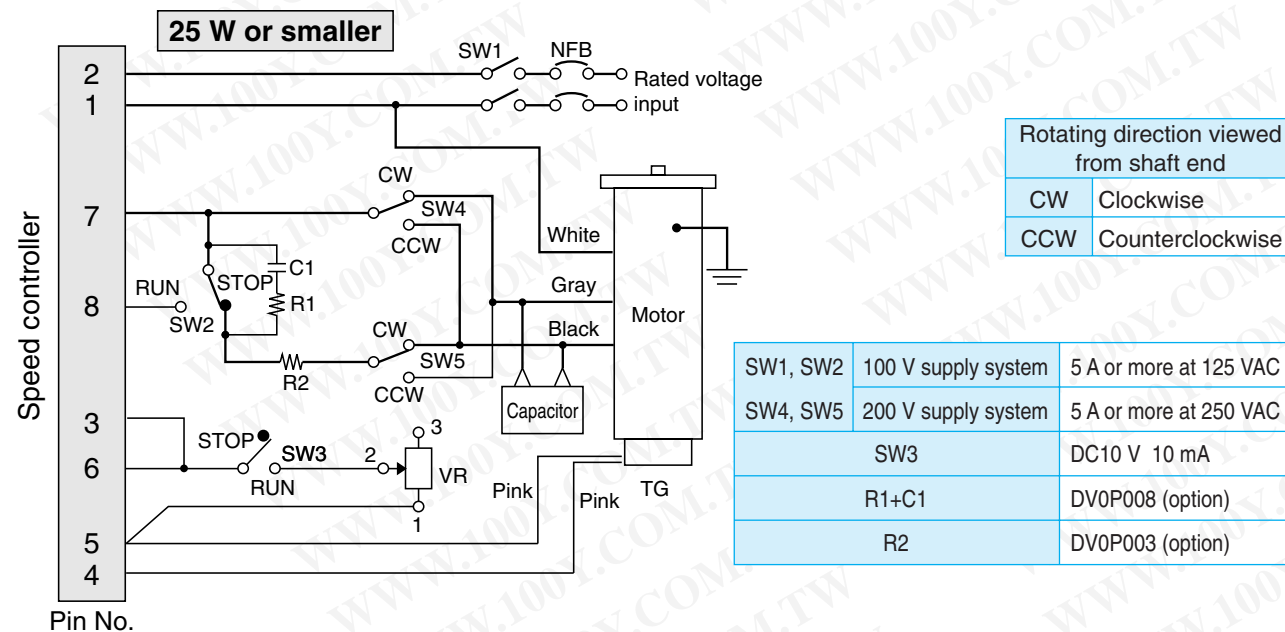
- When no external speed changer is required, the speed can be adjusted from the maximum speed control.



### <Precautions>

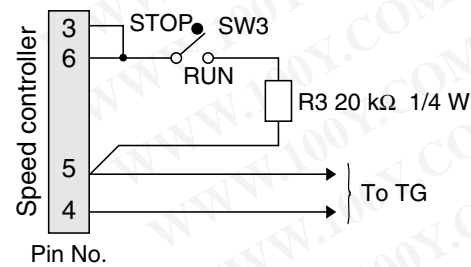
- Connect a fixed resistor (R3) in place of external speed changer (VR).

## 10 Normal/reverse rotation and electric brake



### Operation from maximum speed control

- When no external speed changer is required, the speed can be adjusted from the maximum speed control.



### <Precautions>

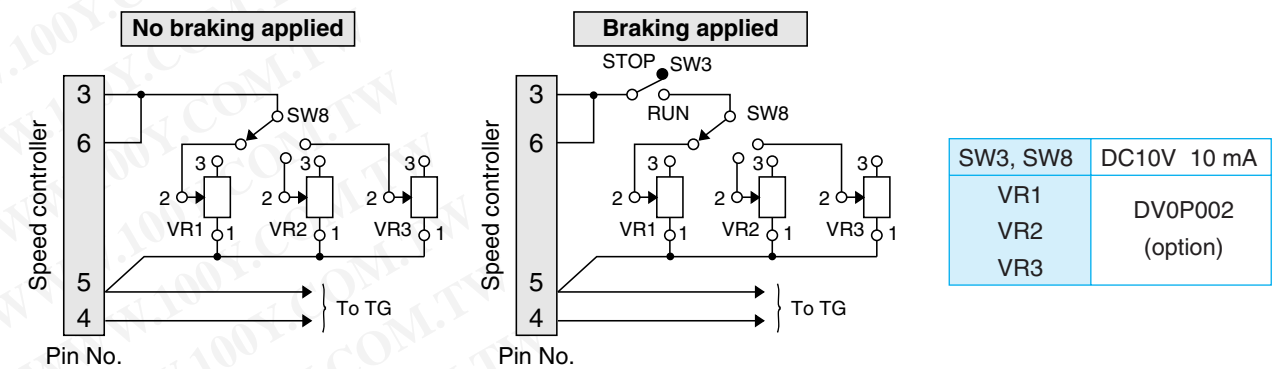
- Connect a fixed resistor (R3) in place of external speed changer (VR).

### <Precautions>

- When SW2 and SW3 are switched from RUN to STOP, electric braking is applied for approx. 5 sec, or until the motor stops. (Do not operate SW4 and SW5 until the motor stops completely.) SW2 and SW3 must be operated simultaneously. Otherwise, abnormal operation occurs (full speed rotation for a short time), causing the motor temperature rises excessively.
- Do not change the rotating direction (SW4, SW5) while the motor is running.
- The number of start/stop cycles must be 6/min. or less.
- When using cooling fan motor or motor with thermal protector, also see page C-20.
- Insert R1 and C1 to protect relay contact.
- R2 restricts discharge current in case of capacitor short circuit during braking.

\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

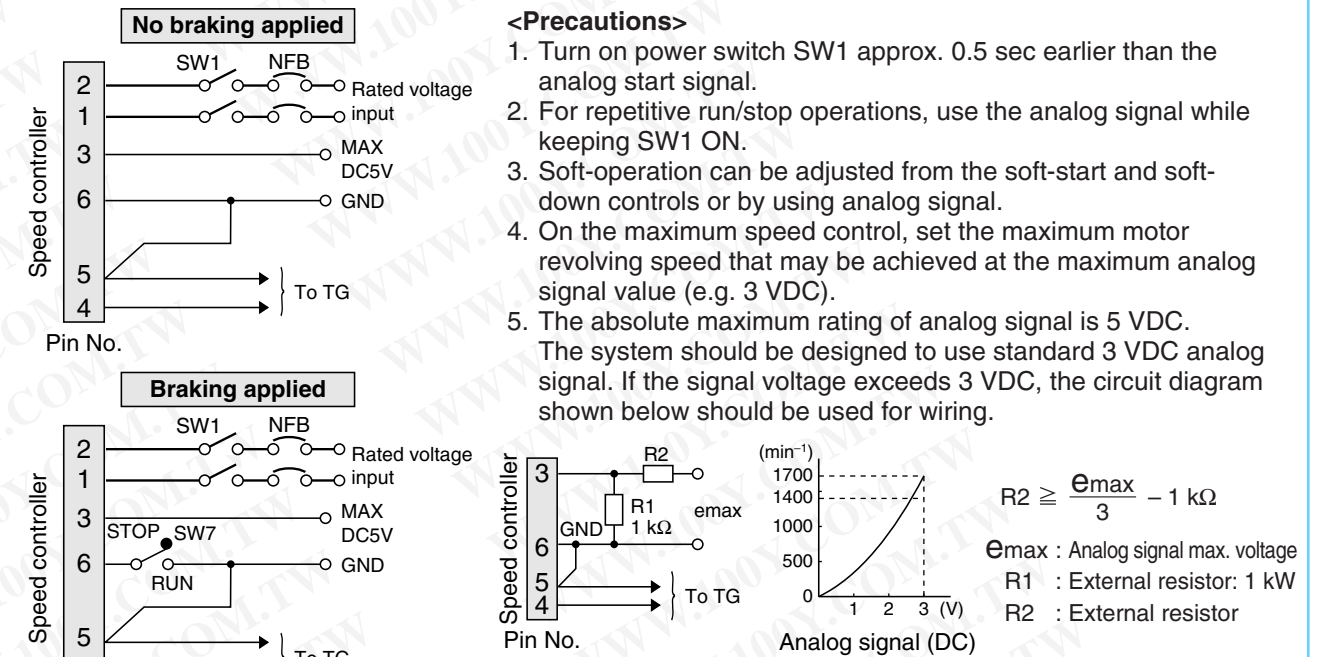
## 11 Multispeed setting application



### <Precautions>

- Set external speed changers VR1, VR2 and VR3 to 3 different speeds and select the desired speed from SW8.
- When activating the brake, simultaneously switch over SW3 and RUN-STOP of other switches.
- For remaining wirings, refer to the corresponding wiring diagrams.

## 12 Speed change with analog signal



### <Precautions>

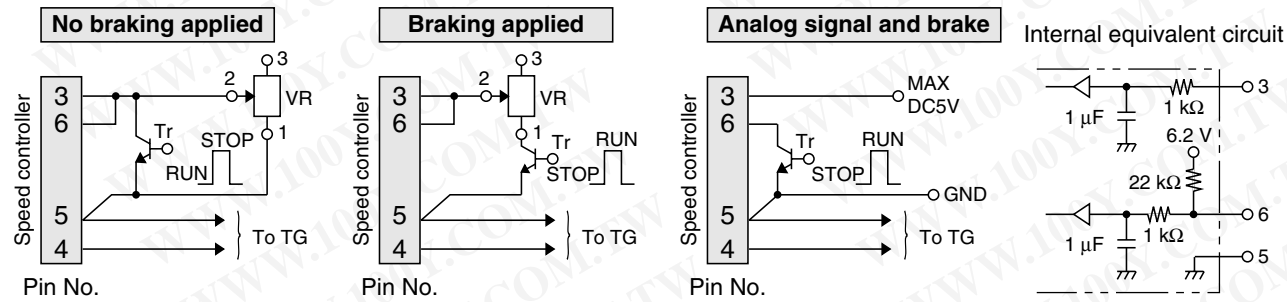
- Turn on power switch SW1 approx. 0.5 sec earlier than the analog start signal.
- For repetitive run/stop operations, use the analog signal while keeping SW1 ON.
- Soft-operation can be adjusted from the soft-start and soft-down controls or by using analog signal.
- On the maximum speed control, set the maximum motor revolving speed that may be achieved at the maximum analog signal value (e.g. 3 VDC).
- The absolute maximum rating of analog signal is 5 VDC. The system should be designed to use standard 3 VDC analog signal. If the signal voltage exceeds 3 VDC, the circuit diagram shown below should be used for wiring.
- Revolution speed "0" signal should not exceed 0.1 VDC.
- The input speed pattern (curve) may not be exactly reflected on the motor speed, due to inertial effect of the load, especially during stop sequence.
- The percentage ripple of analog voltage signal should be 2% or less.
- For other wirings, refer to the corresponding circuit/wiring diagrams.
- When using the braking feature, motor wiring (pins 1, 7 and 8) should be in accordance with pages C-8 and C-9. To activate braking, switch SW2 and SW7 at the same time. If SW2 is in RUN position while SW7 is in STOP, abnormal operation occurs (full speed rotation for a short time); or if SW7 is in RUN position while SW2 is in STOP, motor temperature rises excessively.

\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.



## 13 Operation through contactless signal

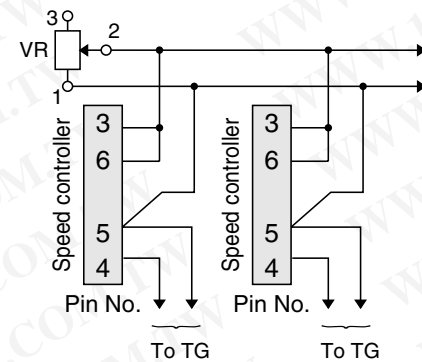
- Small signal relays SW3, SW6 and SW7 can be replaced with transistor.



## 14 Parallel operation through external speed changer

### <Precautions>

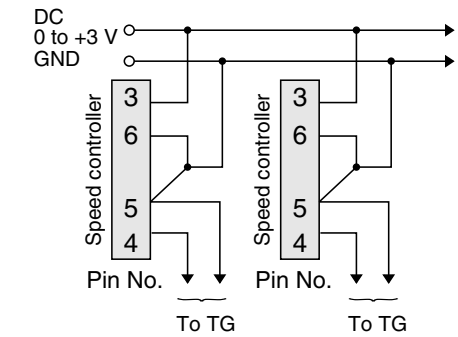
- The resistance  $R_s$  of the external speed changer VR should be as follows:  
 $R_s = 20/N$  (kΩ)  
 where, N is the number of motors.
- For synchronous operation or ratio operation, desired revolving speeds must be set from the maximum speed control. Soft-start and soft-down controls and operation changeover switch must be set to the same position.
- Wirings from the external speed changer VR should be connected to the same pins (No.5 and 6) on the controller.
- Malfunction may occur as the number of devices operated in parallel increases. To secure correct operation, connect a noise filter to each unit.
- For other electrical connections, refer to corresponding circuit/wiring diagrams.



## 15 Parallel operation through analog signal

### <Precautions>

The input impedance of the controller is approx. 100 kΩ. The output impedance of the analog signal source should be determined based on the total input impedance of the speed controllers.

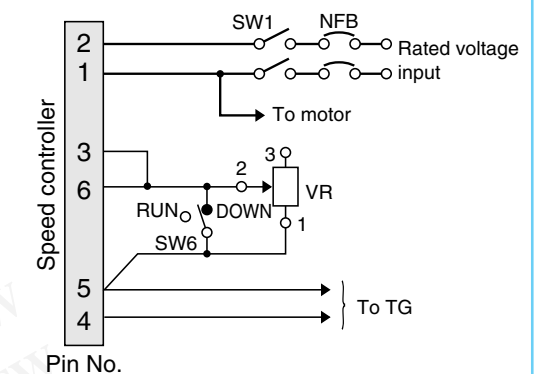


## 16 Soft-operation

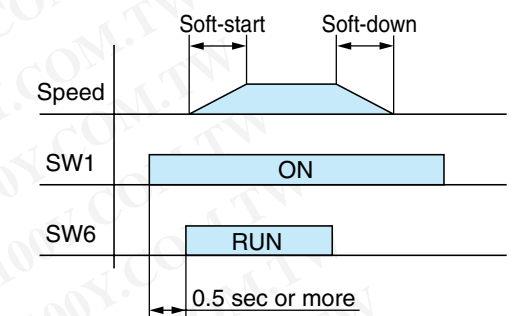
### • Soft-start, soft-down

#### <Precautions>

- Power switch SW1 should be turned on approx. 0.5 sec before the operation start signal from SW6.
- When repeating run/stop cycles, turn on/off only SW6 while keeping SW1 turned ON. In this way, the motor can be controlled by using a small signal. To stop operation for a long time, also turn off SW1.
- Soft-start/soft-down period is the time required for the equipment to start up from stop state to full speed when the external speed changer is set at maximum value.
- Soft-start/soft-down control, when at the full clockwise position, disables the soft-down function. As the stop signal is input, power supply to the motor is turned off immediately. However, the revolving speed gradually decreases in proportion to the inertia of the load and motor starts free-running stop sequence.
- Soft-start/soft-down control can set maximum time length of approx. 5 seconds (Typ. at FCCW). The setting may be exceeded if the inertia of the load is too large.
- For other electrical connections, refer to corresponding circuit/wiring diagrams.



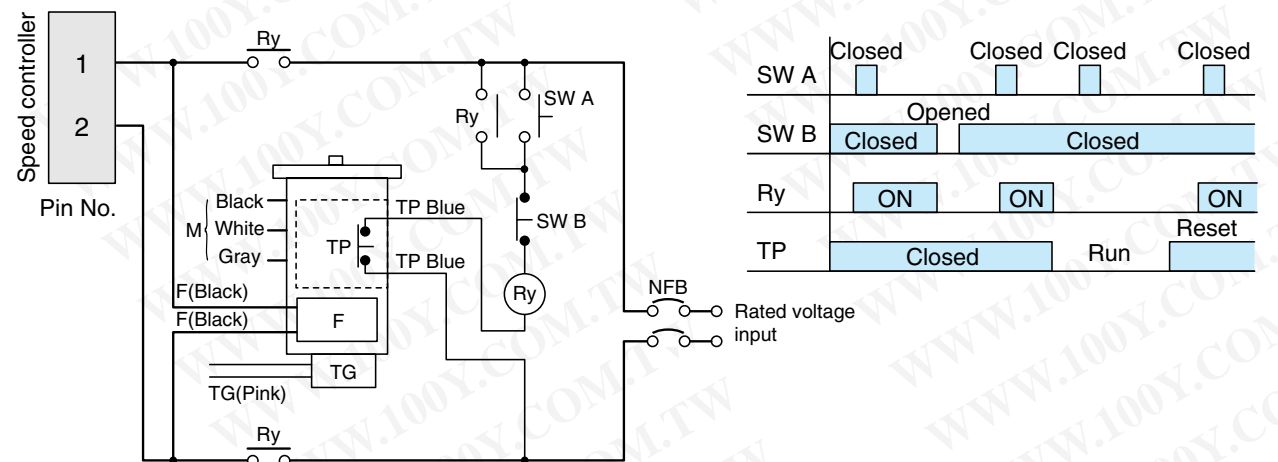
SW1	100 V supply system	5 A or more at 125 VAC
	200 V supply system	5 A or more at 250 VAC
SW6		DC10 V 10 mA



### • Soft-start and electric brake

Electrical wirings are the same as for "Unidirectional rotation and electric brake" and "Normal/reverse rotation and electric brake". Adjust the soft-start time from the soft-start/down control.

17 Wiring of cooling fan motor and motor with thermal protector



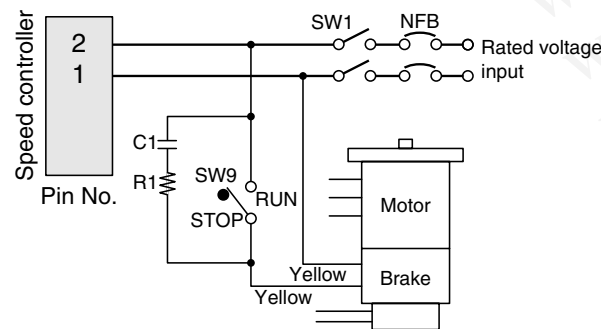
SW A	Momentary N.O. contact	
SW B	Momentary N.C. contact	
Ry	100 V supply system	125 VAC 5 A or more 3a contact
	200 V supply system	250 VAC 5 A or more 3a contact

<Precautions>

1. The thermal protector (TP) is an automatic reset type. To prevent hazards caused by restarting, connect the TP as shown above. Don't connect TP directly to the power supply.
2. Once the TP operates, cooling period is required before the operation can restart.
3. Connect the cooling fan motor (F) across pins 1 and 2 on the power terminal.
4. Motor (M) and tachometer generator (TG) should be connected according to corresponding wiring diagram shown later.

18 Wiring to electromagnetic brake

• Variable speed motor with electromagnetic brake should be wired as shown below.



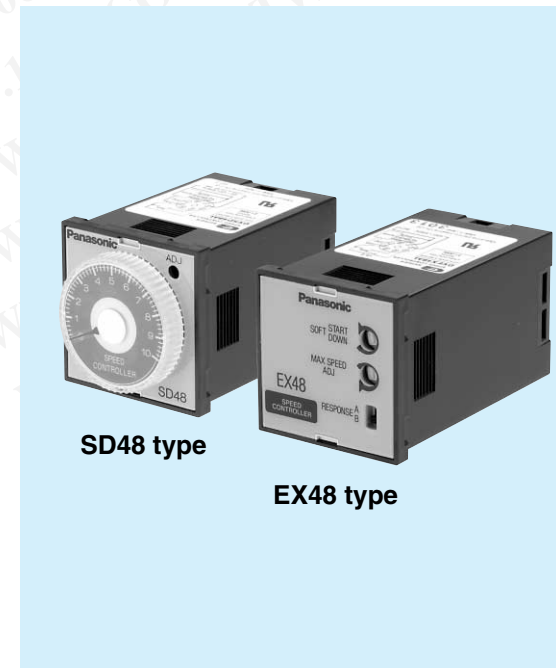
SW1	100 V supply system	5 A or more at 125 VAC
SW9	200 V supply system	5 A or more at 250 VAC
R1+C1	DV0P008 (option)	

<Precautions>

1. SW9 should be switched to RUN or STOP at the same time as the other switches are switched to RUN or STOP.  
If the other switches are set to RUN while the brake is energized (SW9 in STOP position), the motor will generate heat.
2. For other wirings, refer to the corresponding circuit/wiring diagrams.  
If the application is speed change without using electric braking (page C-14), perform wiring according to "Start/stop control with small signal".

\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

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 Http://www.100y.com.tw



- First DIN 48 size in the industry
- Compact space saving model (control panel) (standardized panel machining holes)
- A wide choice of options (recommended by Matsushita Electric Works, Ltd.)
- Simplified and neat wiring arrangement
- Main circuit and signal inputs are isolated on the terminal block.
- Use of 8-pin terminal block requires fewer wiring connections.
- Can operate under a wide range of power supply voltage (100V→100 to 120V, 200V→200 to 240V)

• Standard specification

Part No.	SD48 type						EX48 type					
	DVSD 48AL	DVSD 48BL	DVSD 48CL	DVSD 48AY	DVSD 48BY	DVSD 48CY	DVEX 48AL	DVEX 48BL	DVEX 48CL	DVEX 48AY	DVEX 48BY	DVEX 48CY
Rated voltage	100 to 120 VAC			200 to 240 VAC			100 to 120 VAC			200 to 240 VAC		
Operating voltage range	±10% (at rated voltage)											
Power frequency	50/60Hz						50/60 Hz					
Rated current	0.5 A	1.0 A	2.0 A	0.3 A	0.5 A	1.0 A	0.5 A	1.0 A	2.0 A	0.3 A	0.5 A	1.0 A
Compatible motor output *1	3 to 20 W	25 to 40 W	60 to 90 W	3 to 20 W	25 to 40 W	60 to 90 W	3 to 20 W	25 to 40 W	60 to 90 W	3 to 20 W	25 to 40 W	60 to 90 W
Speed variation	90 to 1400 min <sup>-1</sup> / 90 to 1700 min <sup>-1</sup>						Mode A (high-response mode): 50 to 1400 min <sup>-1</sup> / 50 to 1700 min <sup>-1</sup> Mode B (high-response mode): 90 to 1400 min <sup>-1</sup> / 90 to 1700 min <sup>-1</sup> *2					
Speed setting	Internal						External speed changer, analog voltage, maximum speed setting control					
Brake *3	Applies braking force to the motor by feeding electric braking current to the motor for 0.5 sec (typ)						Applies braking force to the motor by feeding electric braking current to the motor for 5 sec (typ) (Turns off electric braking current even within 5 sec as the motor stops.)					
Parallel operation	Not possible						Possible					
Soft-start/down	Not applicable						Variable up to 5 sec (typ) (0 to max. revolving speed)					
Operating temperature range	-10 to 50°C						-10 to 50°C					
Storage temperature	-20 to 60°C						-20 to 60°C					

\*1. Applicable to Panasonic compact geared motors and variable speed motors.

\*2. EX48 models are set to mode A (high-stable) upon shipment.

\*3. Electric braking has no mechanical brake holding force.

To provide the holding force, use a variable speed motor with electromagnetic braking feature.

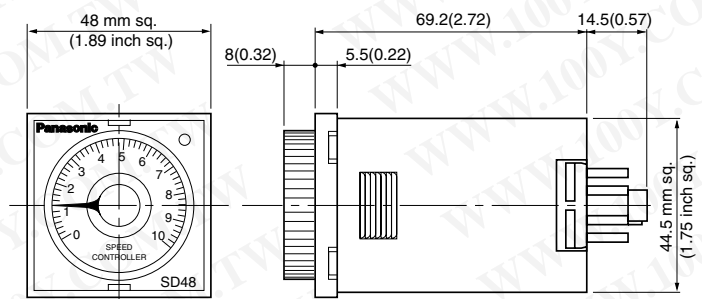
\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

# Speed controller

48 mm sq. (1.89 inchsq.) type

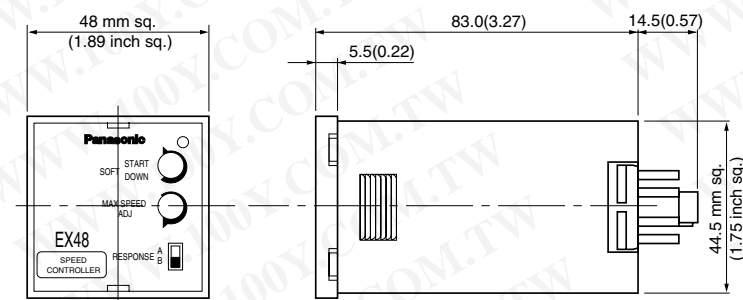
## • Outline drawing

### 48 mm sq. SD48 type



Unit: mm (inch)

### 48 mm sq. EX48 type



Unit: mm (inch)

## • Connection diagram list

Connection diagram	Function	Speed controller	Page
1	Wiring diagram (for unidirectional rotation)	SD48 type	C-23
2	Speed change only	SD48 type	C-24
3	Unidirectional rotation and electric brake	SD48 type	C-25
4	Normal/reverse rotation and electric brake	SD48 type	C-26
5	Wiring of cooling fan motor (F) or motor with thermal protector (TP)	SD48 type	C-27
6	Wiring to electromagnetic brake	SD48 type	C-27
7	Wiring diagram (for unidirectional rotation)	EX48 type	C-28
8	Speed change only	EX48 type	C-29
9	Unidirectional rotation and electric brake	EX48 type	C-30
10	Normal/reverse rotation and electric brake	EX48 type	C-31
11	Multispeed setting application	EX48 type	C-32
12	Speed change with analog signal	EX48 type	C-32
13	Operation through contactless signal	EX48 type	C-32
14	Parallel operation through external speed changer	EX48 type	C-33
15	Parallel operation through analog signal	EX48 type	C-33
16	Soft-operation	EX48 type	C-34
17	Wiring of cooling fan motor (F) and motor with thermal protector (TP)	EX48 type	C-35
18	Wiring to electromagnetic brake	EX48 type	C-35

\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

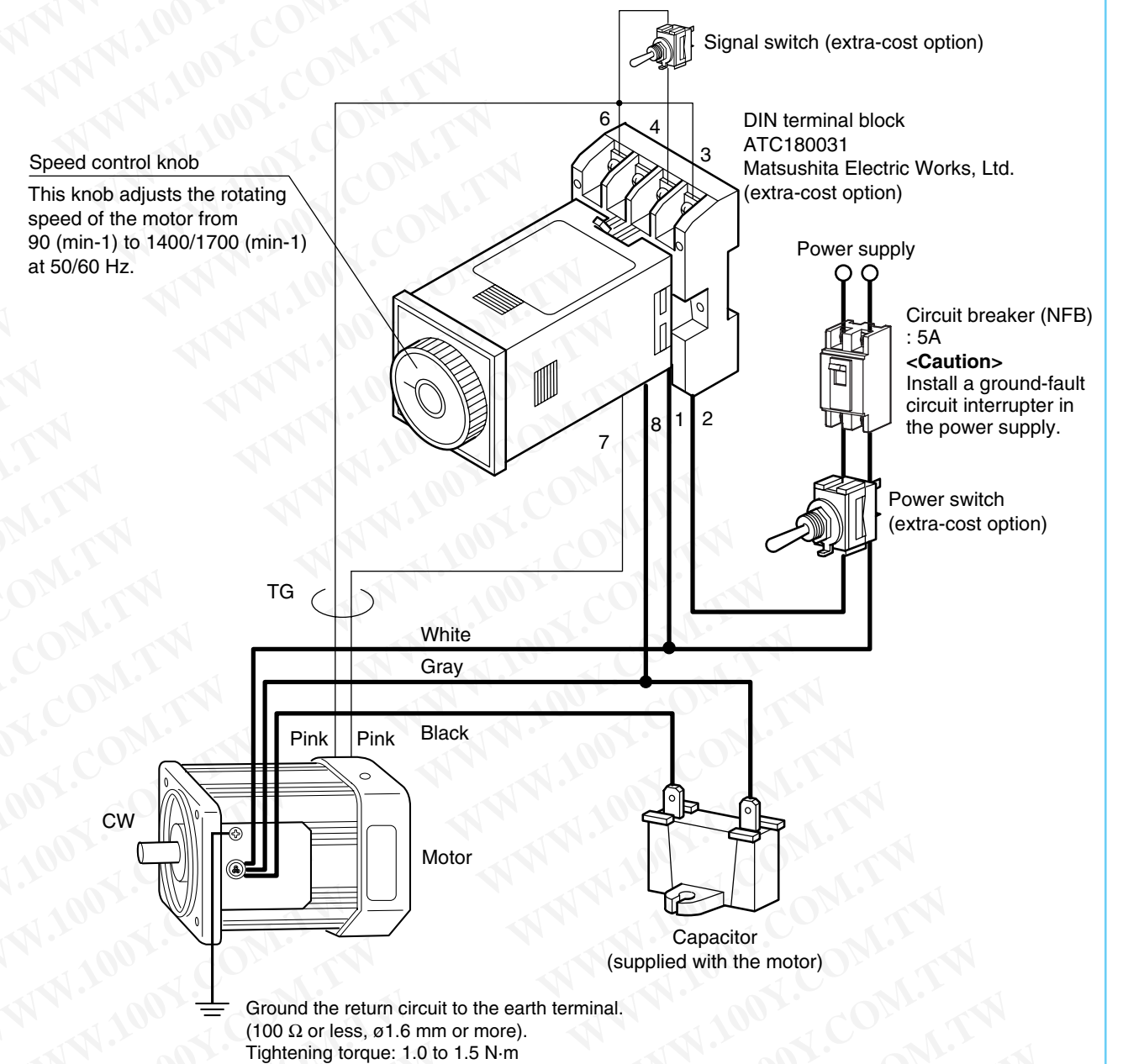
# Speed controller

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 胜特力电子(深圳) 86-755-83298787  
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SD48 type

## 1 Wiring diagram (for unidirectional rotation)

- The motor revolving speed can be set from the speed setting knob on the panel.
- The thick continuous lines represent main circuit. Use conductor of size 0.75 mm<sup>2</sup> (AWG 18) or larger for the main line.
- The thin continuous lines represent signal circuit. Use conductor of size 0.3 mm<sup>2</sup> or larger in the signal circuit. When the distance from the tachometer generator (TG) is long, use shielded twisted pair cable. Do not ground the shielding material.

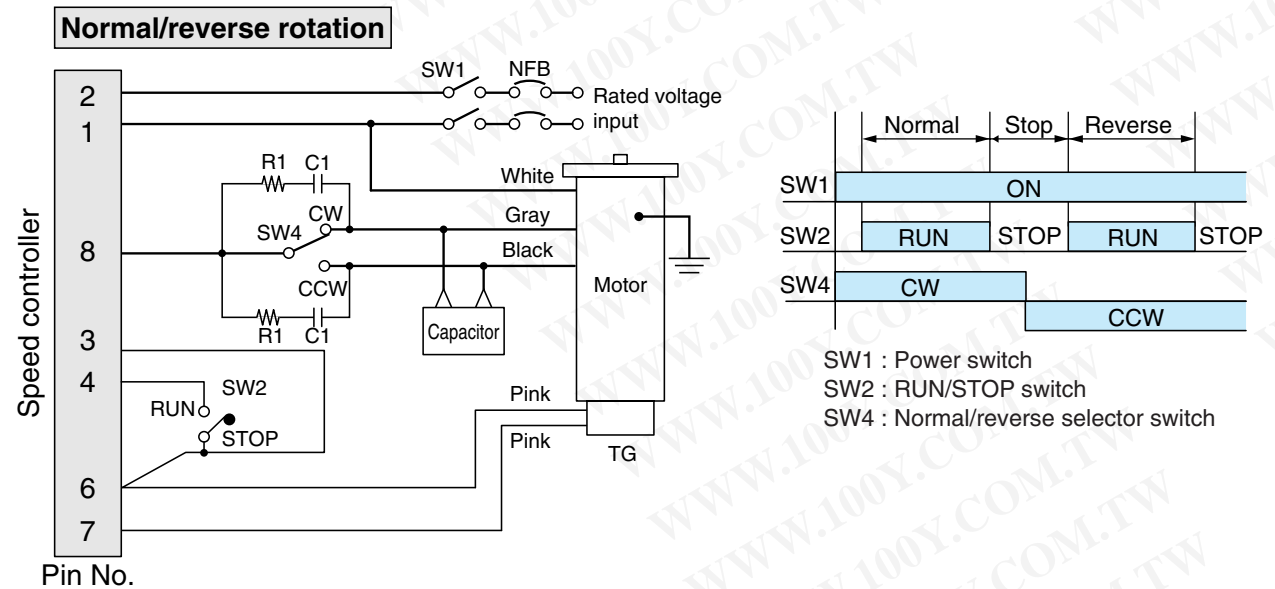
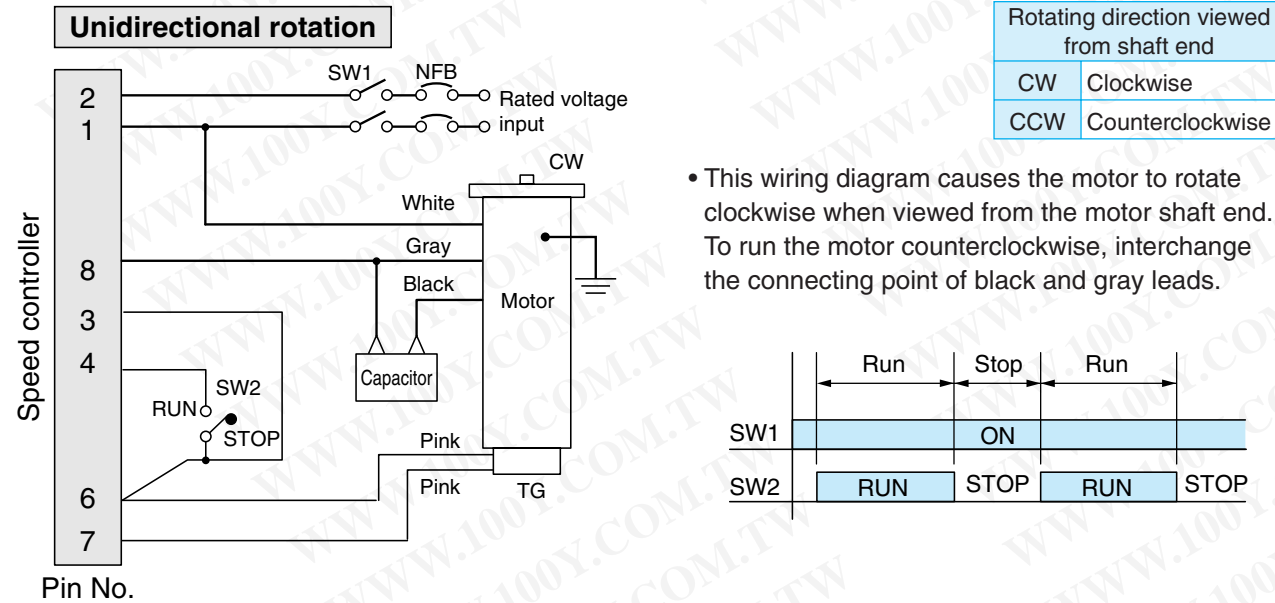


### • Rotating direction viewed from shaft end

**CW** : Clockwise  
**CCW** : Counterclockwise

\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

## 2 Speed change only



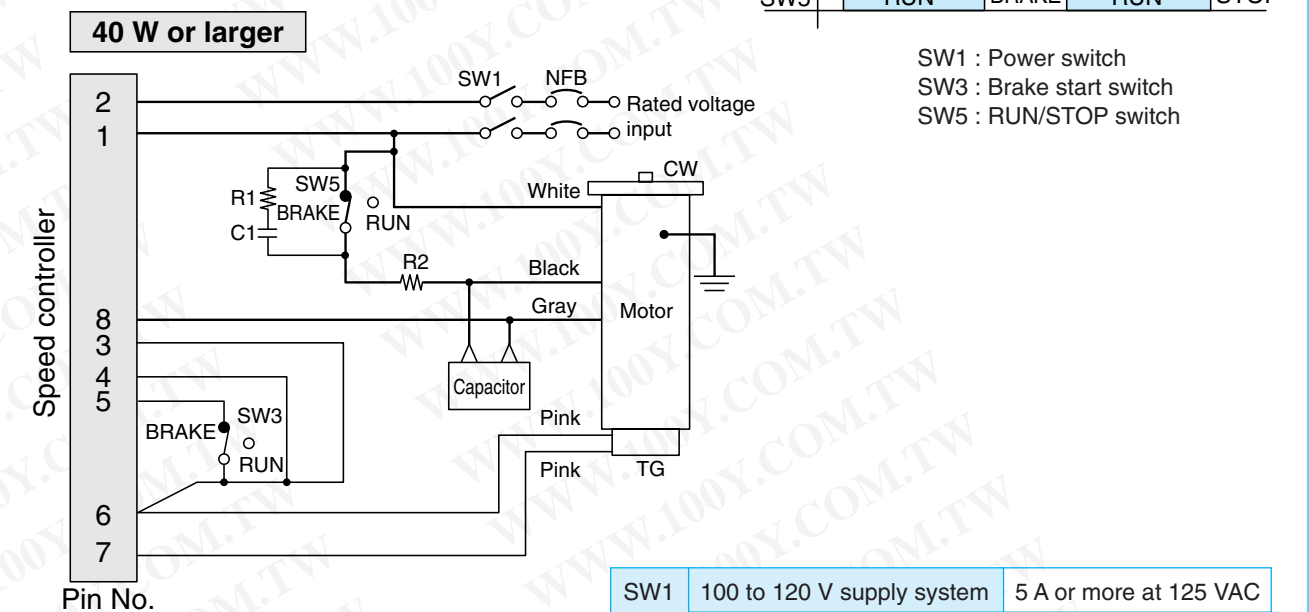
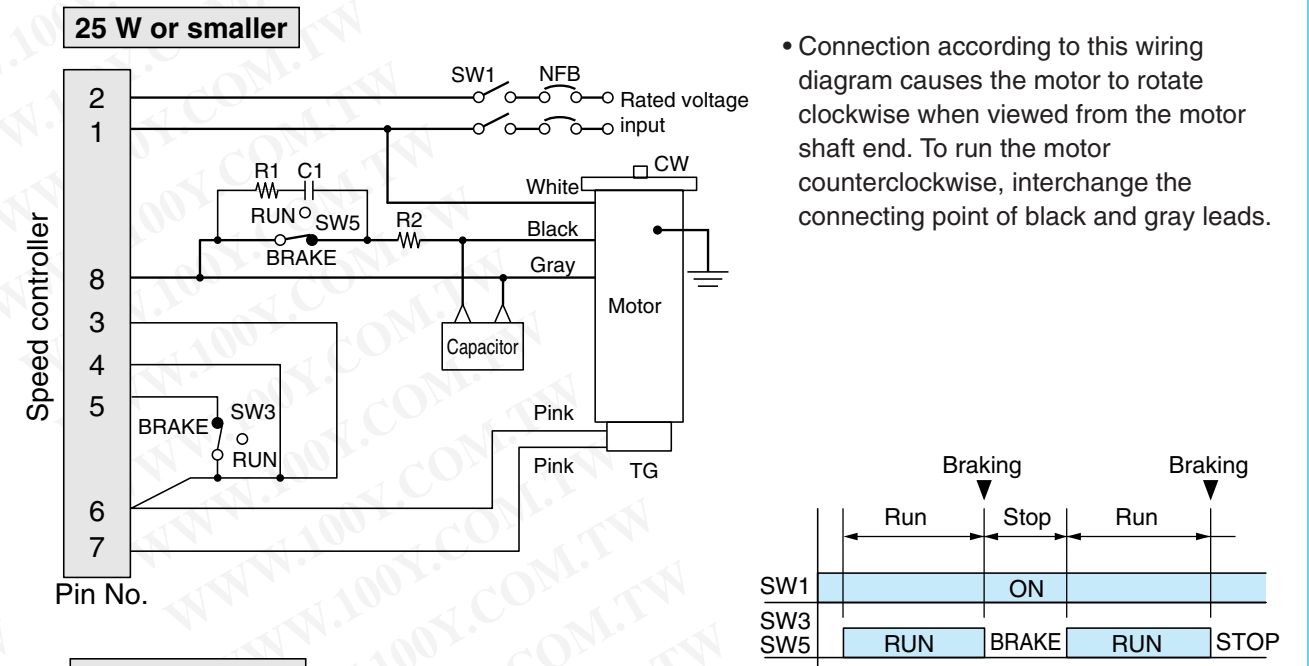
SW1	100 to 120 V supply system	5 A or more at 125 VAC
SW4	200 to 240 V supply system	5 A or more at 250 VAC
R1, C1	DV0P008 (option)	

### <Precautions>

- To change rotating direction of induction motor:  
Provide a motor halt period. Switch over SW4 after complete stop of the motor.
- To change rotating direction of reversible motor:  
A motor halt period is not necessary. Switch over SW4 while keeping SW1 turned ON. When configuring SW4 with relay contacts, use a relay having large gap between contacts (e.g. HG/HP relay from Matsushita Electric Works, Ltd.) to prevent malfunction due to short-circuited capacitor.
- For motors for cooling fan and motors with thermal protector, also refer to page C-27.
- When using independent relay contacts for SW4 to change over normal/reverse, interlock both contacts so that they will not close simultaneously.
- The spark killer consisting of R1 and C1 must be used to protect the relay contacts.

\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

## 3 Unidirectional rotation and electric braking



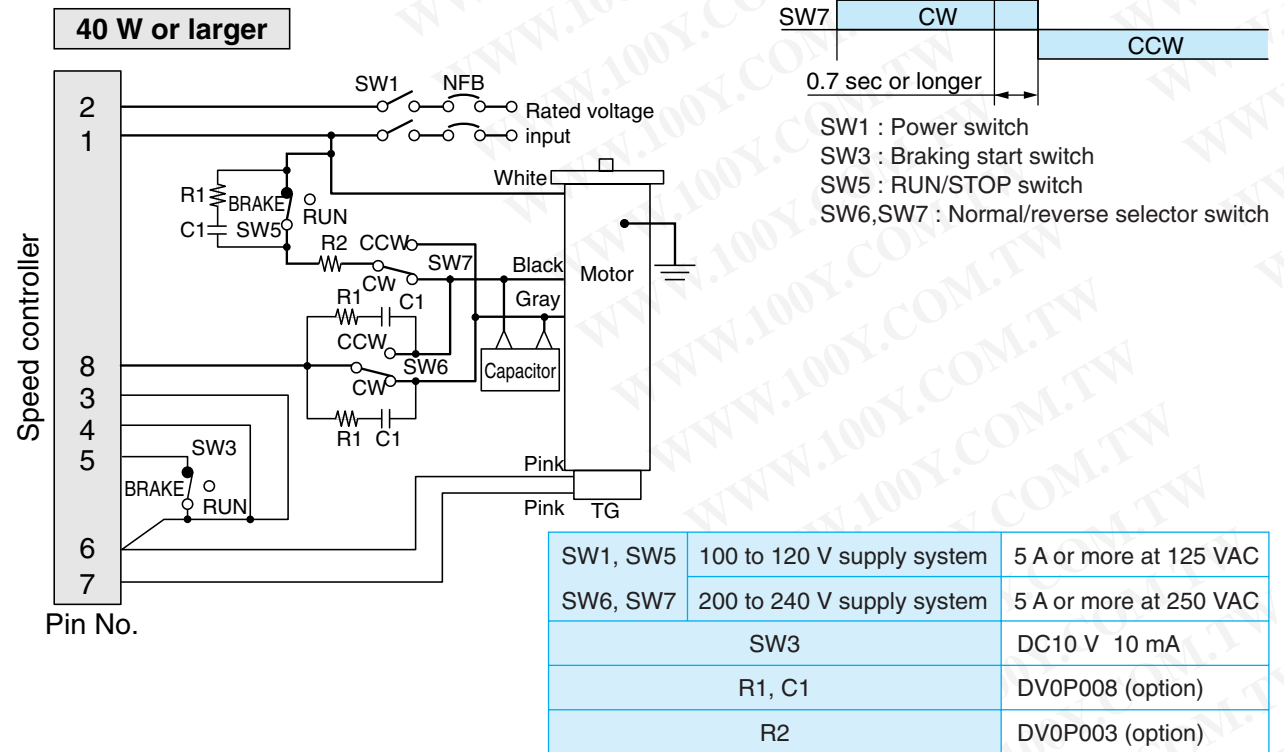
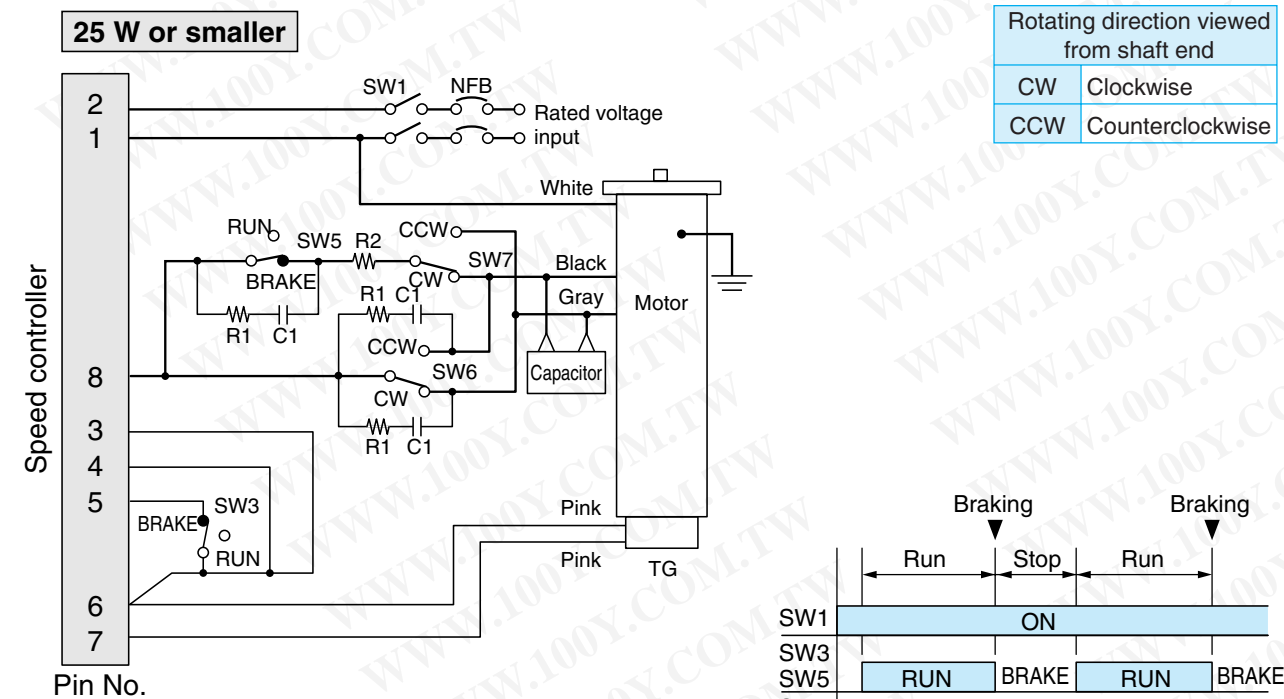
SW1	100 to 120 V supply system	5 A or more at 125 VAC
SW5	200 to 240 V supply system	5 A or more at 250 VAC
SW3	DC10 V 10 mA	
R1, C1	DV0P008 (option)	
R2	DV0P003 (option)	

### <Precautions>

- When SW3 and SW5 are moved from RUN to STOP, electric braking operates for approx. 0.5 sec causing the motor to stop immediately. SW3 and SW5 must be turned on/off simultaneously. Otherwise, abnormal operation occurs (full speed rotation for a short time), causing the motor temperature to rise excessively.
- The number of start/stop operations must be 6/min. or less.
- For motors for cooling fan and motors with thermal protector, also refer to page C-27.
- The spark killer consisting of R1 and C1 must be used to protect the relay contacts.
- R2 limits flow of discharging current upon short-circuiting of the capacitor during braking.

\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

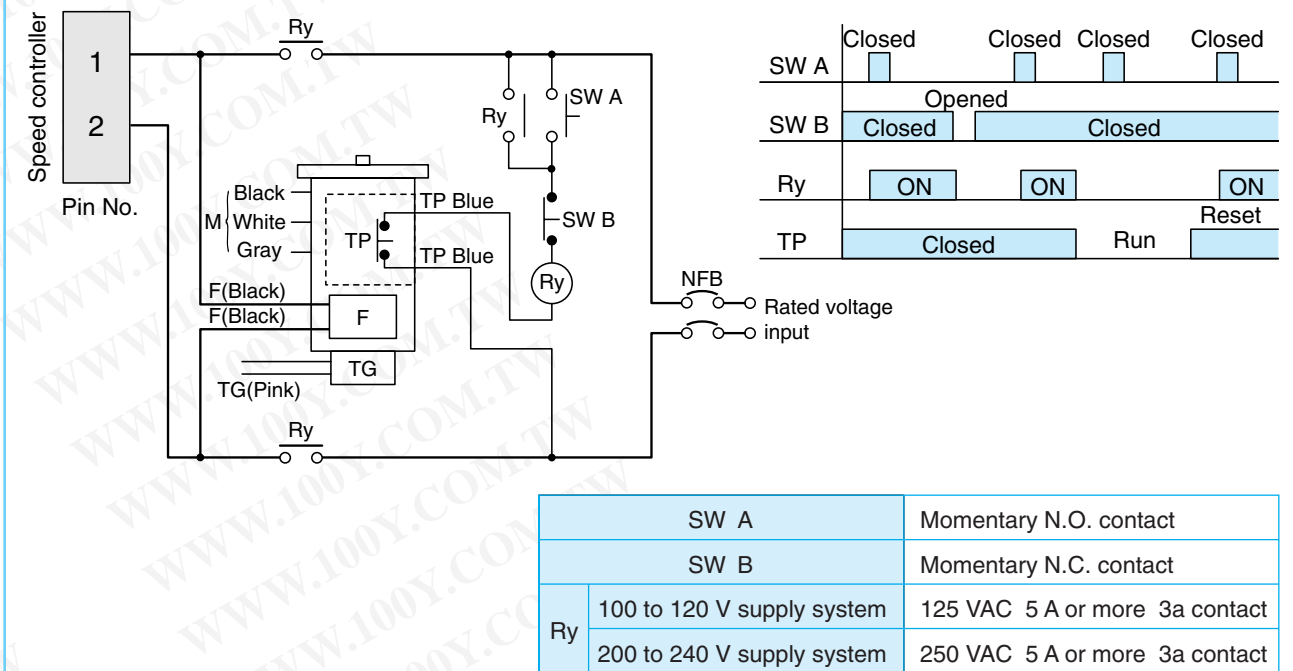
## 4 Normal/reverse rotation and electric brake



- <Precautions>**
- When SW3 and SW5 are moved from RUN to STOP, electric braking operates for approx. 0.5 sec causing the motor to stop immediately. (Do not operate SW6 and SW7 until the motor stops completely.) SW3 and SW5 must be turned on/off simultaneously. Otherwise, abnormal operation occurs (full speed rotation for a short time), causing the motor temperature to rise excessively.
  - Never change the direction of rotation (CCW/CW, SW6, SW7) while the motor is running.
  - The number of start/stop cycles must be 6/min. or less.
  - When using cooling fan motor or motor with thermal protector, also see page C-27.
  - Insert R1 and C1 to protect relay contact.
  - R2 restricts discharge current in case of capacitor short circuit during braking.

\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

## 5 Wiring of cooling fan motor (F) or motor with thermal protector (TP)

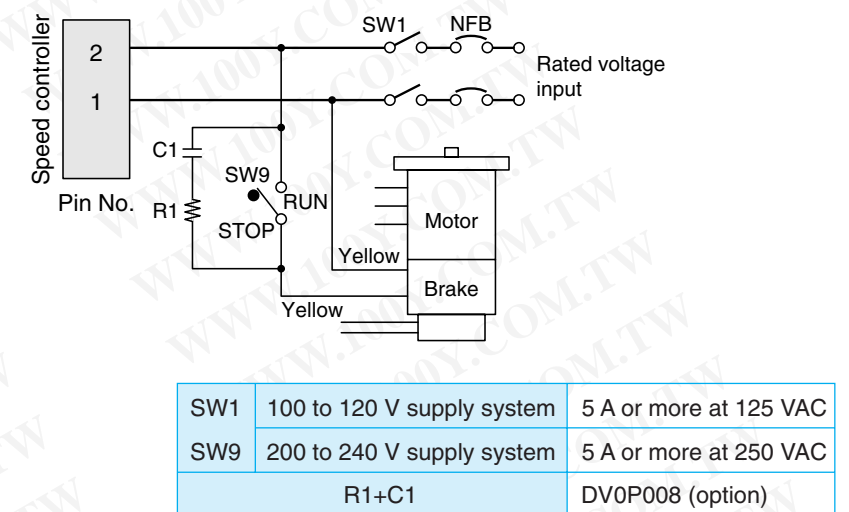


**<Precautions>**

- The thermal protector (TP) is an automatic reset type. To prevent hazards caused by restarting, connect the TP as shown above. Don't connect TP directly to the power supply.
- Once the TP operates, cooling period is required before the operation can restart.
- Connect the cooling fan motor (F) across pins 1 and 2 on the power terminal.
- Motor (M) and tachometer generator (TG) should be connected according to corresponding wiring diagram shown later.

## 6 Wiring to electromagnetic brake

- Variable speed motor with electromagnetic brake should be wired as shown below.



**<Precautions>**

- Operate SW9 simultaneously with RUN/STOP (BRAKE) switching of other switches, if any. Placing other switches to RUN position while the brake is active (SW9 at STOP position) causes the motor to generate heat.
- For remaining wirings, refer to corresponding wiring diagram.

\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

### 7 Wiring diagram (for unidirectional rotation)

- The thick continuous lines represent main circuit. Use conductor of size approx. 0.75 mm<sup>2</sup>.
  - The thin continuous lines represent signal circuit. Use conductor of size approx. 0.3 mm<sup>2</sup>.
- When the distance from the tachometer generator (TG) is long, use shielded twisted pair cable.

#### • Soft-start/down control

Soft-start and soft-down times can be adjusted by a single setting. Use this feature to protect the load from shock caused by sharp speed change at startup and shutdown of the motor.  
 To disable the soft operation, turn the control fully clockwise.

#### • Maximum speed control

Use this control to adjust the revolving speed when the external speed changer is set at the top speed. Adjust the speed to 1400 (min-1) or below at 50 Hz; or 1700 (min-1) or below at 60 Hz. If the external speed setting is not required, the maximum speed control can also be used for setting the speed.

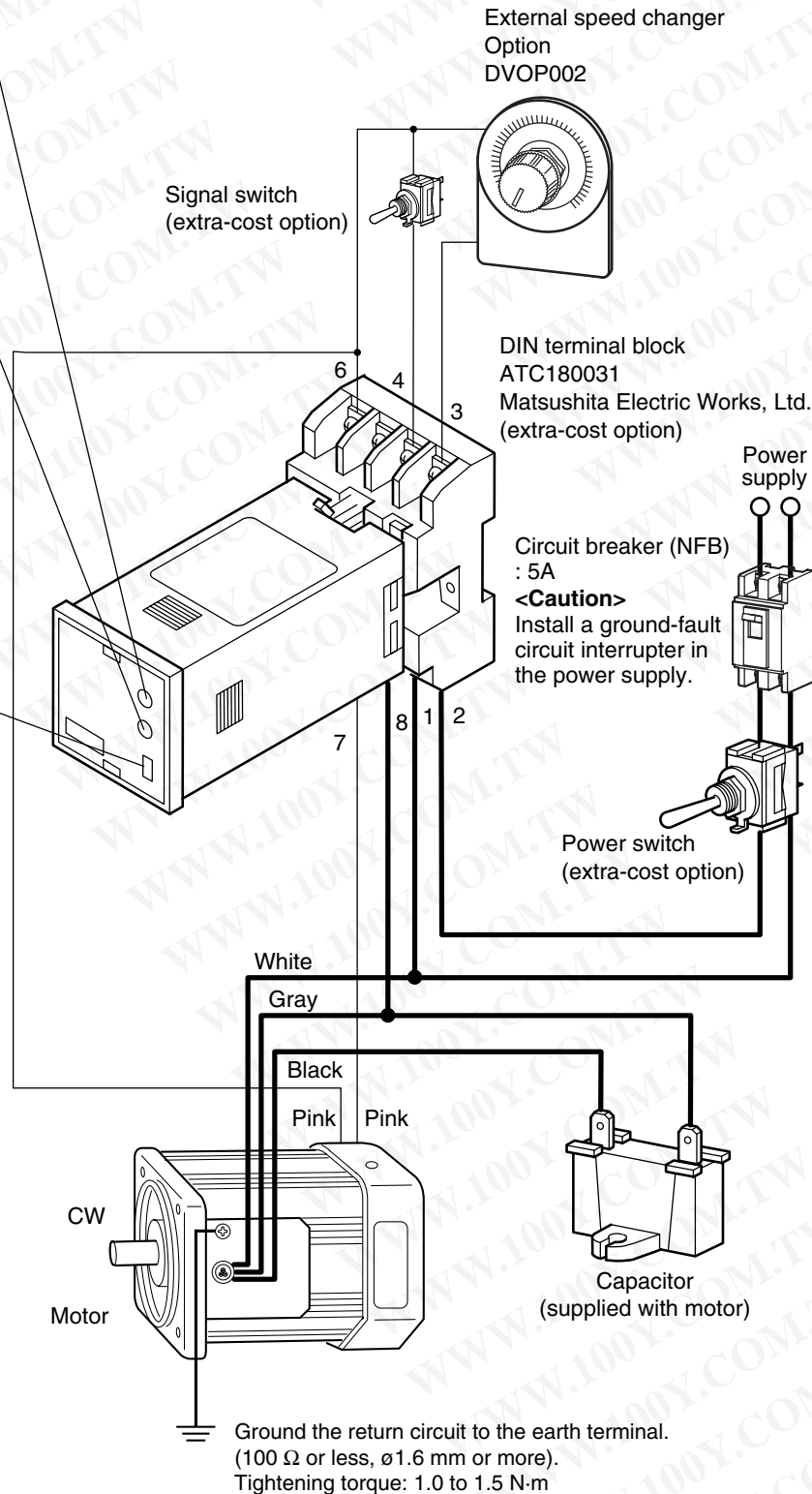
#### • Response changeover switch

##### A: High-stable mode

- Keeps the rotation speed variation low against variation in load.
- Enables a wide range of speed control.
- Suitable for capability control.
- May fail to maintain constant rotation speed upon sharp load change.

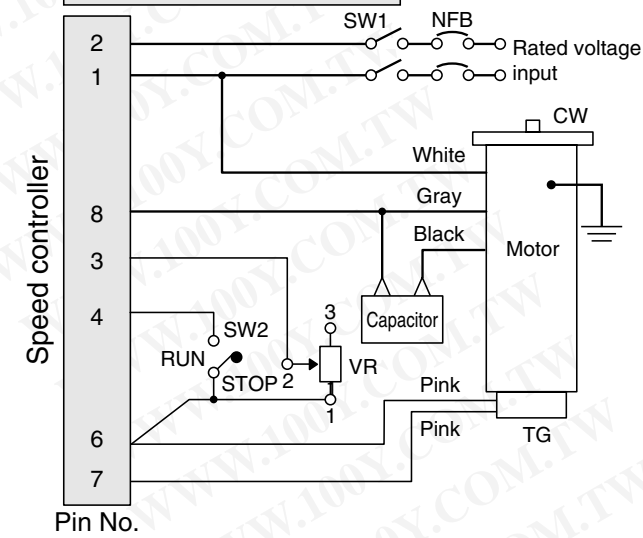
##### B: High-response mode

- Enables quick response with low hunting.
- Suitable for positioning application.
- May fail to keep rotation speed variation low against variation in load.
- Not suitable for controlling wide range of speed change.

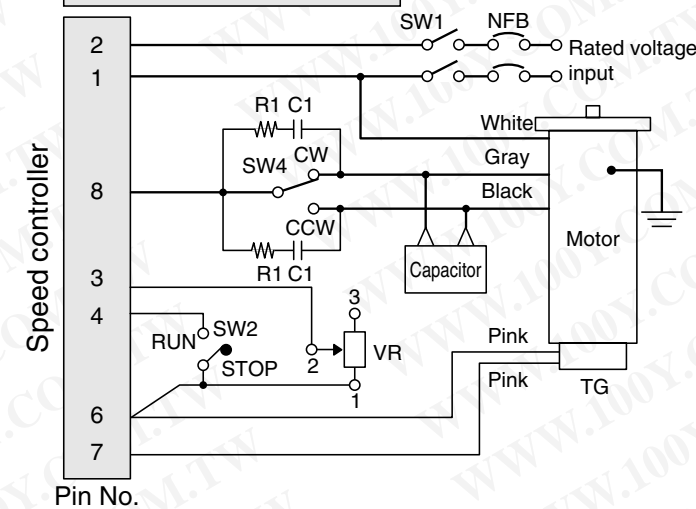


### 8 Speed change only

#### Unidirectional rotation



#### Normal/reverse rotation

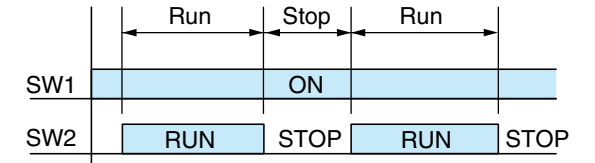


#### <Precautions>

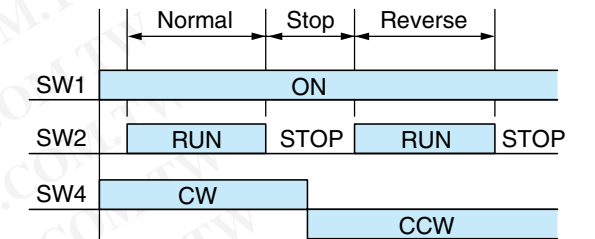
- To change rotating direction of induction motor: Provide a motor halt period. Switch over SW2 after complete stop of the motor.
- To change rotating direction of reversible motor: A motor halt period is not necessary. Switch over SW2 while keeping SW1 turned ON. When configuring SW2 with relay contacts, use a relay having large gap between contacts (e.g. HG/HP relay from Matsushita Electric Works, Ltd.) to prevent malfunction due to short-circuited capacitor.
- For motors for cooling fan and motors with thermal protector, also refer to page C-35.
- When using independent relay contacts for SW2 to change over normal/reverse, interlock both contacts so that they will not close simultaneously.
- The spark killer consisting of R1 and C1 must be used to protect the relay contacts.

Rotating direction viewed from shaft end	
CW	Clockwise
CCW	Counterclockwise

- This wiring diagram causes the motor to rotate clockwise when viewed from the motor shaft end. To run the motor counterclockwise, interchange the connecting point of black and gray leads. interchange the connecting point of black and gray leads.



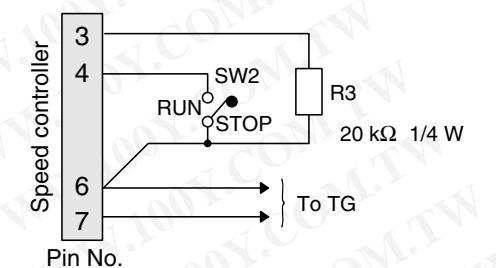
SW1	100 to 120 V supply system	5 A or more at 125 VAC
SW4	200 to 240 V supply system	5 A or more at 250 VAC
SW2		DC10 V 10 mA
R1, C1		DV0P008 (option)
VR		DV0P003 (option)



SW1 : Power switch  
 SW2 : RUN/STOP switch  
 SW4 : Normal/reverse selector switch

#### Operation from maximum speed control

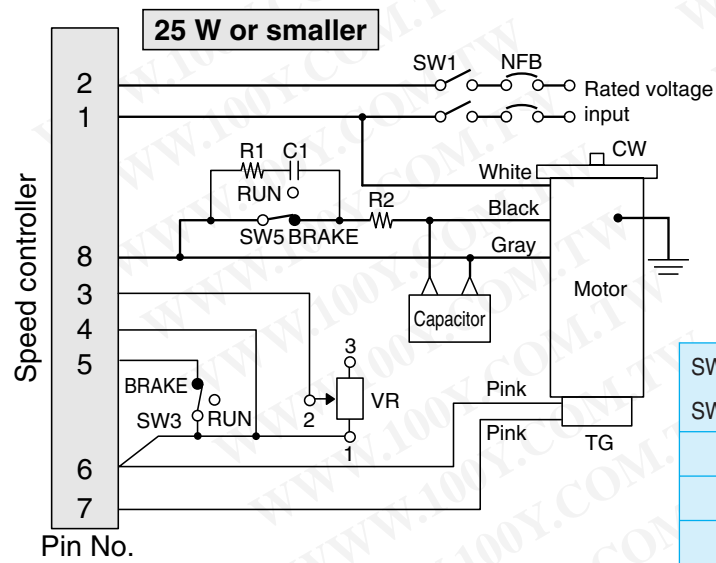
- When no external speed changer is required, the speed can be adjusted from the maximum speed control.



#### <Precautions>

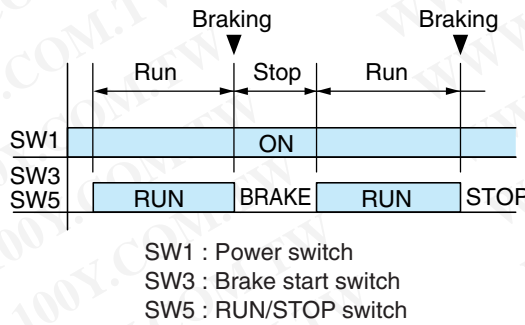
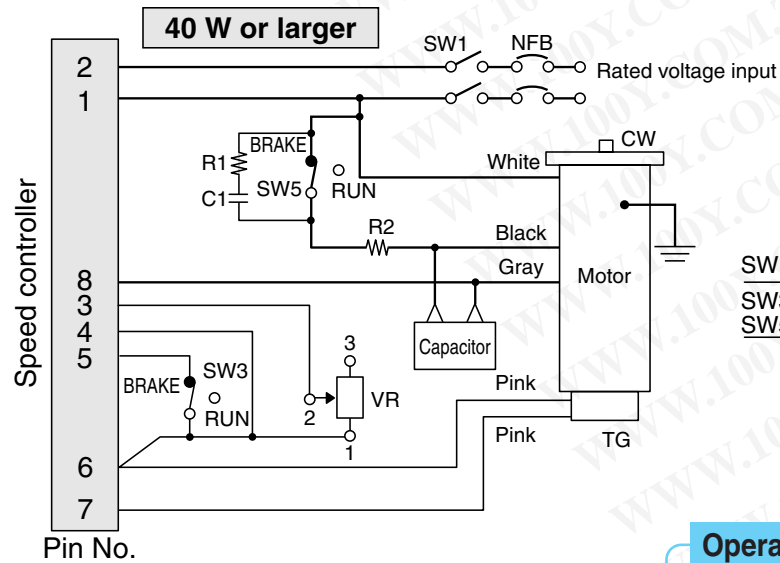
Connect a fixed resistor (R3) in place of external speed changer (VR). Even if the R3 is not used (connection across pins 3 and 6 are open), the speed can be adjusted from the maximum speed control within its adjustable range (not full range but almost by half).

9 Unidirectional rotation and electric brake



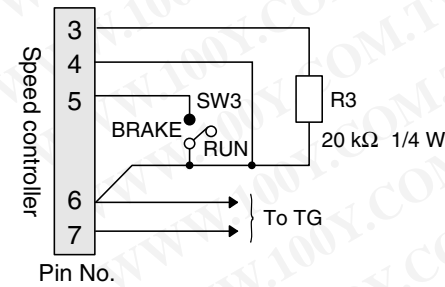
• Connection according to this wiring diagram causes the motor to rotate clockwise when viewed from the motor shaft end. To run the motor counterclockwise, interchange the connecting point of black and gray leads.

SW1	100 to 120 V supply system	5 A or more at 125 VAC
SW5	200 to 240 V supply system	5 A or more at 250 VAC
SW3		DC10 V 10 mA
R1, C1		DV0P008 (option)
R2		DV0P003 (option)
VR		DV0P002 (option)



Operation from maximum speed control

• When no external speed changer is required, the speed can be adjusted from the maximum speed control.

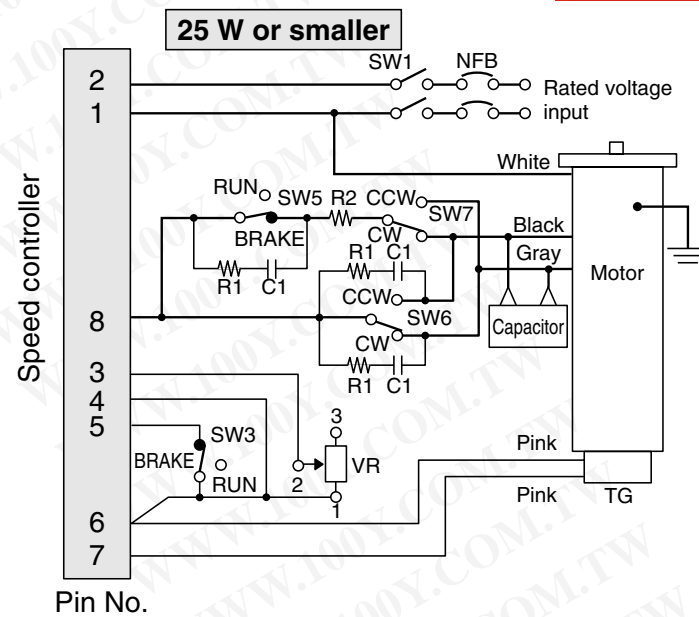


**<Precautions>**  
 Connect a fixed resistor (R3) in place of external speed changer (VR). Even if the R3 is not used (connection across pins 3 and 6 are open), the speed can be adjusted from the maximum speed control within its adjustable range (not full range but almost by half).

- <Precautions>**
- When SW3 and SW5 are switched from RUN to STOP, electric braking is applied for approx. 5 sec, or until the motor stops. SW3 and SW5 must be operated simultaneously. Otherwise, abnormal operation occurs (full speed rotation for a short time), causing the motor temperature to rise excessively.
  - The number of start/stop cycles must be 6/min. or less.
  - When using cooling fan motor or motor with thermal protector, also see page C-35.
  - Insert R1 and C1 to protect relay contact.
  - R2 restricts discharge current in case of capacitor short circuit during braking.

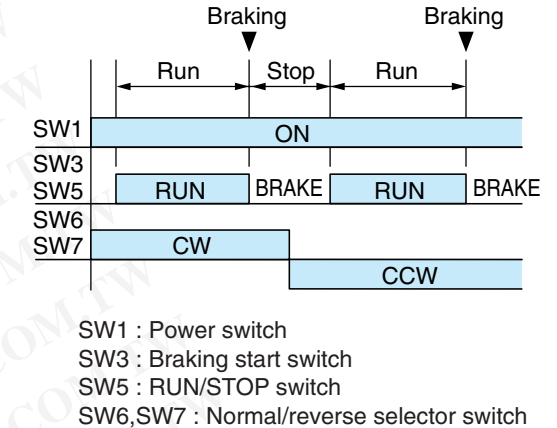
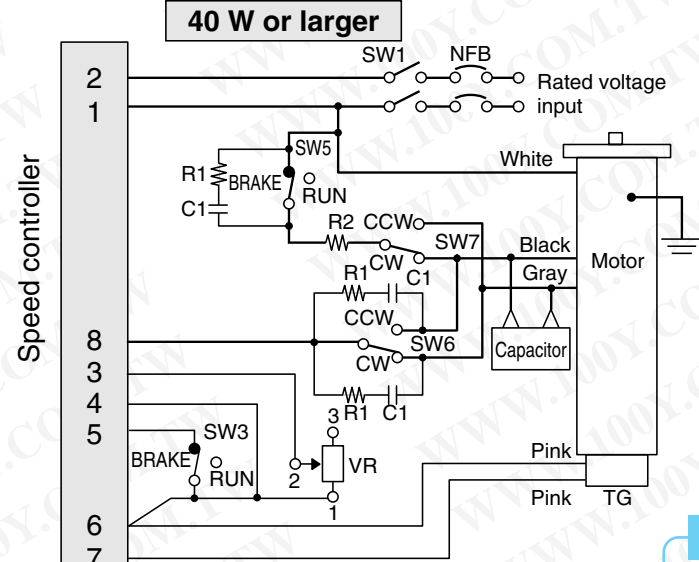
\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

10 Normal/reverse rotation and electric brake



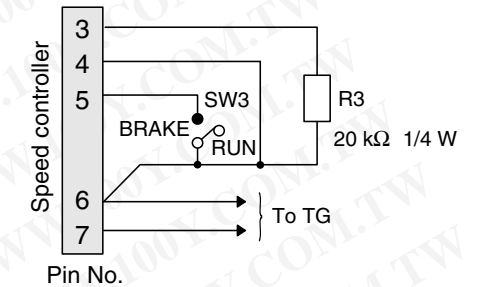
Rotating direction viewed from shaft end	
CW	Clockwise
CCW	Counterclockwise

SW1, SW5	100 to 120 V supply system	5 A or more at 125 VAC
SW6, SW7	200 to 240 V supply system	5 A or more at 250 VAC
SW3		DC10 V 10 mA
R1, C1		DV0P008 (option)
R2		DV0P003 (option)
VR		DV0P002 (option)



Operation from maximum speed control

• When no external speed changer is required, the speed can be adjusted from the maximum speed control.

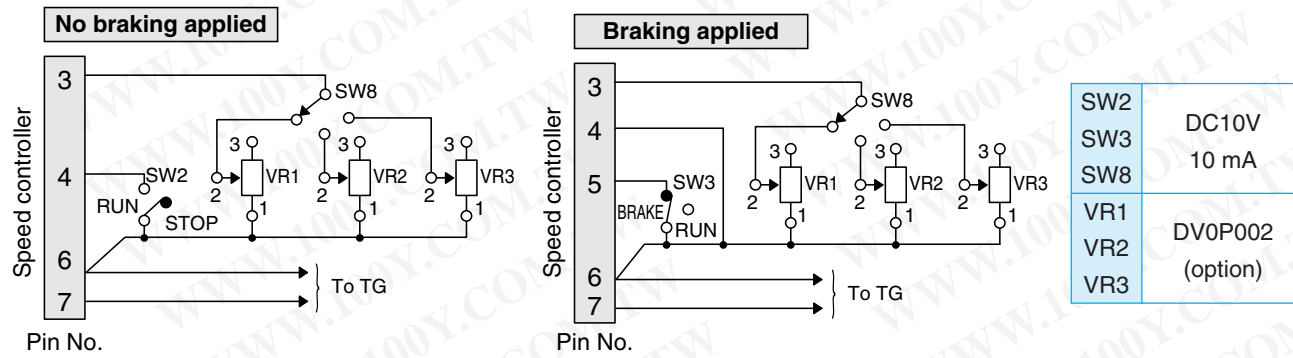


**<Precautions>**  
 Connect a fixed resistor (R3) in place of external speed changer (VR). Even if the R3 is not used (connection across pins 3 and 6 are open), the speed can be adjusted from the maximum speed control within its adjustable range (not full range but almost by half).

- <Precautions>**
- When SW3 and SW5 are switched from RUN to STOP, electric braking is applied for approx. 5 sec, or until the motor stops. (Do not operate SW6 and SW7 until the motor stops completely.) SW3 and SW5 must be operated simultaneously. Otherwise, abnormal operation occurs (full speed rotation for a short time), causing the motor temperature to rise excessively.
  - Do not change the rotating direction (SW6, SW7) while the motor is running.
  - The number of start/stop cycles must be 6/min. or less.
  - When using cooling fan motor or motor with thermal protector, also see page C-35.
  - Insert R1 and C1 to protect relay contact.
  - R2 restricts discharge current in case of capacitor short circuit during braking.

\* Please read your User's manual carefully so that you will understand the operation and safety precautions before attempting to operate the system.

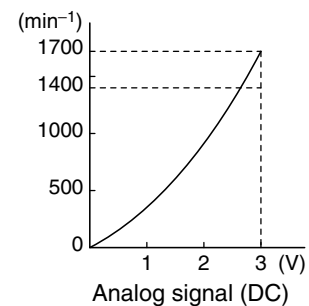
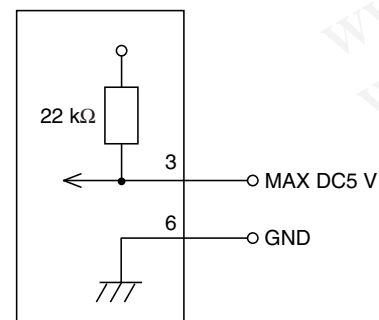
## 11 Multispeed setting application



### <Precautions>

- Set external speed changers VR1, VR2 and VR3 to 3 different speeds and select the desired speed from SW8.
- When activating the brake, simultaneously switch over SW3 and RUN-STOP of other switches.
- For remaining wirings, refer to the corresponding wiring diagrams.

## 12 Speed change with analog signal



### <Precautions>

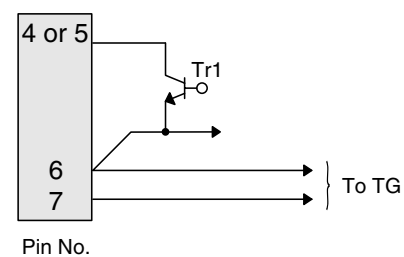
- Soft-operation can be adjusted from the soft-start and soft-down controls or by using analog signal.
- The absolute maximum rating of analog signal is 5 VDC. The system should be designed to use standard 3 VDC analog signal. If the signal voltage exceeds 3 VDC, the circuit diagram shown below should be used for wiring.
 

$$R2 \geq \frac{e_{max}}{3} - 1 \text{ k}\Omega$$

$e_{max}$  : Analog signal max. voltage  
 R1 : External resistor: 1 kW  
 R2 : External resistor
- Revolution speed "0" signal should not exceed 0.1 VDC.
- The percentage ripple of analog voltage signal should be 2% or less.
- For other wirings, refer to the corresponding circuit/wiring diagrams.

## 13 Operation through contactless signal

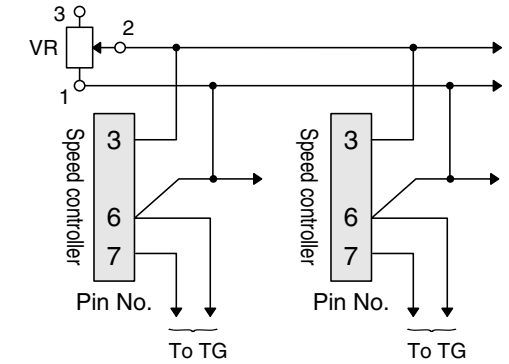
- Small signal relays SW2 and SW3 can be replaced with transistor.



## 14 Parallel operation through external speed changer

### <Precautions>

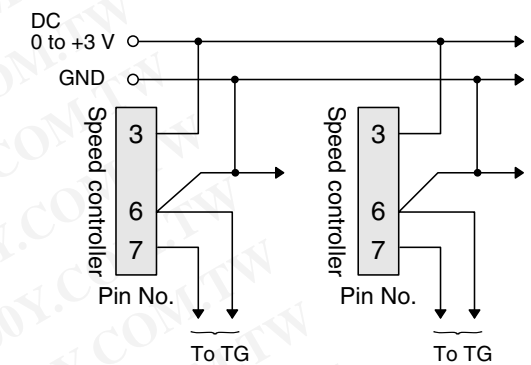
- The resistance  $R_s$  of the external speed changer VR should be as follows:  
 $R_s = 20/N \text{ (k}\Omega\text{)}$   
 where, N is the number of motors.
- For synchronous operation or ratio operation, desired revolving speeds must be set from the maximum speed control. Soft-start and soft-down controls and operation changeover switch must be set to the same position.
- Wirings from the external speed changer VR should be connected to the same pins (No.3 and No.6) on the controller.
- Malfunction may occur as the number of devices operated in parallel increases. To secure correct operation, connect a noise filter to each unit.
- For other electrical connections, refer to corresponding circuit/wiring diagrams.



## 15 Parallel operation through analog signal

### <Precautions>

- The input impedance of the controller is approx. 22 kΩ. The output impedance of the analog signal source should be determined based on the total input impedance of the speed controllers. For other precautions, refer to [14] Parallel operation through external speed changer and [12] Speed change with analog signal.





## 16 Soft-operation

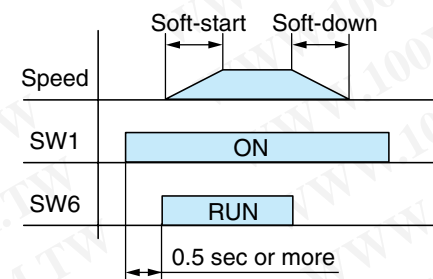
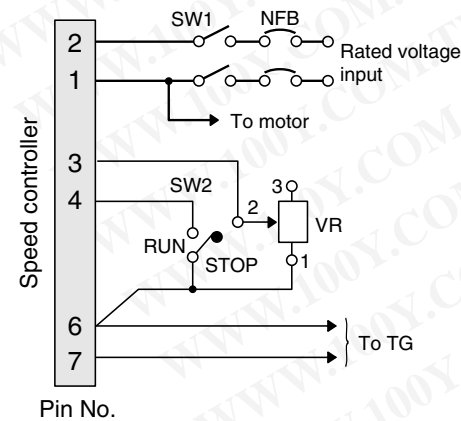
### • Soft-start, soft-down

#### <Precautions>

1. Power switch SW1 should be turned on approx. 0.5 sec before the operation start signal from SW6.
2. When repeating run/stop cycles, turn on/off only SW6 while keeping SW1 turned ON. In this way, the motor can be controlled by using a small signal. To stop operation for a long time, also turn off SW1.
3. Soft-start/soft-down period is the time required for the equipment to start up from stop state to full speed when the external speed changer is set at maximum value.
4. Soft-start/soft-down control, when at the full clockwise position, disables the soft-start/soft-down function.

As the stop signal is input, power supply to the motor is turned off immediately. However, the revolving speed gradually decreases in proportion to the inertia of the load and motor starts free-running stop sequence.

5. Soft-start/soft-down control can set maximum time length of approx. 5 seconds (Typ. at FCCW). The setting may be exceeded if the inertia of the load is too large.
6. For other electrical connections, refer to corresponding circuit/wiring diagrams.

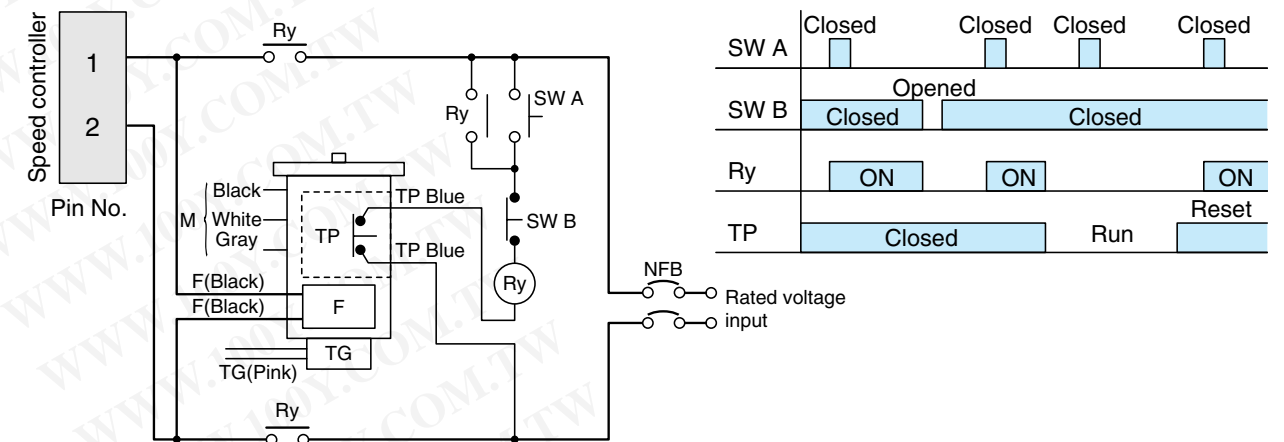


SW1	100 to 120 V supply system	5 A or more at 125 VAC
	200 to 240 V supply system	5 A or more at 250 VAC
SW2	DC10 V 10 mA	
VR	DV0P002 (option)	

### • Soft-start and electric brake

Electrical wirings are the same as for "Unidirectional rotation and electric brake" and "Normal/reverse rotation and electric brake". Adjust the soft-start time from the soft-start/soft-down control.

## 17 Wiring of cooling fan motor and motor with thermal protector (TP)



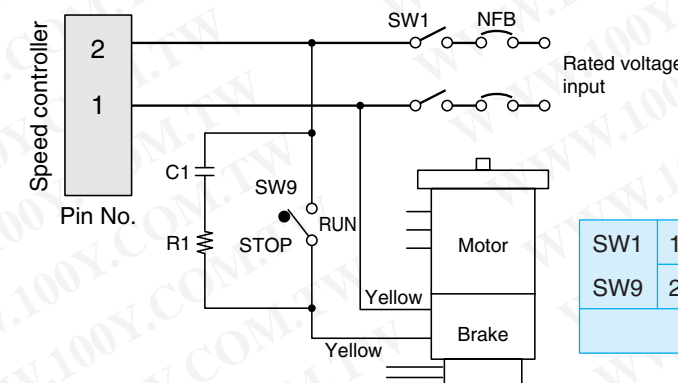
SW A	Momentary N.O. contact	
SW B	Momentary N.C. contact	
Ry	100 to 120 V supply system	5 A or more at 125 VAC 3a contact
	200 to 240 V supply system	5 A or more at 250 VAC 3a contact

#### <Precautions>

1. The thermal protector (TP) is an automatic reset type. To prevent hazards caused by restarting, connect the TP as shown above. Don't connect TP directly to the power supply.
2. Once the TP operates, cooling period is required before the operation can restart.
3. Connect the cooling fan motor (F) across pins 1 and 2 on the power terminal.
4. Motor (M) and tachometer generator (TG) should be connected according to corresponding wiring diagram shown later.

## 18 Wiring to electromagnetic brake

- Variable speed motor with electromagnetic brake should be wired as shown below.



SW1	100 to 120 V supply system	5 A or more at 125 VAC
SW9	200 to 240 V supply system	5 A or more at 250 VAC
R1+C1	DV0P008 (option)	

#### <Precautions>

1. SW9 should be switched to RUN or STOP at the same time as the other switches are switched to RUN or STOP. If the other switches are set to RUN while the brake is energized (SW9 in STOP position), the motor will generate heat.
2. For other wirings, refer to the corresponding circuit/wiring diagrams.