SMLS128E-OCTOBER 1984-REVISED JANUARY 1993

This Data Sheet is Applicable to All TMS27C128s and TMS27PC128s Symbolized with Code "B" as Described on Page 12.

- Organization . . . 16K × 8
- Single 5-V Power Supply
- Pin Compatible With Existing 128K MOS ROMs, PROMs, and EPROMs
- All Inputs/Outputs Fully TTL Compatible
- Max Access/Min Cycle Times

V<sub>CC</sub> ± 10% '27C128-12 120 ns '27C/PC128-15 150 ns '27C/PC128-20 200 ns '27C/PC128-25 250 ns



- Power Saving CMOS Technology
- Very High-Speed SNAP! Pulse Programming
- 3-State Output Buffers
- 400-mV Minimum DC Noise Immunity With Standard TTL Loads
- Latchup Immunity of 250 mA on All Input and Output Lines
- Low Power Dissipation (V<sub>CC</sub> = 5.25 V)
  - Active . . . 158 mW Worst Case
  - Standby . . . 1.4 mW Worst Case (CMOS Input Levels)
- PEP4 Version Available With 168-Hour Burn-In and Choices of Operating Temperature Ranges
- 128K EPROM Available With MIL-STD-883C Class B High-Reliability Processing (SMJ27C128)

## description

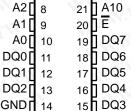
The TMS27C128 series are 131 072-bit, ultraviolet-light erasable, electrically programmable read-only memories.

The TMS27PC128 series are 131 072-bit, one time electrically programmable read-only memories.

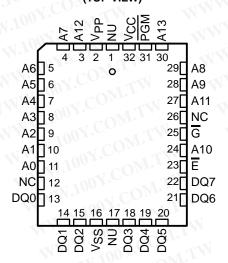
# V<sub>PP</sub> 1 28 V<sub>CC</sub> PGM A12 2 27 PGM A7 3 26 A13 A6 4 25 A8 A5 5 24 A9 A4 6 23 A11 A3 7 22 G

J AND N PACKAGES

(TOP VIEW)



## FM PACKAGE (TOP VIEW)



#### PIN NOMENCLATURE

	-71,0
A0-A13	Address Inputs
ĒŃ	Chip Enable/Powerdown
<u>E</u> G	Output Enable
GND	Ground
NC	No Connection
NU	Make No External Connection
PGM	Program
DQ0-DQ7	Inputs (programming)/Outputs
VCC	5-V Power Supply
Vpp	12-13 V Programming Power Supply

Texas VI

SMLS128E-OCTOBER 1984-REVISED JANUARY 1993

These devices are fabricated using power-saving CMOS technology for high speed and simple interface with MOS and bipolar circuits. All inputs (including program data inputs) can be driven by Series 74 TTL circuits without the use of external pull-up resistors. Each output can drive one Series 74 TTL circuit without external resistors.

The data outputs are three-state for connecting multiple devices to a common bus. The TMS27C128 and the TMS27PC128 are pin compatible with 28-pin 128K MOS ROMs, PROMs, and EPROMs.

The TMS27C128 EPROM is offered in a dual-in-line ceramic package (J suffix) designed for insertion in mounting hole rows on 15,2-mm (600-mil) centers. The TMS27C128 is offered with two operating temperature ranges of 0°C to 70°C (JL suffix) and – 40°C to 85°C (JE suffix). The TMS27C128 is also offered with 168-hour burn-in temperature ranges (JL4 and JE4 suffixes). (See table below).

The TMS27PC128 PROM is offered in a dual-in-line plastic package (N suffix) designed for insertion in mounting hole rows on 15,2-mm (600-mil) centers. The TMS27PC128 is also supplied in a 32-lead plastic leaded chip carrier package using 1,25-mm (50-mil) lead spacing (FM suffix). The TMS27PC128 is also offered with two operating temperature ranges of 0°C to 70°C (NL and FML suffixes) and –40°C to 85°C (NE and FME suffixes). The TMS27PC128 is also offered with 168 hour burn-in temperature ranges (NL4, FML4, NE4, and FME4 suffixes). (See table below).

All package styles conform to JEDEC standards.

EPROM AND PROM	TEMPERAT	R OPERATING URE RANGES EP4 BURN-IN	SUFFIX FOR OPERATING TEMPERATURE RANGES WITH PEP4 168 HR. BURN-IN			
WINOM 100	0°C TO 70°C	-40 °C TO 85°C	0°C TO 70°C	-40 °C TO 85°C		
TMS27C128-XXX	JL	JE	10 JL4	JE4		
TMS27PC128-XXX	V. UNL	NE NE	NL4	NE4		
TMS27PC128-XXX	FML	FME	FML4	FME4		

These EPROMs and PROMs operate from a single 5-V supply (in the read mode), thus are ideal for use in microprocessor-based systems. One other 12-13-V supply is needed for programming . All programming signals are TTL level. These devices are programmable by using the SNAP! Pulse programming algorithm. The SNAP! Pulse programming algorithm uses a  $V_{PP}$  of 13.0 V and a  $V_{CC}$  of 6.5 V for a nominal programming time of two seconds. For programming outside the system, existing EPROM programmers can be used. Locations may be programmed singly, in blocks, or at random.



SMLS128E-OCTOBER 1984-REVISED JANUARY 1993

## operation

The seven modes of operation are listed in the following table. Read mode requires a single 5-V supply. All inputs are TTL level except for Vpp during programming (13 V for SNAP! Pulse), and 12 V on A9 for the signature mode.

FUNCTION	READ OUTPUT DISABLE		STANDBY	PROGRAMMING	VERIFY	PROGRAM INHIBIT			
Ē	VIL	V <sub>IL</sub>	V <sub>IH</sub> √	V <sub>IL</sub>	VIL	VIH	1007	/IL	
G	V <sub>IL</sub>	VIH	χ†	VIH.	VIL	X N	44.	/IL	
PGM	ViH	VIH	Х	VIL	ViH	Х	Mira	VIH COM	
VPP	Vcc	Vcc	Vcc	V <sub>PP</sub>	Vpp	V <sub>PP</sub>	.1 V	Vcc	
V <sub>C</sub> C	Vcc	Vcc	√ V <sub>CC</sub>	Vcc	Vcc	Vcc	V	Vcc	
A9	X	$\mathcal{T}(X)$	X	X	CX	X X	VH	V <sub>H</sub> ‡	
A0	X	X	Х	X	X	Х	VIL	VIH	
	10	01.0	1.11	W 10	Mo	1.	CODE		
DQ0-DQ7	Data Out	HI-Z	HI-Z Data In Data Out	HI-Z	MFG	DEVICE			
	WW.	o CO	NI.	MW.		TW	97	83	

WWW.100Y.COM.TW

WWW.100Y.COM.TW 勝 特 力 材 料 886-3-5753170 胜特力电子(上海) 86-21-54151736 胜特力电子(深圳) 86-755-83298787 Http://www. 100y. com. tw

WWW.100Y.COM.

WW.100Y.COM.TW

<sup>†</sup> X can be V<sub>IL</sub> or V<sub>IH</sub>.  $V_H = 12 V \pm 0.5 V.$ 

SMLS128E-OCTOBER 1984-REVISED JANUARY 1993

## read/output disable

When the outputs of two or more TMS27C128s or TMS27PC128s are connected in parallel on the same bus, the output of any particular device in the circuit can be read with no interference from the competing outputs of the other devices. To read the output of a single device, a low-level signal is applied to the  $\overline{E}$  and  $\overline{G}$  pins. All other devices in the circuit should have their outputs disabled by applying a high-level signal to one of these pins. Output data is accessed at pins DQ0 through DQ7.

## latchup immunity

Latchup immunity on the TMS27C128 and TMS27PC128 is a minimum of 250 mA on all inputs and outputs. This feature provides latchup immunity beyond any potential transients at the P.C. board level when the devices are interfaced to industry-standard TTL or MOS logic devices. Input/output layout approach controls latchup without compromising performance or packing density.

## power down

Active  $I_{CC}$  supply current can be reduced from 30 mA to 500  $\mu$ A (TTL-level inputs) or 250  $\mu$ A (CMOS-level inputs) by applying a high TTL or CMOS signal to the  $\overline{E}$  pin. In this mode all outputs are in the high-impedance state

## erasure (TMS27C128)

Before programming, the TMS27C128 EPROM is erased by exposing the chip through the transparent lid to a high intensity ultraviolet light (wavelength 2537 Å). EPROM erasure before programming is necessary to assure that all bits are at the logic high level. Logic lows are programmed into the desired locations. A programmed logic low can be erased only by ultraviolet light. The recommended minimum ultraviolet light exposure dose (UV intensity × exposure time) is 15-W·s/cm². A typical 12-mW/cm², filterless UV lamp will erase the device in 21 minutes. The lamp should be located about 2.5 cm above the chip during erasure. It should be noted that normal ambient light contains the correct wavelength for erasure. Therefore, when using the TMS27C128, the window should be covered with an opaque label.

## initializing (TMS27PC128)

The one-time programmable TMS27PC128 PROM is provided with all bits at the logic high level. The logic lows are programmed into the desired locations. Logic lows programmed into a PROM cannot be erased.

#### **SNAP!** Pulse programming

The 128K EPROM and PROM are programmed using the TI SNAP! Pulse programming algorithm, illustrated by the flowchart in Figure 1, which programs in a nominal time of two seconds. Actual programming time will vary as a function of the programmer used.

Data is presented in parallel (eight bits) on pins DQ0 to DQ7. Once addresses and data are stable,  $\overline{\text{PGM}}$  is pulsed.

The SNAP! Pulse programming algorithm uses initial pulses of 100 microseconds ( $\mu$ s) followed by a byte verification to determine when the addressed byte has been successfully programmed. Up to 10 (ten) 100- $\mu$ s pulses per byte are provided before a failure is recognized.

The programming mode is achieved when  $V_{PP}=13$  V,  $V_{CC}=6.5$  V,  $\overline{G}=V_{IH}$ , and  $\overline{E}=V_{IL}$ . More than one device can be programmed when the devices are connected in parallel. Locations can be programmed in any order. When the SNAP! Pulse programming routine is complete, all bits are verified with  $V_{CC}=V_{PP}=5$  V.

# program inhibit

Programming may be inhibited by maintaining a high level input on the E or PGM pin.



SMLS128E-OCTOBER 1984-REVISED JANUARY 1993

## program verify

Programmed bits may be verified with  $V_{PP} = 13 \text{ V}$  when  $\overline{G} = V_{IL}$ ,  $\overline{E} = V_{IL}$ , and  $\overline{PGM} = V_{IH}$ .

## signature mode

The signature mode provides access to a binary code identifying the manufacturer and type. This mode is activated when A9 is forced to 12 V  $\pm$  0.5 V. Two identifier bytes are accessed by A0; i.e., A0 =  $V_{IL}$  accesses the manufacturer code, which is output on DQ0–DQ7; A0 =  $V_{IH}$  accesses the device code, which is output on DQ0–DQ7. All other addresses must be held at  $V_{IL}$ . The manufacturer code for these devices is 97, and the device code is 83.

SMLS128E-OCTOBER 1984-REVISED JANUARY 1993

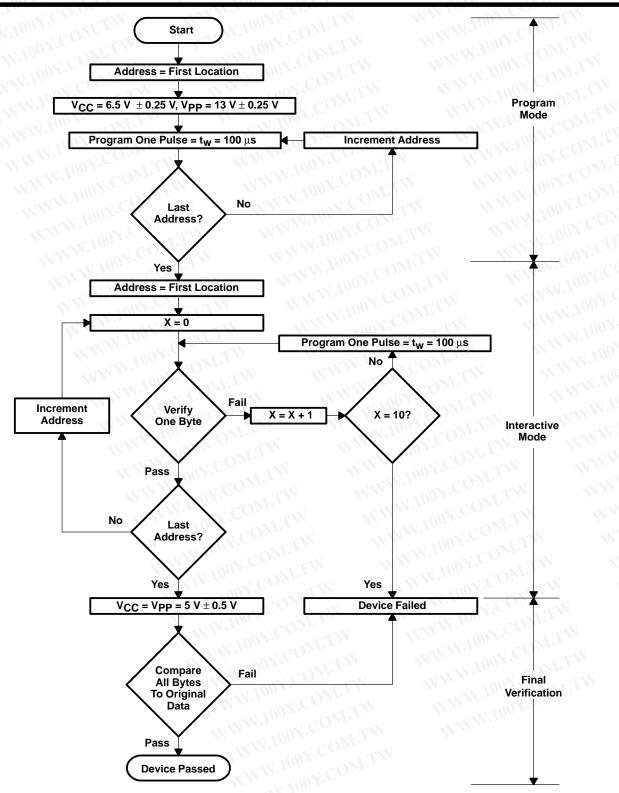
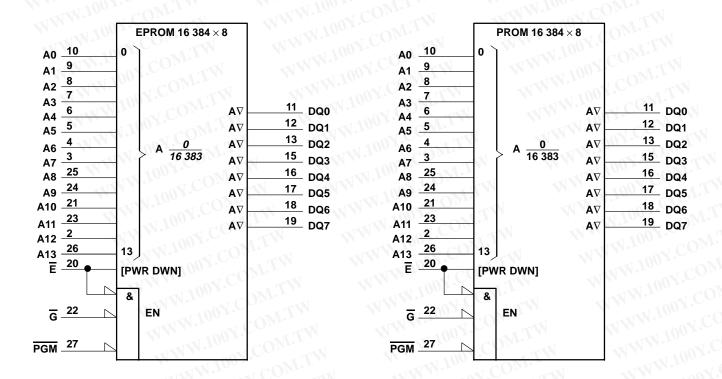


Figure 1. SNAP! Pulse Programming Flowchart



# logic symbol†



<sup>†</sup> These symbols are in accordance with ANSI/IEEE Std 91-1984 and IEC Publication 617-12 Pin numbers shown are J and N packages.

# 

NOTE 1: Under absolute maximum ratings, voltage values are with respect to GND.



<sup>‡</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

SMLS128E-OCTOBER 1984-REVISED JANUARY 1993

# recommended operating conditions

MW	11007.00	MA	71100Y. OM.TW	MIN	NOM	MAX	UNIT
VAL	Cumply valtage	Read mode (	see Note 2)	4.5	1005	5.5	W
VCC	Supply voltage	SNAP! Pulse	programming algorithm	6.25	6.5	6.75	V
\/	Cumply voltage	Read mode	IN Ton COM.	V <sub>CC</sub> -0.6	N'Inc	V <sub>CC</sub> + 0.6	V
VPP	Supply voltage	SNAP! Pulse	programming algorithm	12.75	13	13.25	V
VIH	High-level dc input voltage		THE	2	-11	V <sub>CC</sub> +1	V
			CMOS	V <sub>CC</sub> -0.2	MAN	V <sub>CC</sub> +1	V
V			TTL WILL COM.	-0.5	WW	0.8	V
$V_{IL}$	Low-level dc input voltage	N.T.W	CMOS	-0.5		0.2	V
T <sub>A</sub>	Operating free-air temperature	MIW	'27C128JL,JL4 '27PC128NL,NL4 FML, FML4	0	MM	70	C°C
T <sub>A</sub>	Operating free-air temperature	CON.TW	'27C128JE,JE4 '27PC128NE,NE4 FME, FME4	-40	W	70	°C

NOTES: 2. V<sub>CC</sub> must be applied before or at the same time as V<sub>PP</sub> and removed after or at the same time as V<sub>PP</sub>. The device must not be inserted into or removed from the board when V<sub>PP</sub> or V<sub>CC</sub> is applied.

# electrical characteristics over full ranges of operating conditions

	PARAMETER	COM	TEST CONDITIONS	MIN	TYP <sup>†</sup>	MAX	UNIT
V	High-level dc output voltage		I <sub>OH</sub> = −2.5 mA	3.5		W.	N.V
VOH			I <sub>OH</sub> = -20 μA	V <sub>CC</sub> -0.1		Mar	٧
V	Low lovel de output voltege	ON COM	I <sub>OL</sub> = 2.1 mA	Op. TV		0.4	V
VOL	Low-level dc output voltage		I <sub>OL</sub> = 20 μA	COM	x N	0.1	V
II	Input current (leakage)		V <sub>I</sub> = 0 to 5.5 V	COM	-1	±1	μΑ
ΙΟ	Output current (leakage)		$V_O = 0$ to $V_{CC}$	).V	LAN	±1	μΑ
I <sub>PP1</sub>	Vpp supply current	M. F. COM.	$V_{PP} = V_{CC} = 5.5 V$	N.Co.	111	10	μΑ
I <sub>PP2</sub>	VPP supply current (during prog	ram pulse)	Vpp = 13 V	COM	35	50	mA
	\/a = quanty querent (atondhy)	TTL-input level	$V_{CC} = 5.5 \text{ V}, \overline{E} = V_{IH}$	(0)	250	500	μΑ
ICC1	VCC supply current (standby)	CMOS-input level	$V_{CC} = 5.5 \text{ V}, \overline{E} = V_{CC}$	1007.	100	250	μΑ
I <sub>CC2</sub>	V <sub>CC</sub> supply current (active)	WWW.100X.C	$V_{CC} = 5.5 \text{ V}, \overline{E} = V_{IL},$ $t_{cycle} = minimum cycle time,$ outputs open	1.100X.C	15	30	mA

<sup>†</sup> Typical values are at  $T_A = 25^{\circ}$ C and nominal voltages.

# capacitance over recommended ranges of supply voltage and operating free-air temperature, $f = 1 \text{ MHz}^{\ddagger}$

	PARAMETER	TEST CONDITIONS	MIN TYPT	MAX	UNIT
Ci	Input capacitance	V <sub>I</sub> = 0, f = 1 MHz	100 6	10	pF
CO	Output capacitance	V <sub>O</sub> = 0, f = 1 MHz	10	14	pF

<sup>†</sup> Typical values are at T<sub>A</sub> = 25°C and nominal voltages. Capacitance measurements are made on sample basis only.



SMLS128E-OCTOBER 1984-REVISED JANUARY 1993

# switching characteristics over full ranges of recommended operating conditions (see Notes 3 and 4)

MM.	1007.	TEST CONDITIONS (SEE NOTES 3 AND 4)		'27C128-12		'27C/PC128-15	
	PARAMETER			MAX	MIN	MAX	UNIT
ta(A)	Access time from address	COM	471	120	OV.C	150	ns
ta(E)	Access time from chip enable	C <sub>I</sub> = 100 pF,	-1	120	-1	150	ns
ten(G)	Output enable time from G	1 Series 74 TTL Load,	14	55	700 7.	75	ns
<sup>t</sup> dis	Output disable time from $\overline{G}$ or $\overline{E}$ , whichever occurs first $\dagger$	Input $t_{\Gamma} \le 20 \text{ ns}$ , Input $t_{\Gamma} \le 20 \text{ ns}$	0	45	0	60	ns
t <sub>V</sub> (A)	Output data valid time after change of address, E, or G, whichever occurs first <sup>†</sup>	MAN (1.2.2011)	0	MM	W.000	Y.CC	ns

	MAN. TO COME AND	TEST CONDITIONS		'27C/PC128-20		'27C/PC128-25		
	WW.100 COM.	(SEE NOTES 3 AND 4)	MIN MAX		MIN MAX		UNIT	
ta(A)	Access time from address	C <sub>I</sub> = 100 pF,	_ *1	200	TINN	250	ns	
t <sub>a(E)</sub>	Access time from chip enable		1.11	200	- 11	250	ns	
ten(G)	Output enable time from G	1 Series 74 TTL Load,	TW	75	MA	100	ns	
<sup>t</sup> dis	Output disable time from $\overline{G}$ or $\overline{E}$ , whichever occurs first $\dagger$	Input t <sub>r</sub> ≤ 20 ns, Input t <sub>f</sub> ≤ 20 ns	0	60	0	60	ns	
t <sub>V</sub> (A)	Output data valid time after change of address, $\overline{E}$ , or $\overline{G}$ , whichever occurs first $\overline{I}$	input if \$ 20 ns	0	N	0	NVV.	ns	

<sup>†</sup> Value calculated from 0.5 V delta to measured level. This parameter is only sampled and not 100% tested.

# switching characteristics for programming: $V_{CC} = 6.5 \text{ V}$ and $V_{PP} = 13 \text{ V}$ (SNAP! Pulse), $T_A = 25 ^{\circ}\text{C}$ (see Note 3)

	PARAMETER	MIN	NOM	MAX	UNIT	
t <sub>dis(G)</sub>	Output disable time from G	0		130	ns	
ten(G)	Output enable time from G	$-0_{M^{**}}$		150	ns	

# recommended timing requirements for programming: $V_{CC}$ = 6.5 V and $V_{PP}$ =13 V (SNAP! Pulse), $T_A$ = 25°C (see Note 3)

		M. Jun . COM. I.	MIN	NOM	MAX	UNIT
tw(IPGM)	Initial program pulse duration	SNAP! Pulse programming algorithm	95	100	105	μs
t <sub>su(A)</sub>	Address setup time	WWW. TO	2	TILL		μs
t <sub>su(E)</sub>	E setup time	MM. TO COMP. TW. WMM.	2	J. 1	W	μs
t <sub>su(G)</sub>	G setup time	COM.	2	OM.	- N	μs
t <sub>su(D)</sub>	Data setup time	MILLIAN TOOLS ON THE	2	MOD	. 1	μs
t <sub>su(VPP)</sub>	Vpp setup time	MM. 100XICE TITM WIT	1002	.01	LTW	μs
t <sub>su(VCC)</sub>	V <sub>CC</sub> setup time	WWW. OOV. COM TW	2	I.Co.	TT	μs
th(A)	Address hold time	COM.	0	V.CO	Mr.	μs
<sup>t</sup> h(D)	Data hold time	M. TOOT. CONT. I.	2	J - C	OM.	μs

NOTES: 3. For all switching characteristics the input pulse levels are 0.4 V to 2.4 V. Timing measurements are made at 2 V for logic high and 0.8 V for logic low (reference page 10).

4. Common test conditions apply for t<sub>dis</sub> except during programming.



#### PARAMETER MEASUREMENT INFORMATION

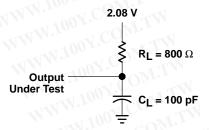
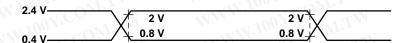


Figure 2. AC Testing Output Load Circuit

## AC testing input/output wave forms



AC testing inputs are driven at 2.4 V for logic high and 0.4 V for logic low. Timing measurements are made at 2 V for logic high and 0.8 V for logic low for both inputs and outputs.

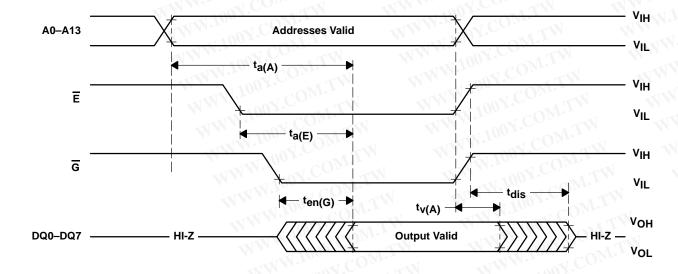
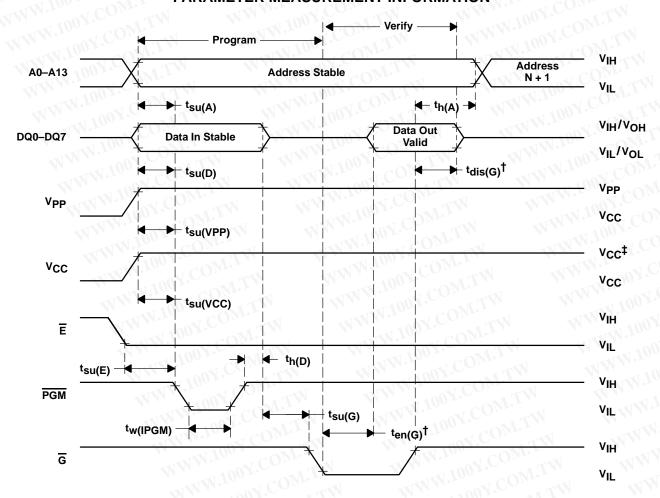


Figure 3. Read Cycle Timing



SMLS128E-OCTOBER 1984-REVISED JANUARY 1993

## PARAMETER MEASUREMENT INFORMATION



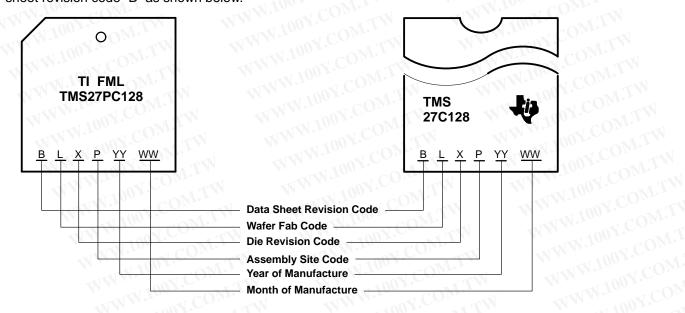
 $<sup>\</sup>dagger$   $t_{dis(G)}$  and  $t_{en(G)}$  are characteristics of the device but must be accommodated by the programmer. 13-V V<sub>PP</sub> and 6.5-V V<sub>CC</sub> for SNAP! Pulse programming.

Figure 4. Program Cycle Timing

SMLS128E-OCTOBER 1984-REVISED JANUARY 1993

## device symbolization

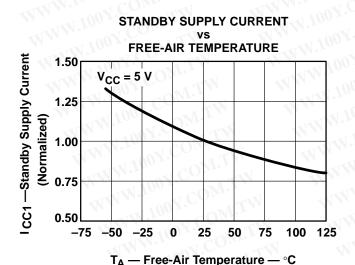
This data sheet is applicable to all TI TMS27C128 CMOS EPROMs and TMS27PC128 PROMs with the data sheet revision code "B" as shown below.

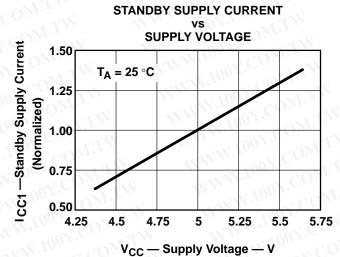


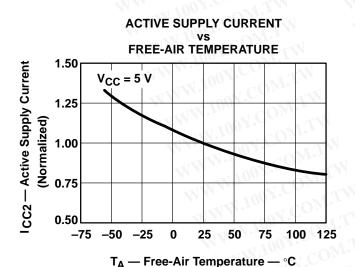
勝 特 力 材 料 886-3-5753170 胜特力电子(上海) 86-21-54151736 胜特力电子(深圳) 86-755-83298787 Http://www.100y.com.tw

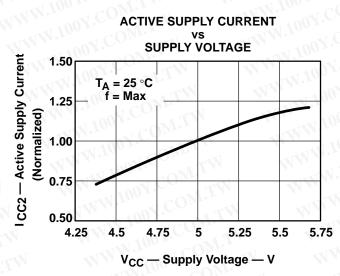
WWW.100Y.COM.TW

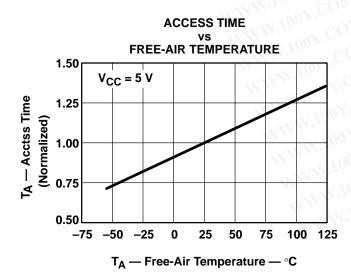
## TYPICAL TMS27C/PC128 CHARACTERISTICS

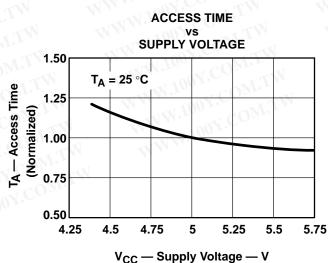














#### IMPORTANT NOTICE

Texas Instruments (TI) reserves the right to make changes to its products or to discontinue any semiconductor product or service without notice, and advises its customers to obtain the latest version of relevant information to verify, before placing orders, that the information being relied on is current.

TI warrants performance of its semiconductor products and related software to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are utilized to the extent TI deems necessary to support this warranty. Specific testing of all parameters of each device is not necessarily performed, except those mandated by government requirements.

Certain applications using semiconductor products may involve potential risks of death, personal injury, or severe property or environmental damage ("Critical Applications").

TI SEMICONDUCTOR PRODUCTS ARE NOT DESIGNED, INTENDED, AUTHORIZED, OR WARRANTED TO BE SUITABLE FOR USE IN LIFE-SUPPORT APPLICATIONS, DEVICES OR SYSTEMS OR OTHER CRITICAL APPLICATIONS.

Inclusion of TI products in such applications is understood to be fully at the risk of the customer. Use of TI products in such applications requires the written approval of an appropriate TI officer. Questions concerning potential risk applications should be directed to TI through a local SC sales office.

In order to minimize risks associated with the customer's applications, adequate design and operating safeguards should be provided by the customer to minimize inherent or procedural hazards.

TI assumes no liability for applications assistance, customer product design, software performance, or infringement of patents or services described herein. Nor does TI warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right of TI covering or relating to any combination, machine, or process in which such semiconductor products or services might be or are used.

Copyright © 1996, Texas Instruments Incorporated