

Unipolar Driver ICs

勝特力材料 886-3-5753170
 勝特力电子(上海) 86-21-54151736
 勝特力电子(深圳) 86-755-83298787
[Http://www.100y.com.tw](http://www.100y.com.tw)

SLA7020M WITH MOSFETs

SLA7021M

■ Ratings

Absolute maximum ratings	Motor supply Voltage	FET output breakdown voltage	Control voltage	TTL input voltage	Reference voltage	Output current	Power dissipation	Channel temperature	Storage temperature
	(V)	(V)	(V)	(V)	(V)	(A)	(W)	(°C)	(°C)
Type No.	V _{CC}	V _{DS}	V _S	V _{IN}	V _{REF}	I _O	P _D	T _{ch}	T _{stg}
SLA7020M	46	100	32	7	2	1.5	4.5 (No Fin)	150	-40 to +150
SLA7021M						3			

■ Characteristics (1) DC Characteristics

Electrical characteristics	Control current (mA)			Control voltage (V)			FET turn-on voltage (V)			FET drain leak current (mA)			TTL input current (μA)			TTL input current (mA)			TTL input voltage (OUT) (V)			TTL input voltage (V)			TTL input voltage (OUT) (V)			TTL input voltage (V)							
	V _S = 30V						(7020M) I _D = 1A, V _S = 14V (7021M) I _D = 3A, V _S = 14V			V _{DSS} = 100V V _S = 30V			V _{IH} = 2.4V V _S = 30V			V _{IL} = 0.4V V _S = 30V			I _D = 1A			V _{DSS} = 100V			V _{DSS} = 100V			I _D = 1A							
	I _S			V _S			V _{DS}			I _{DSS}			I _{IH}			I _{IL}			V _{IH}			V _{IL}			V _{IH}			V _{IL}							
Type No.	min	typ	max	min	typ	max	min	typ	max	min	typ	max	min	typ	max	min	typ	max	min	typ	max	min	typ	max	min	typ	max	min	typ	max	min	typ	max		
SLA7020M									0.6																										
SLA7021M	5.5	10	15	10	19	30			0.85			4			40			-0.8	2.0					0.8	2.0										0.8

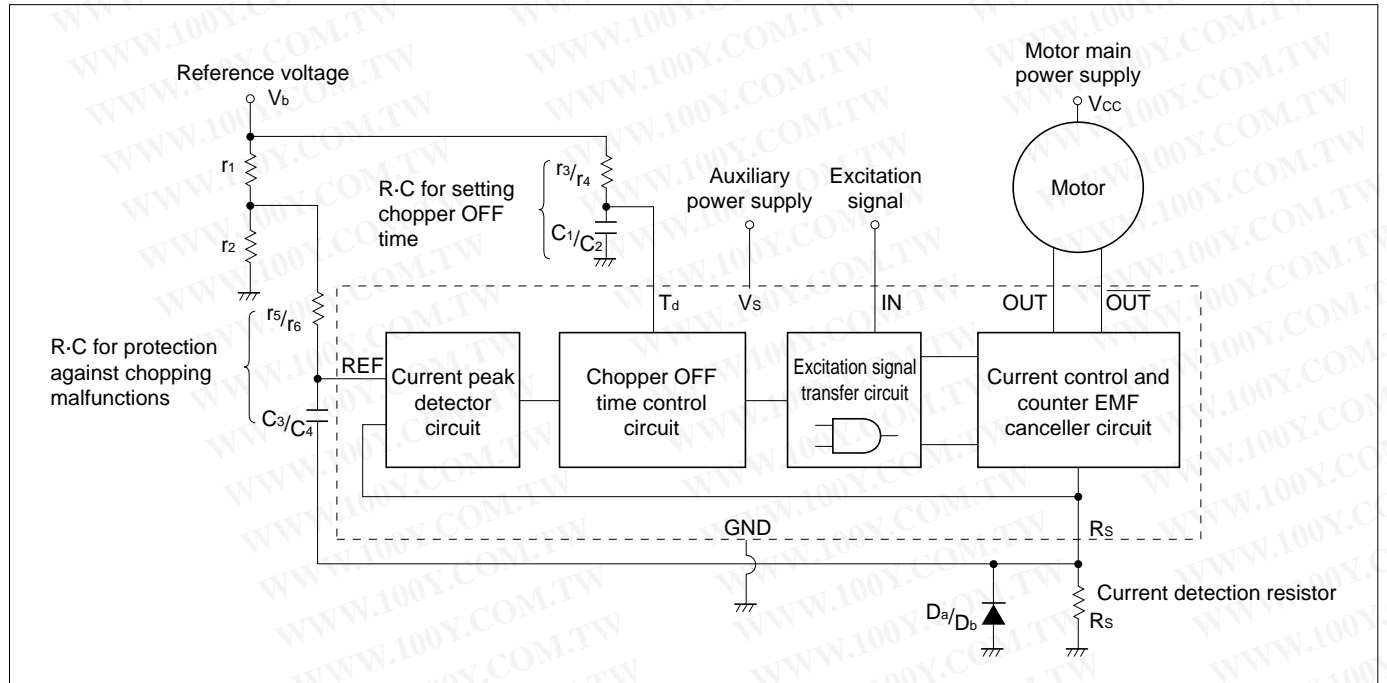
(2) AC Characteristics

Electrical characteristics	FET diode forward voltage (V)			Switching time (μs)											
	(7020M) I _{SD} = 1A (7021M) I _{SD} = 3A			V _S = 24V I _D = 1A											
	V _{SD}			T _r			T _{stg}			T _f					
Type No.	min	typ	max	min	typ	max	min	typ	max	min	typ	max	min	typ	max
SLA7020M			1.1												
SLA7021M			2.3		0.5			0.7						0.1	

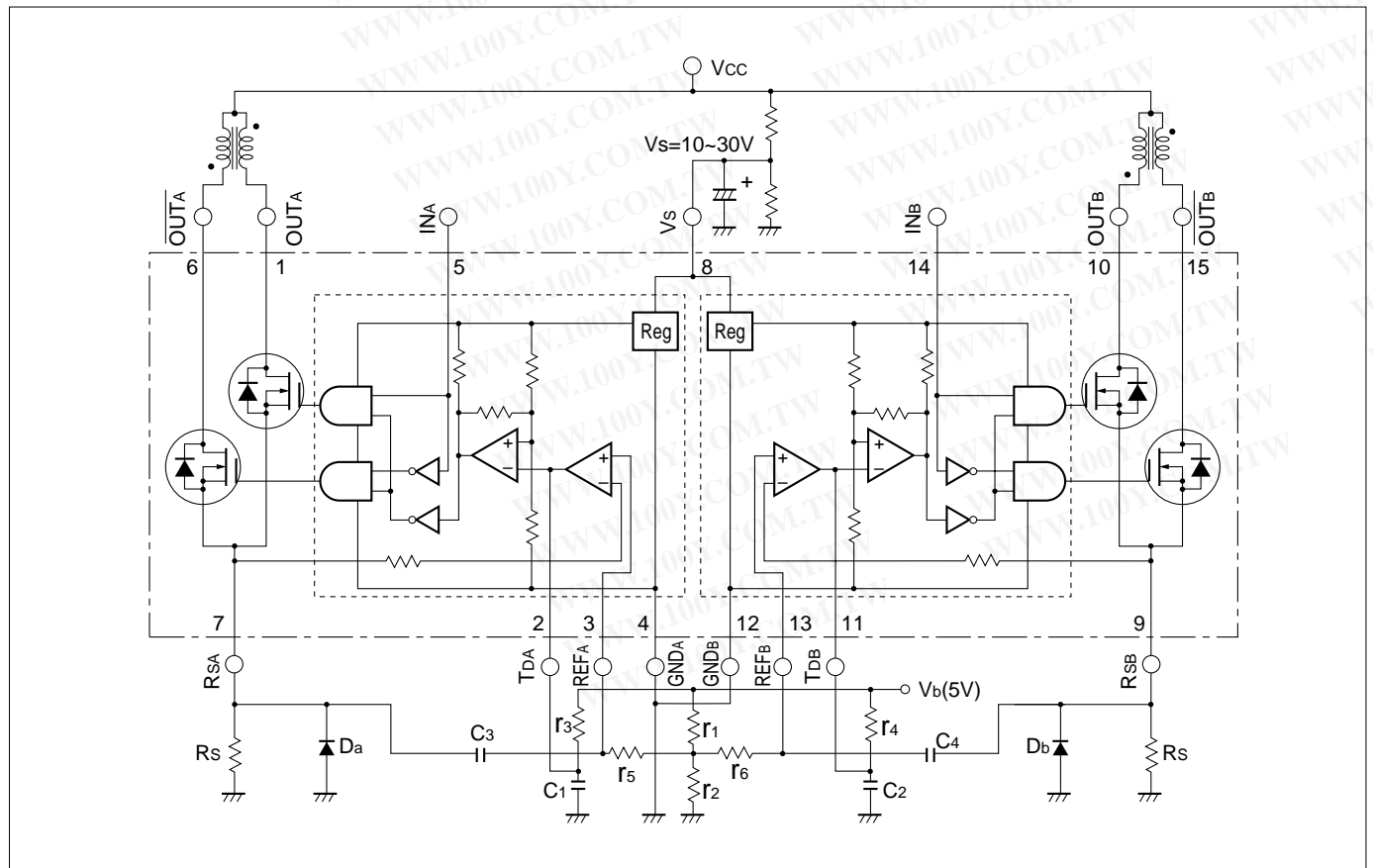
SLA7020M and SLA7021M

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■ Block diagram

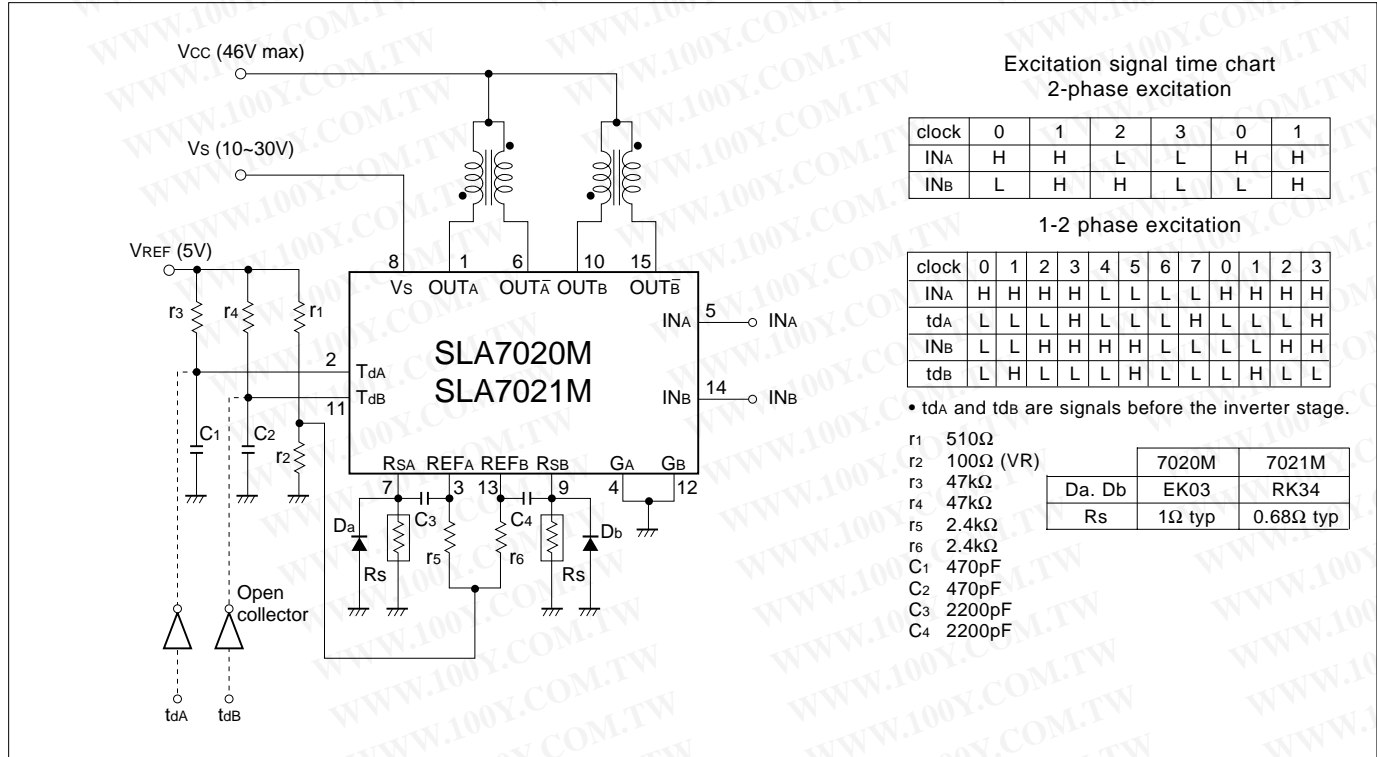


■ Internal circuit diagram (enclosed with chain line)



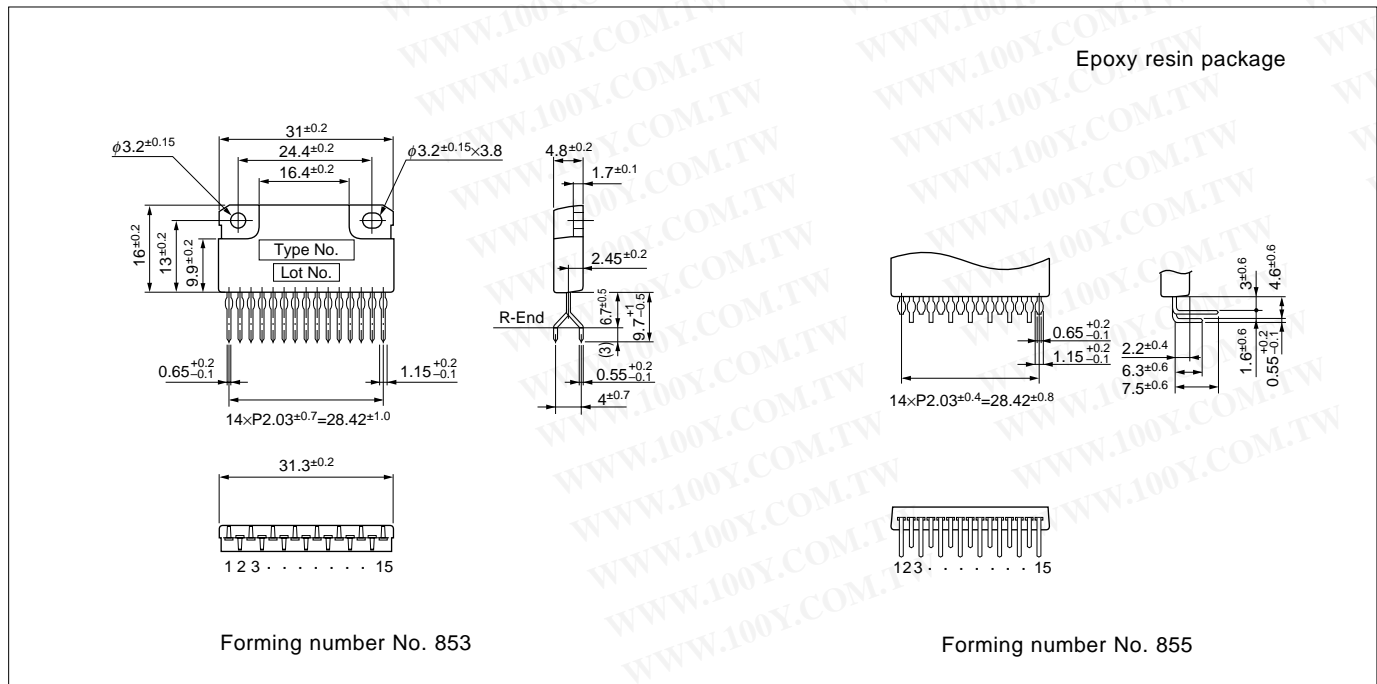
SLA7020M and SLA7021M

Diagram of standard external circuit (Recommended circuit constants)



External dimensions

(Unit: mm)



SLA7024M, SLA7026M, SLA7027MU, SLA7022MU, SLA7029M, SMA7022MU, SMA7029M, SLA7020M, SLA7021M and SDK03M

Application Note

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■ Determining the output current

Fig. 1 shows the waveform of the output current (motor coil current). The method of determining the peak value (I_o) of the output current based on this waveform is shown below.

<Parameters for determining the output current I_o >

- V_b : Reference supply voltage
- r_1, r_2 : Voltage-divider resistors for the reference supply voltage
- R_s : Current detection resistor

(1) Normal rotation mode

I_o is determined as follows when current flows at the maximum level during motor rotation. See Fig. 2, 3 and 4.

$$I_o \doteq \frac{r_2}{r_1+r_2} \cdot \frac{V_b}{R_s} \dots\dots\dots ①$$

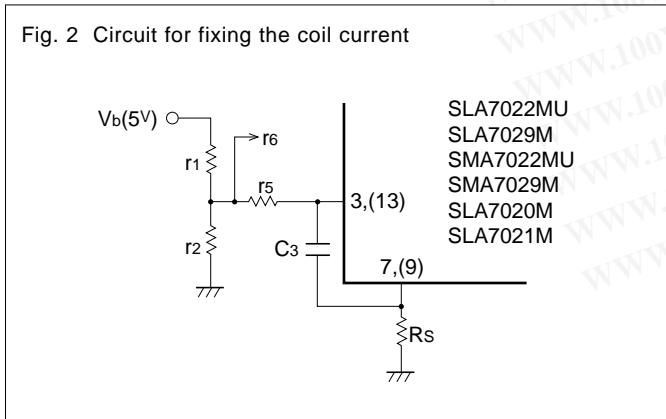
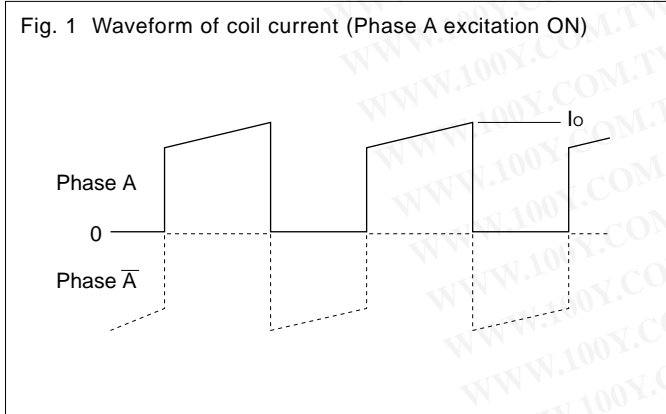
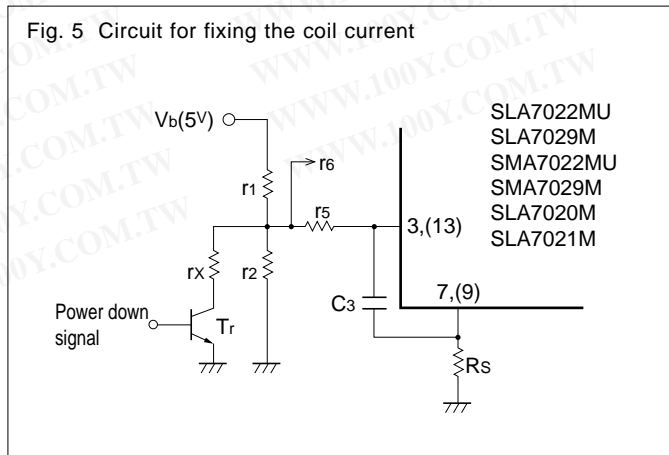
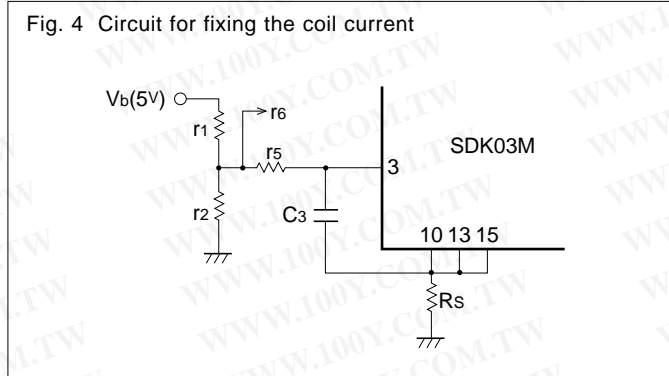
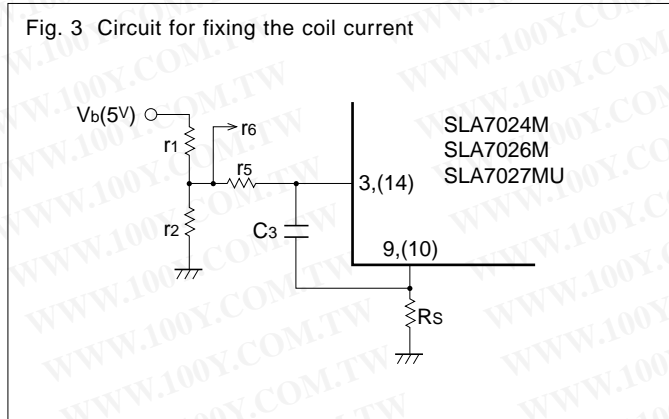
(2) Power down mode

The circuits in Fig. 5, 6 and 7 (r_x and T_r) are added in order to decrease the coil current. I_o is then determined as follows.

$$I_{OPD} \doteq \frac{1}{1 + \frac{r_1(r_2+r_x)}{r_2 \cdot r_x}} \cdot \frac{V_b}{R_s} \dots\dots\dots ②$$

To determine r_x , equation ② can be modified to obtain equation ③.

$$r_x \doteq \frac{1}{\frac{1}{r_1} \left(\frac{V_b}{R_s \cdot I_{OPD}} - 1 \right) - \frac{1}{r_2}} \dots\dots\dots ③$$



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Application Note

Fig. 6 Circuit for fixing the coil current

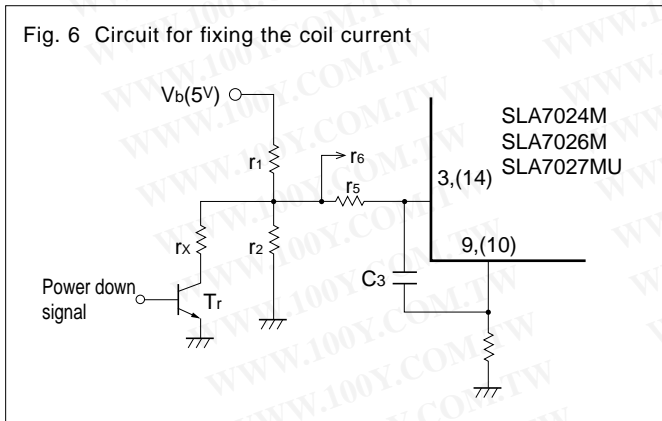


Fig. 7 Circuit for fixing the coil current

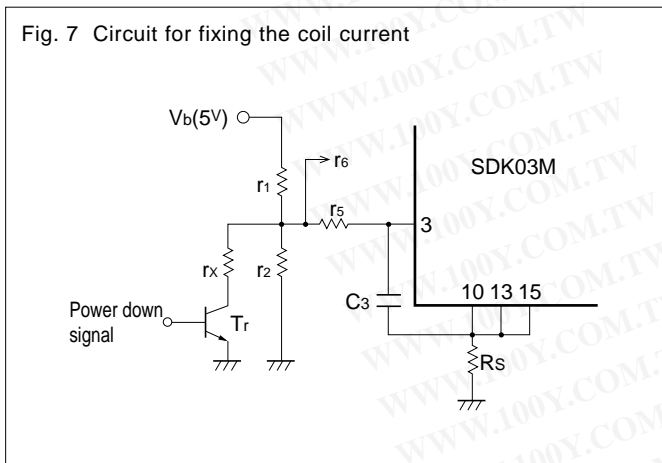


Fig. 8 and 9 show the graphs of equations ① and ②, respectively.

Fig. 8 Output current I_o vs. Current detection resistor R_s

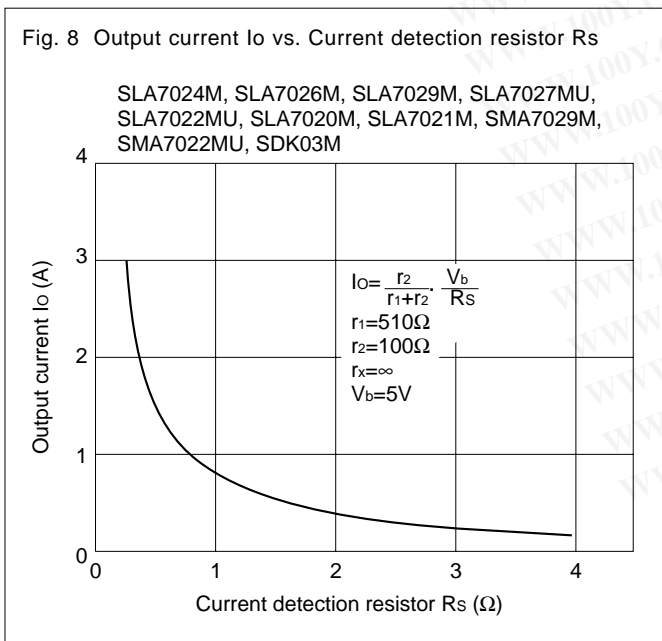
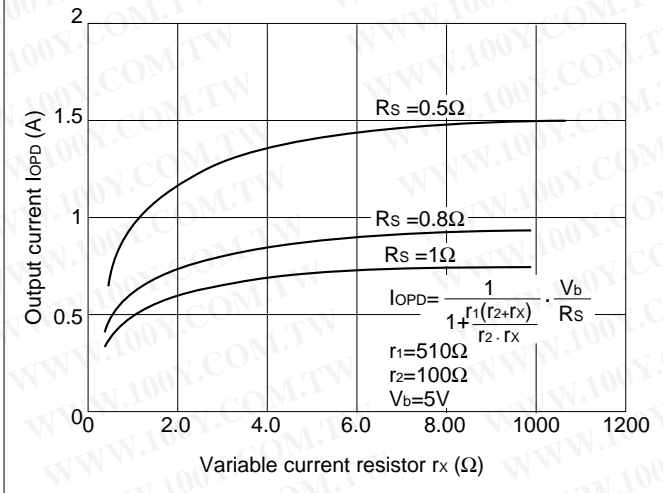


Fig. 9 Output current I_{OPD} vs. Variable current resistor r_x

SLA7024M, SLA7026M, SLA7029M, SLA7027MU, SLA7022MU, SLA7020M, SLA7021M, SMA7029M, SMA7022MU, SDK03M



NOTE:

Ringing noise is produced in the current detection resistor R_s when the MOSFET is switched ON and OFF through chopping. This noise is also generated in feedback signals from R_s which may therefore causes the comparator to malfunction.

To prevent chopping malfunctions, $r_5(r_6)$ and $C_3(C_4)$ are added in order to act as noise filter.

However, when the values of these constants are increased, the response from R_s to the comparator becomes slow. Hence, the value of the output current I_o is higher to some extent than the computed value.

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Application Note

Determining the chopper frequency

Determining T_{OFF} : SLA7000M series, SMA7000M series and SDK03M are self-excited choppers. The chopping OFF time T_{OFF} is fixed by r_3/C_1 and r_4/C_2 connected to terminal Td.

T_{OFF} can be computed through the following formula:

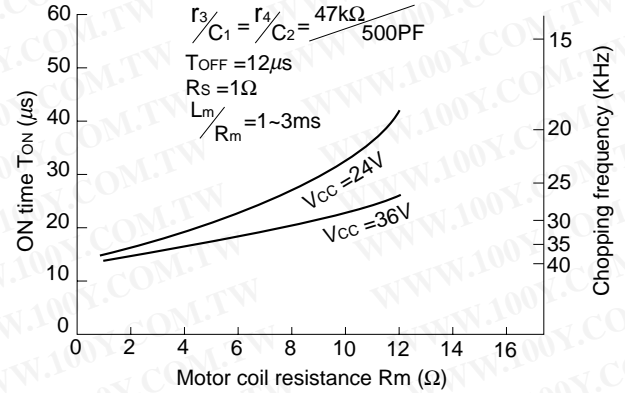
$$T_{OFF} \cong -r_3 \cdot C_1 \ln \left(1 - \frac{2}{V_b}\right) = -r_4 \cdot C_2 \ln \left(1 - \frac{2}{V_b}\right)$$

The circuit constants and the T_{OFF} value shown below are recommended.

$$\begin{aligned} T_{OFF} &= 12 \mu s \\ r_3 &= 47 \text{ K}\Omega \\ C_1 &= 500 \text{ pF} \\ V_b &= 5 \text{ V} \end{aligned}$$

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Fig. 10 Chopper frequency vs. Motor coil resistance



Thermal design

An outline on the method of computing heat dissipation is shown below.

- Obtain the P_H that corresponds to the motor coil current I_o from Fig. 11 "Heat dissipation per phase P_H vs. Output current I_o ".
- The power dissipation P_{diss} is obtained through the following formula.
 - SLA7000M and SMA7000M series
 - 2-phase excitation : $P_{diss} \cong 2P_H + 0.015 \times V_s$ (W)
 - 1-2 phase excitation : $P_{diss} \cong \frac{3}{2}P_H + 0.015 \times V_s$ (W)
 - SDK03M
 - 2-phase excitation : $P_{diss} \cong P_H + 0.015 \times V_s$ (W)
 - 1-2 phase excitation : $P_{diss} \cong \frac{3}{4}P_H + 0.015 \times V_s$ (W)
- Obtain the temperature rise that corresponds to the computed P_{diss} from Fig. 12 "Temperature rise curve."

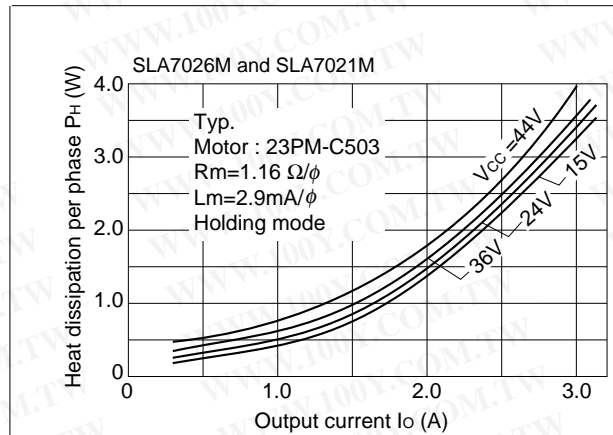
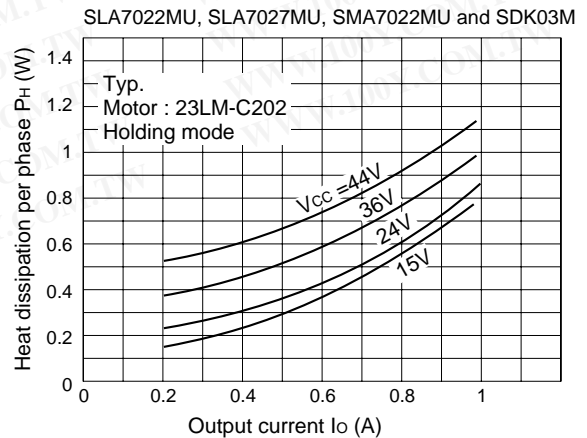
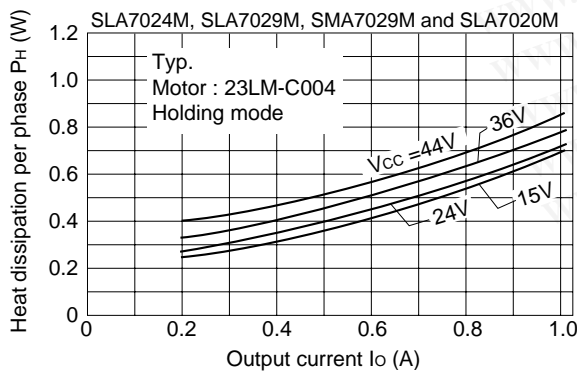


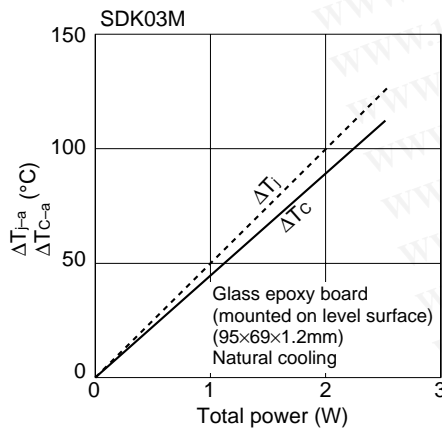
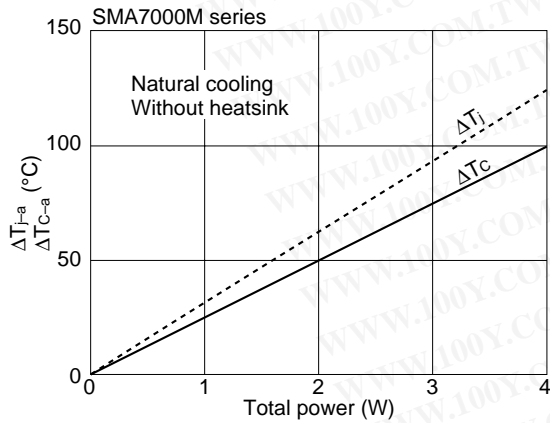
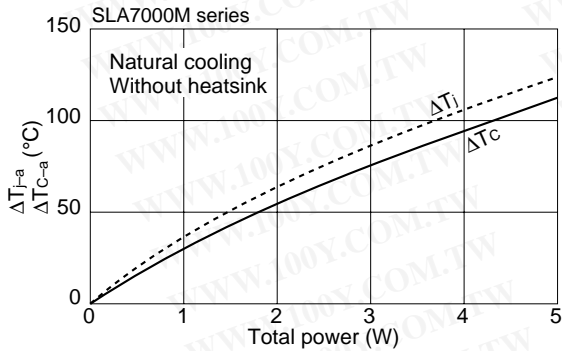
Fig. 11 Heat dissipation per phase P_H vs. Output current I_o



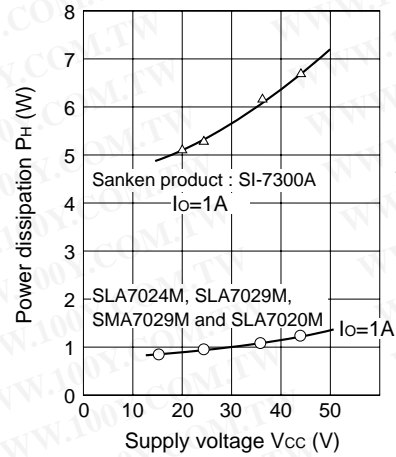
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Application Note

Fig. 12 Temperature rise curve



Comparison of losses



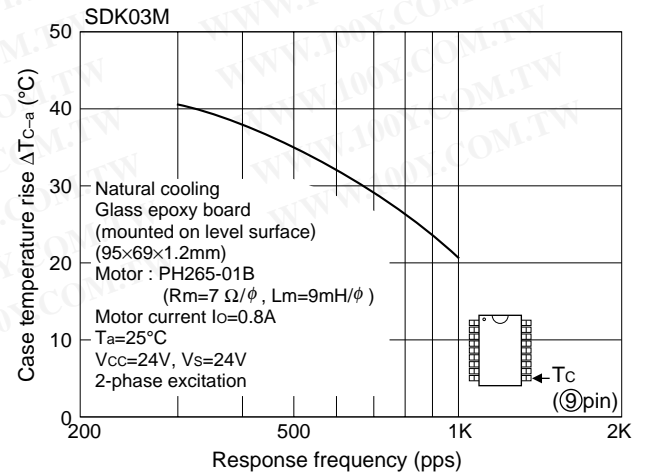
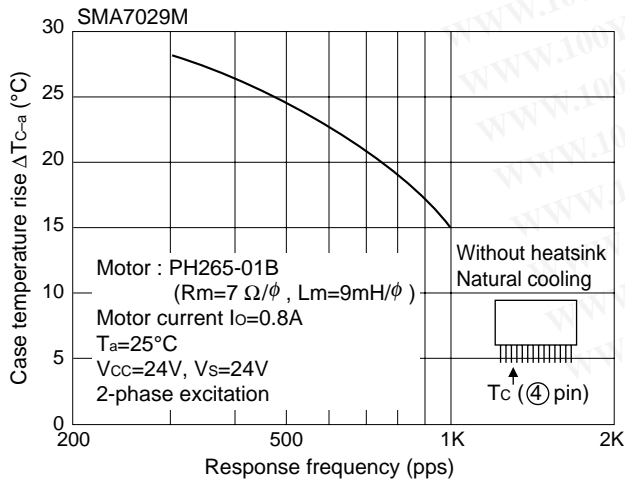
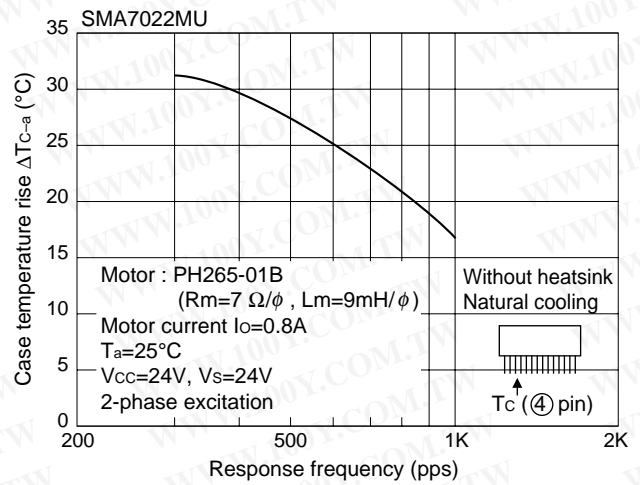
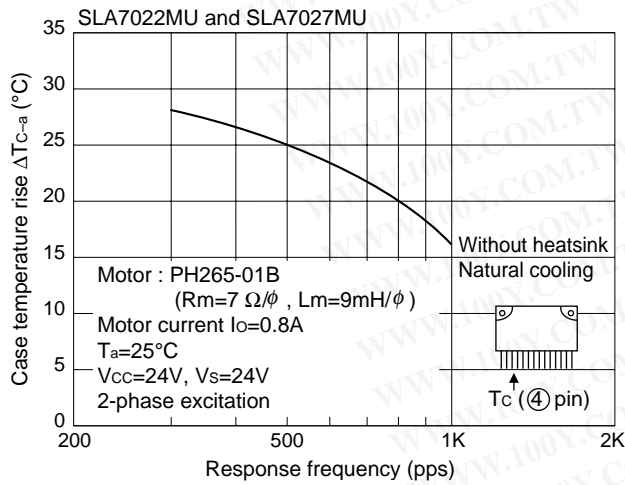
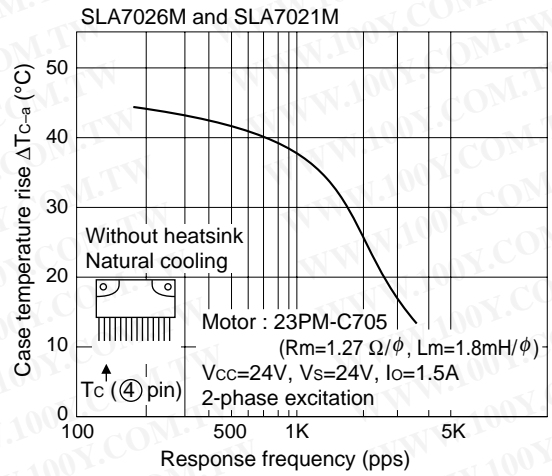
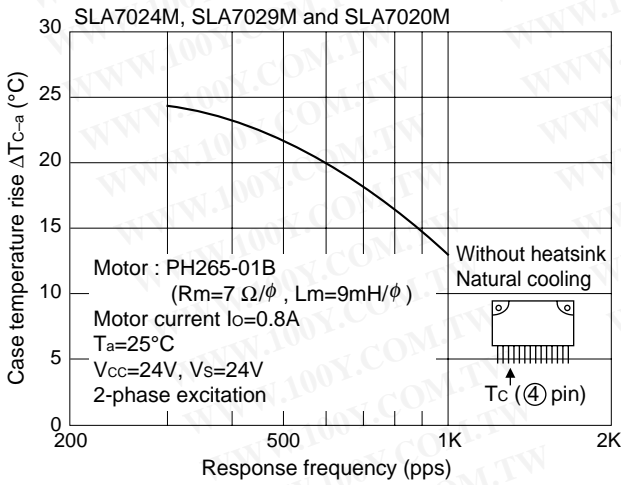
Motor : 23LM-C202
Io : Output current
2-phase excitation,
holding mode

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Application Note

Heat dissipation characteristics

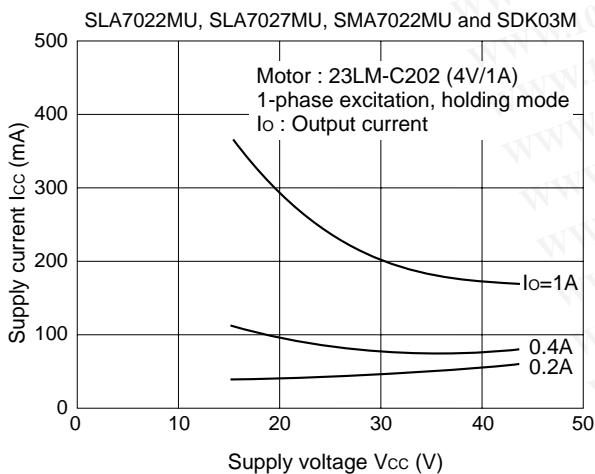
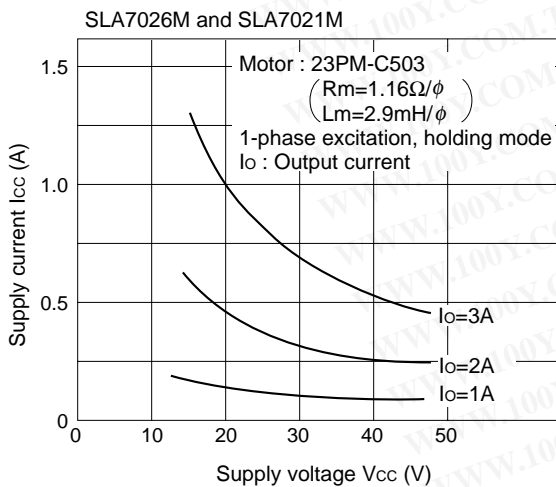
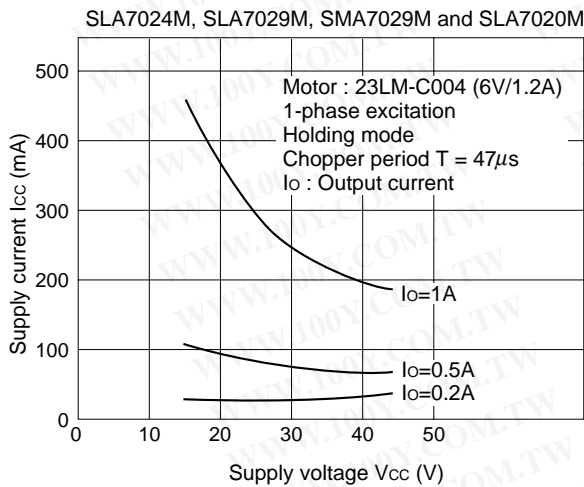


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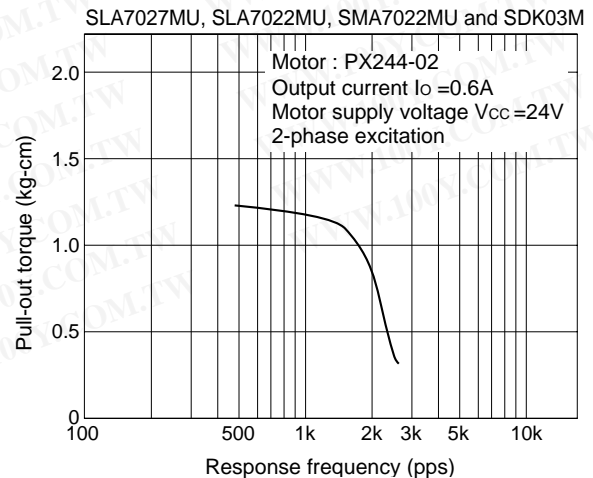
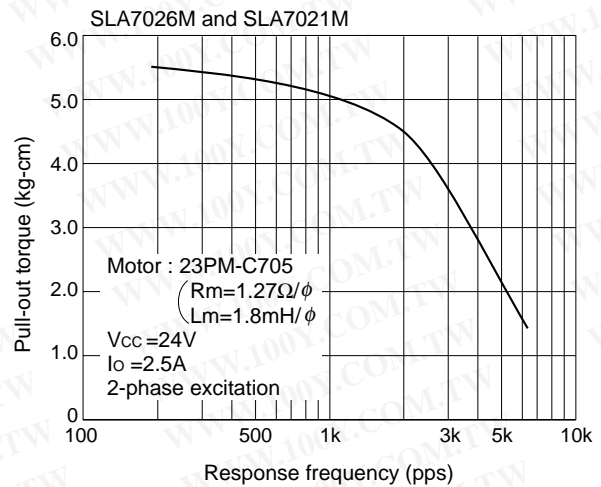
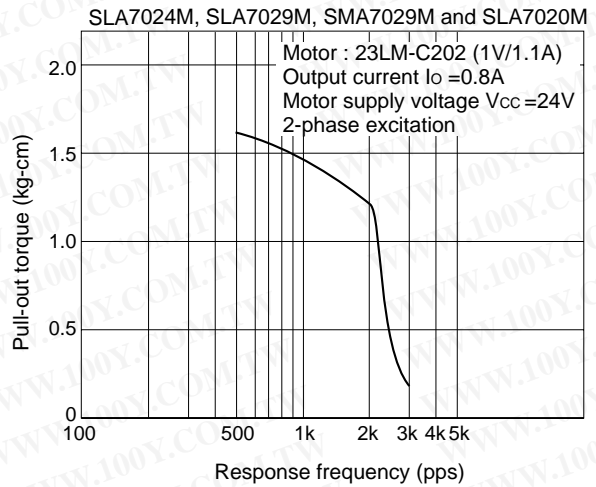
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Application Note

Supply voltage V_{cc} vs. Supply current I_{cc}



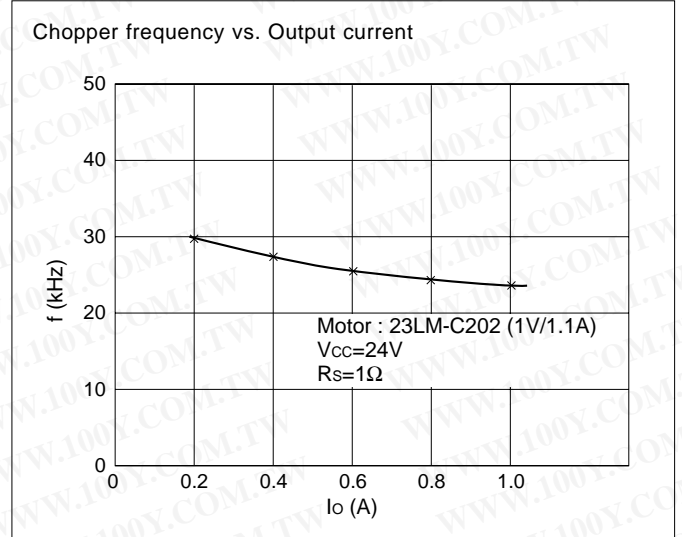
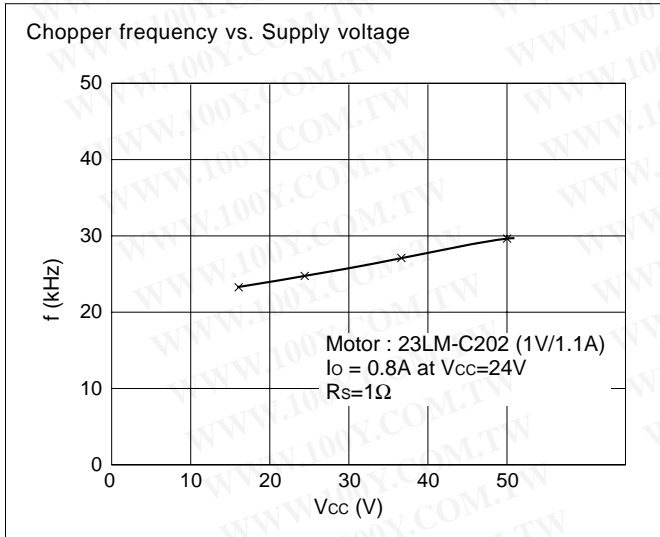
Torque characteristics



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Application Note



NOTE

Either active high or active low excitation input signals can be used for SLA7024M, SLA7026M, SLA7027MU and SDK03M. However, take note of the output that corresponds to a specified input as shown in the table below.

- SLA7024M, SLA7026M and SLA7027MU

Active High

Input	Output
IN _A (6 pin)	OUT _A (1 pin)
IN _A (5 pin)	OUT _A (8 pin)
IN _B (17 pin)	OUT _B (11 pin)
IN _B (16 pin)	OUT _B (18 pin)

Active Low

Input	Output
IN _A (6 pin)	OUT _A (8 pin)
IN _A (5 pin)	OUT _A (1 pin)
IN _B (17 pin)	OUT _B (18 pin)
IN _B (16 pin)	OUT _B (11 pin)

- SDK03M

Active High

Input	Output
IN ₁ (6 pin)	OUT ₁ (1, 16 pin)
IN ₂ (5 pin)	OUT ₂ (8, 9 pin)

Active Low

Input	Output
IN ₁ (6 pin)	OUT ₁ (8, 9 pin)
IN ₂ (5 pin)	OUT ₂ (1, 16 pin)

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