Philips Semiconductors Product specification

# Phase-locked loop

NE/SE564

#### DESCRIPTION

The NE/SE564 is a versatile, high guaranteed frequency phase-locked loop designed for operation up to 50MHz. As shown in the Block Diagram, the NE/SE564 consists of a VCO, limiter, phase comparator, and post detection processor.

#### **FEATURES**

- Operation with single 5V supply
- TTL-compatible inputs and outputs
- Guaranteed operation to 50MHz
- External loop gain control
- Reduced carrier feedthrough
- No elaborate filtering needed in FSK applications
- Can be used as a modulator
- Variable loop gain (externally controlled)

#### **APPLICATIONS**

- High speed modems
- FSK receivers and transmitters
- Frequency Synthesizers

#### **PIN CONFIGURATIONS**

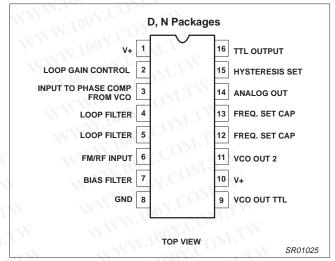


Figure 1. Pin Configuration

- Signal generators
- Various satcom/TV systems
- pin configuration

#### **ORDERING INFORMATION**

DESCRIPTION	TEMPERATURE RANGE	ORDER CODE	DWG#
16-Pin Plastic Small Outline (SO) Package	0 to +70°C	NE564D	SOT109-1
16-Pin Plastic Dual In-Line Package (DIP)	0 to +70°C	NE564N	SOT38-4
16-Pin Plastic Dual In-Line Package (DIP)	-55 to +125°C	SE564N	SOT38-4

#### **BLOCK DIAGRAM**

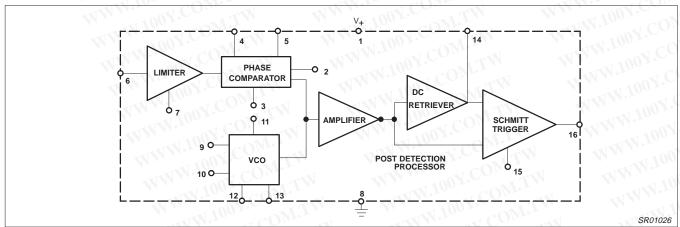


Figure 2. Block Diagram

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#### **ABSOLUTE MAXIMUM RATINGS**

SYMBOL	PARAMETER	RATING	UNITS
OM V+	Supply voltage Pin 1 Pin 10	14 6	V
l <sub>OUT</sub>	Sink Max (Pin 9) and sourcing (Pin 11)	CON-11	mA
I <sub>BIAS</sub>	Bias current adjust pin (sinking)	111	mA
P <sub>D</sub>	Power dissipation	600	mW
, CT <sub>A</sub>	Operating ambient temperature NE	0 to +70	°C
COM	SE WWW. COM WWW.	-55 to +125	°C
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C

## DC AND AC ELECTRICAL CHARACTERISTICS

SYMBOL	$_{\Lambda}$ = 0 to 25°C; $f_{O}$ = 5MHz, $I_{2}$ = 40	TEST CONDITIONS	LIMITS		LIMITS		1		
			SE564		NE564		T.Mc	UNITS	
			MIN	TYP	MAX	MIN	TYP	MAX	
WW	Maximum VCO frequency	C <sub>1</sub> = 0 (stray)	50	65	TIN S	45	60	Ohr.	MHz
WWW	Lock range	$\begin{aligned} & \text{Input} \geq 200\text{mV}_{\text{RMS}} \\ & T_{\text{A}} = 25^{\circ}\text{C} \\ & T_{\text{A}} = 125^{\circ}\text{C} \\ & T_{\text{A}} = -55^{\circ}\text{C} \\ & T_{\text{A}} = 0^{\circ}\text{C} \\ & T_{\text{A}} = 70^{\circ}\text{C} \end{aligned}$	40 20 50	70 30 80	N	40	70 70 40	COM	% of f <sub>O</sub>
W.	Capture range	Input $\geq$ 200mV <sub>RMS</sub> , R <sub>2</sub> = 27 $\Omega$	20	30		20	30	-10	% of f <sub>O</sub>
N	VCO frequency drift with temperature	$\begin{split} f_O &= 5 \text{MHz}, \\ T_A &= -55^{\circ} \text{C to } + 125^{\circ} \text{C} \\ T_A &= 0 \text{ to } + 70^{\circ} \text{C} \\ &= 0 \text{ to } + 70^{\circ} \text{C} \\ f_O &= 5 \text{MHz}, \\ T_A &= -55^{\circ} \text{C to } + 125^{\circ} \text{C} \\ T_A &= 0 \text{ to } + 70^{\circ} \text{C} \end{split}$	CON V.CO	500 300	1500	77	600 500	7 100 7007 7007	PPM/°C
	VCO free-running frequency	$C_1 = 91pF$ $R_C = 100\Omega$ "Internal"	0(4).	5	6	3.5	5	6.5	MHz
	VCO frequency change with supply voltage	V <sub>CC</sub> = 4.5V to 5.5V	100X	3	8	ī	3	8	% of f <sub>O</sub>
	Demodulated output voltage	Modulation frequency: 1kHz $f_O = 5$ MHz, input deviation: $2\%T = 25^{\circ}$ C $1\%T = 25^{\circ}$ C $1\%T = 0^{\circ}$ C $1\%T = -55^{\circ}$ C $1\%T = 70^{\circ}$ C $1\%T = 125^{\circ}$ C	16 8 6	28 14 10	CON CONT DWT. W.T.	16 8	28 14 13 15	WW.	mV <sub>RMS</sub> mV <sub>RMS</sub> mV <sub>RMS</sub> mV <sub>RMS</sub> mV <sub>RMS</sub>
	Distortion	Deviation: 1% to 8%	-133	140	~O1	1.7.	_ 1		%
S/N	Signal-to-noise ratio	Std. condition, 1% to 10% dev.	MAN.	40		TI	40	1	dB
	AM rejection	Std. condition, 30% AM	WIN	35	V.C	) } ` 1	35	4	dB
	Demodulated output at operating voltage	Modulation frequency: 1kHz $f_O = 5$ MHz, input deviation: 1% $V_{CC} = 4.5$ V $V_{CC} = 5.5$ V	7 8	12 14	00X.C	7 8	12 14		mV <sub>RMS</sub> mV <sub>RMS</sub>
I <sub>CC</sub>	Supply current	$V_{CC} = 5V I_1, I_{10}$	<b>41</b>	45	60	$C_{O_{L}}$	45	60	mA
	Output "1" output leakage current "0" output voltage	V <sub>OUT</sub> = 5V, Pins 16, 9 I <sub>OUT</sub> = 2mA, Pins 16, 9 I <sub>OUT</sub> = 6mA, Pins 16, 9		1 0.3 0.4	20 0.6 0.8	N.CO	1 0.3 0.4	20 0.6 0.8	μA V V

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# Phase-locked loop

NE/SE564

#### TYPICAL PERFORMANCE CHARACTERISTICS

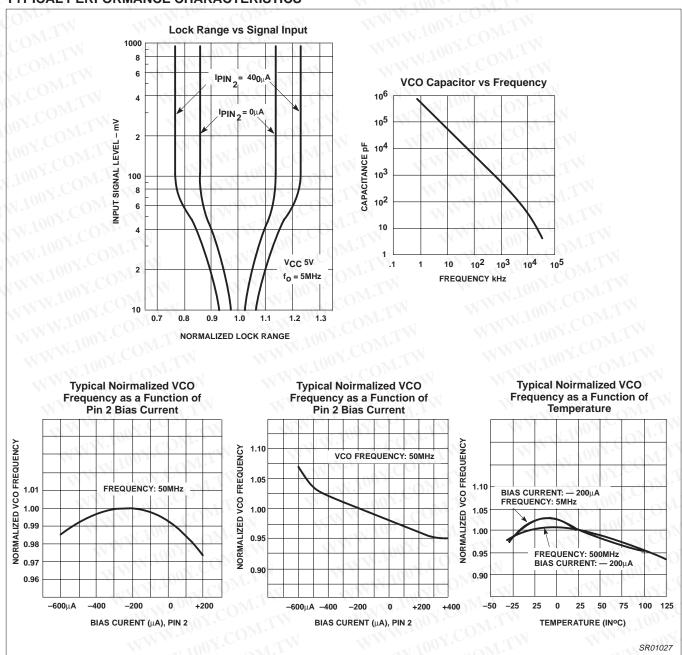


Figure 3. Typical Performance Characteristics

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# Phase-locked loop

NE/SE564

## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

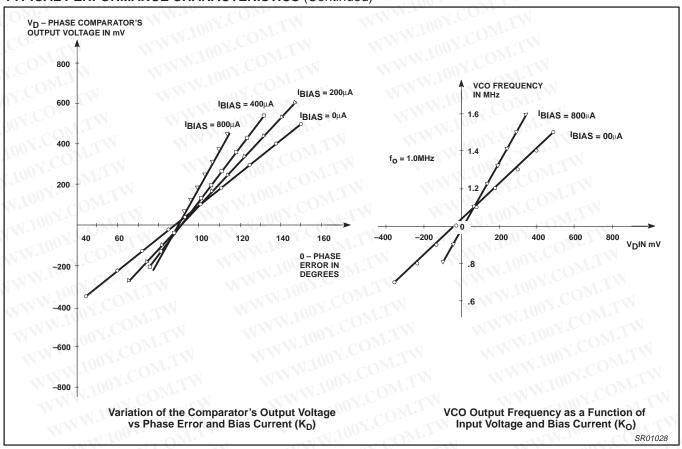


Figure 4. Typical Performance Characteristics (cont.)

#### **TEST CIRCUIT**

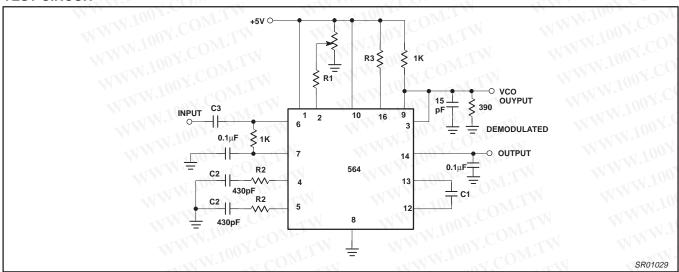


Figure 5. Test Circuit

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## Phase-locked loop

NE/SE564

#### FUNCTIONAL DESCRIPTION

## (Figure 6)

The NE564 is a monolithic phase-locked loop with a post detection processor. The use of Schottky clamped transistors and optimized device geometries extends the frequency of operation to greater than 50MHz.

In addition to the classical PLL applications, the NE564 can be used as a modulator with a controllable frequency deviation.

The output of the PLL can be written as shown in the following equation:

$$V_{O} = \frac{(f_{IN} - f_{O})}{K_{VCO}} \tag{1}$$

K<sub>VCO</sub> = conversion gain of the VCO

f<sub>IN</sub> = frequency of the input signal

f<sub>O</sub> = free-running frequency of the VCO

The process of recovering FSK signals involves the conversion of the PLL output into logic compatible signals. For high data rates, a considerable amount of carrier will be present at the output of the PLL due to the wideband nature of the loop filter. To avoid the use of complicated filters, a comparator with hysteresis or Schmitt trigger is required. With the conversion gain of the VCO fixed, the output voltage as given by Equation 1 varies according to the frequency deviation of  $f_{\rm IN}$  from  $f_{\rm O}$ . Since this differs from system to system, it is necessary that the hysteresis of the Schmitt trigger be capable of being changed, so that it can be optimized for a particular system. This is accomplished in the 564 by varying the voltage at Pin 15 which results in a change of the hysteresis of the Schmitt trigger.

For FSK signals, an important factor to be considered is the drift in the free-running frequency of the VCO itself. If this changes due to temperature, according to Equation 1 it will lead to a change in the DC levels of the PLL output, and consequently to errors in the digital output signal. This is especially true for narrowband signals where the deviation in  $f_{\rm IN}$  itself may be less than the change in  $f_{\rm O}$  due to temperature. This effect can be eliminated if the DC or average value of the signal is retrieved and used as the reference to the comparator. In this manner, variations in the DC levels of the PLL output do not affect the FSK output.

#### **VCO Section**

Due to its inherent high-frequency performance, an emitter-coupled oscillator is used in the VCO. In the circuit, shown in the equivalent schematic, transistors Q21 and Q23 with current sources Q25 - Q26 form the basic oscillator. The approximate free-running frequency of the oscillator is shown in the following equation:

$$f_O \cong \frac{1}{22 R_C (C_1 + C_S)}$$
 (2)

 $R_C = R_{19} = R_{20} = 100\Omega$  (INTERNAL)

C<sub>1</sub> = external frequency setting capacitor

C<sub>S</sub> = stray capacitance

Variation of  $V_D$  (phase detector output voltage) changes the frequency of the oscillator. As indicated by Equation 2, the frequency of the oscillator has a negative temperature coefficient due to the monolithic resistor. To compensate for this, a current  $I_R$  with negative temperature coefficient is introduced to achieve a low frequency drift with temperature.

## **Phase Comparator Section**

The phase detection processor consists of a doubled-balanced modulator with a limiter amplifier to improve AM rejection. Schottky-clamped vertical PNPs are used to obtain TTL level inputs. The loop gain can be varied by changing the current in  $\mathsf{Q}_4$  and  $\mathsf{Q}_{15}$  which effectively changes the gain of the differential amplifiers. This can be accomplished by introducing a current at Pin 2.

#### **Post Detection Processor Section**

The post detection processor consists of a unity gain transconductance amplifier and comparator. The amplifier can be used as a DC retriever for demodulation of FSK signals, and as a post detection filter for linear FM demodulation. The comparator has adjustable hysteresis so that phase jitter in the output signal can be eliminated.

As shown in the equivalent schematic, the DC retriever is formed by the transconductance amplifier  $Q_{42}$  -  $Q_{43}$  together with an external capacitor which is connected at the amplifier output (Pin 14). This forms an integrator whose output voltage is shown in the following equation:

$$V_{O} = \frac{g_{M}}{C_{2}} \quad V_{IN}dt \tag{3}$$

g<sub>M</sub> = transconductance of the amplifier

 $C_2$  = capacitor at the output (Pin 14)

V<sub>IN</sub> = signal voltage at amplifier input

With proper selection of  $C_2$ , the integrator time constant can be varied so that the output voltage is the DC or average value of the input signal for use in FSK, or as a post detection filter in linear demodulation.

The comparator with hysteresis is made up of  $Q_{49}$  -  $Q_{50}$  with positive feedback being provided by  $Q_{47}$  -  $Q_{48}$ . The hysteresis is varied by changing the current in  $Q_{52}$  with a resulting variation in the loop gain of the comparator. This method of hysteresis control, which is a DC control, provides symmetric variation around the nominal value.

### **Design Formula**

The free-running frequency of the VCO is shown by the following equation:

$$f_O \cong \frac{1}{22 R_C (C_1 + C_S)}$$
 (4)

 $R_C = 100\Omega$ 

C<sub>1</sub> = external cap in farads

C<sub>S</sub> = stray capacitance

The loop filter diagram shown is explained by the following equation:

$$f_{S} = \frac{1}{1 + sRC_{3}}$$
 (First Order) (5)

 $R = R_{12} = R_{13} = 1.3k\Omega$  (Internal)\*

By adding capacitors to Pins 4 and 5, a pole is added to the loop transfer at

$$ω = \frac{1}{RC_3}$$
NOTE:
\*Refer to Figure 6.

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#### **EQUIVALENT SCHEMATIC**

Phase-locked loop

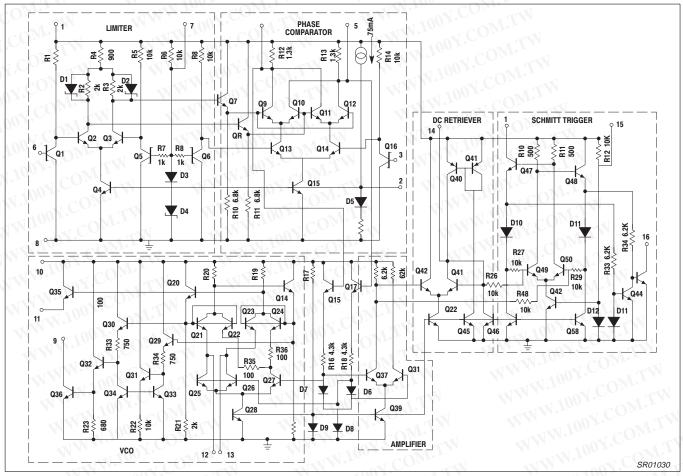


Figure 6. Equivalent Schematic

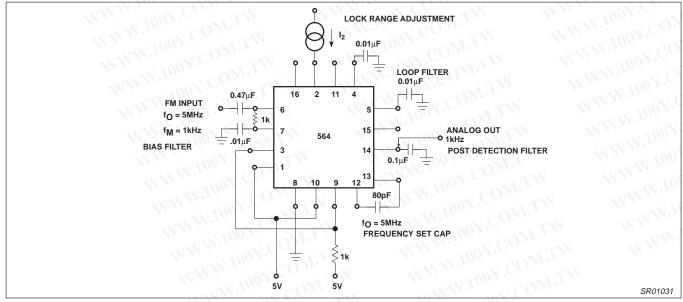


Figure 7. FM Demodulator at 5V

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#### **APPLICATIONS**

#### **FM Demodulator**

The NE564 can be used as an FM demodulator. The connections for operation at 5V and 12V are shown in Figures 7 and 8, respectively. The input signal is AC coupled with the output signal being extracted at Pin 14. Loop filtering is provided by the capacitors at Pins 4 and 5 with additional filtering being provided by the capacitor at Pin 14. Since the conversion gain of the VCO is not very high, to obtain sufficient demodulated output signal the frequency deviation in the input signal should be 1% or higher.

#### **Modulation Techniques**

The NE564 phase-locked loop can be modulated at either the loop filter ports (Pins 4 and 5) or the input port (Pin 6) as shown in Figure 9. The approximate modulation frequency can be determined from the frequency conversion gain curve shown in Figure 10. This curve will be appropriate for signals injected into Pins 4 and 5 as shown in Figure 9.

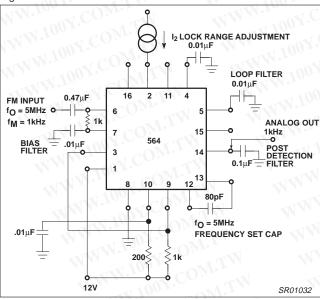


Figure 8. FM Demodulator at 12V

#### **FSK Demodulation**

The 564 PLL is particularly attractive for FSK demodulation since it contains an internal voltage comparator and VCO which have TTL compatible inputs and outputs, and it can operate from a single 5V power supply. Demodulated DC voltages associated with the mark and space frequencies are recovered with a single external capacitor in a DC retriever without utilizing extensive filtering networks. An internal comparator, acting as a Schmitt trigger with an adjustable hysteresis, shapes the demodulated voltages into compatible TTL output levels. The high-frequency design of the 564 enables it to demodulate FSK at high data rates in excess of 1.0M baud.

Figure 10 shows a high-frequency FSK decoder designed for input frequency deviations of  $\pm 1.0 \text{MHz}$  centered around a free-running frequency of 10.8MHz. the value of the timing capacitance required was estimated from Figure 8 to be approximately 40pF. A trimmer capacitor was added to fine tune  $f_{\text{O}}{}^{\prime}$ 10.8MHz.

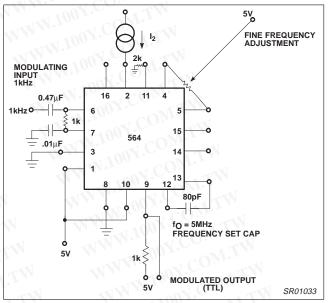


Figure 9. Modulator

The lock range graph indicates that the +1.0 MHz frequency deviations will be within the lock range for input signal levels greater than approximately 50 mV with zero Pin 2 bias current. (While strictly this figure is appropriate only for 50 MHz, it can be used as a guide for lock range estimates at other  $f_O$ ' frequencies).

The hysteresis was adjusted experimentally via the  $10k\Omega$  potentiometer and  $2k\Omega$  bias arrangement to give the waveshape shown in Figure 12 for 20k, 500k, 2M baud rates with square wave FSK modulation. Note the magnitude and phase relationships of the phase comparators' output voltages with respect to each other and to the FSK output. The high-frequency sum components of the input and VCO frequency also are viable as noise on the phase comparator's outputs.

#### **OUTLINE OF SETUP PROCEDURE**

 Determine operating frequency of the VCO: IF÷ N in feedback loop, then

$$f_O = N \times f_{IN}$$
.

2. Calculate value of the VCO frequency set capacitor:

$$C_O \cong \frac{1}{2200 \, f_O}$$

3. Set  $I_2$  (current sinking into Pin 2) for  $\cong 100\mu A$ . After operation is obtained, this value may be adjusted for best dynamic behavior, and replace with fixed resistor value of  $R_2 = \frac{V_{CC} - 1.3V}{V_{CC} + 1.3V}$ .

and replace with fixed resistor value of R<sub>2</sub> = 
$$\frac{V_{CC} - 1.3V}{I_{B_2}}$$

- 4. Check VCO output frequency with digital counter at Pin 9 of device (loop open, VCO to  $\phi$  det.). Adjust  $C_O$  trim or frequency adj. Pins 4 5 for exact center frequency, if needed.
- 5. Close loop and inject input signal to Pin 6. Monitor Pins 3 and 6 with two-channel scope. Lock should occur with  $\Delta\phi_{3-6}$  equal to 90° (phase error).

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- If pulsed burst or ramp frequency is used for input signal, special loop filter design may be required in place of simple single capacitor filter on Pins 4 and 5. (See PLL application section)
- 7. The input signal to Pin 6 and the VCO feedback signal to Pin 3 must have a duty cycle of 50% for proper operation of the phase detector. Due to the nature of a balanced mixer if signals are not
- 50% in duty cycle, DC offsets will occur in the loop which tend to create an artificial or biased VCO.
- 8. For multiplier circuits where phase jitter is a problem, loop filter capacitors may be increased to a value of 10  $50\mu$ F on Pins 4, 5. Also, careful supply decoupling may be necessary. This includes the counter chain  $V_{CC}$  lines.

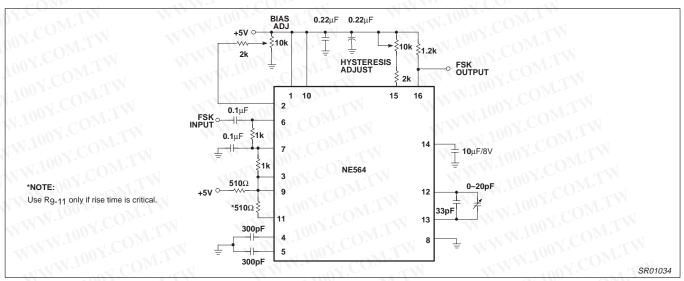


Figure 10. 10.8MHz FSK Decoder Using the 564

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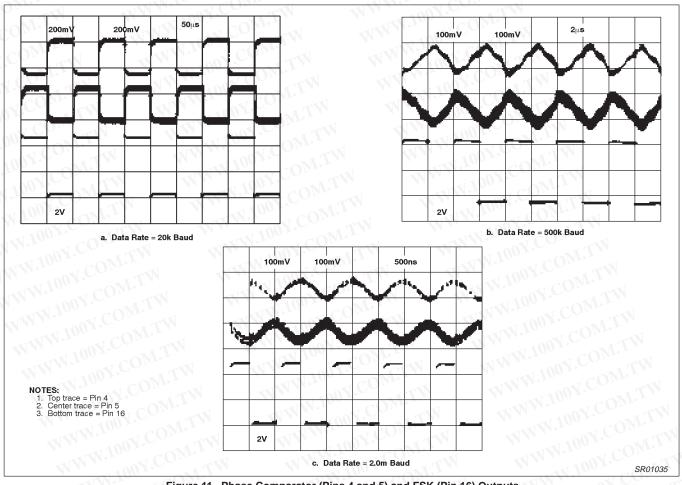


Figure 11. Phase Comparator (Pins 4 and 5) and FSK (Pin 16) Outputs

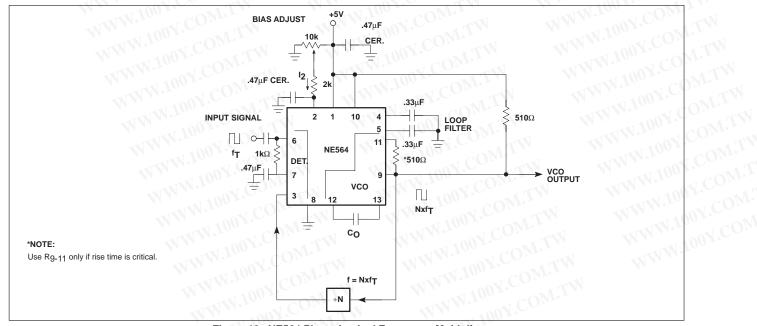


Figure 12. NE564 Phase-Locked Frequency Multiplier

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